User Manual 42/62-50013 EN

Control^{IT} Process controller P100/500

(Protronic 100/500) Versatile controller with powerful PLC functionality, extensible with hardware modules











Process controller P100/500 (Protronic 100/500)

Versatile controller with powerful PLC functionality, extensible with hardware modules

User Manual

Document No. 42/62-50013 EN

Date of issue: 07.03 Revision: 05

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Con	tent	P	'age
Deli	very stat	te	5
4	Importo	ant information in advance	6
1	Importa 1.1		
	1.1	Symbols	
2	Applica	tion according to designation, general safety instructions	
	2.1	Range of application, application according to designation	
	2.2	Safe operation	7
3	Operati	on	9
•	3.1	Operating elements on the P100/500 front panel	
	3.2	LC-Display	
	3.3	Alarm handling	
	3.4	Channel switching	
	3.5	Automatic mode (A)	
	3.6	Manual mode (M)	
	3.7	Setpoints	
	3.8	Ratio controller	
	3.9	Programmer	
	3.9.1	Selecting the program	
	3.9.2	Starting the program	. 14
	3.9.3	Displays during program execution	
	3.9.4	Stopping the program	. 15
	3.9.5	Fast forward/backward	. 15
	3.9.6	Resetting (cancelling) the program	. 15
	3.10	Cascade control	. 16
	3.10.1	Cascade with one slave controller	. 16
	3.10.2	Cascade with several slave controllers (not P100)	. 17
	3.10.3	Combustion control (not P100)	. 19
	3.11	Override-control	. 20
	3.12	DDC-Control (Direct Digital Control)	. 21
	3.13	Stations	. 22
	3.13.1	Manual station	
	3.13.2	Setpoint station	. 22
	3.13.3	Ratio station	
	3.13.4	Positioner	
	3.14	Remote control (Profibus or Modbus)	. 23
4	Error in	formation on the display	. 24
5	Menu s	tructure	. 25
	5.1	Indication 2	
	5.1.1	Inputs/outputs	. 26
	5.1.2	Parameter display	
	5.1.3	Effective PID parameter	
	5.1.4	Identification	
	5.1.5	Library identification	
	5.1.6	Version display	
	5.2	Operate 2	
6	Passwo	ord protection	20
_		•	
7	index .		. 30





Preface

The documentation included in the P100/500 (Protronic 100/500) package consists of the following parts: Commissioning Instructions P100/500 (Protronic 100/500) 42/62-50011 Configuration Instructions P100/500 (Protronic 100/500)/ D500 (Digitric 500) 42/62-50012

User Manual P100/500 (Protronic 100/500)

42/62-50013

Also available on request:

User Manual IBIS-R, List Configuration 42/62-50020 User Manual IBIS-R, Free Configuration 42/62-50030

The User Manual in this manual include all important information for menu-guided configuration and parameterization of the device. All necessary entries can be made locally via the device's front panel operating elements, or remotely from a PC with the IBIS-R configuration and parameterization program.

The configuration options of the device menu are also available in the IBIS-R program. The description of this program is beyond the scope of this user manual.

Delivery state

The devices are delivered off stock and without customized settings. The factory setting is adjusted to the following functions:

- Single-loop continuous controller
- Input: 4...20 mA
- Output: 4...20 mA
- Language: German

The factory setting and its definitions are described in detail in this user manual.

Customized versions are available upon special request.

Switching on the device

Upon power-on or return of the power after power failure the device automatically performs a selftest of the internal functions. The progress of the test program can be seen on the display. Usually, no special attention has to be paid to this display.



1 Important information in advance

1.1 Symbols

To ensure optimum use of these user manual and a safe use of the assemblies during commissioning, operation and maintenance, please observe the following explanations regarding the symbols used.

Explanations of symbols used.

STOP	Warning	Indicates a risk or potentially hazardous situation which, if not avoided, could result in death or serious injury.
<u></u>	Caution	Indicates a potentially hazardous situation or alerts against unsafe practices which, if not avoided, may result in injury of persons or property damage.
<u></u>	Notice	Indicates a potentially harmful situation which, if not avoided, may result in damage of the product itself or of adjacent objects.
i	Important	Indicates useful hints or other special information which, if not observed, could lead to a decline in operating convenience or affect the functionality.

Apart from the information in these user manual you must also observe commonly valid safety and accident prevention directives.

If the information contained in these user manual is not sufficient for an application our service organisation will gladly be at your disposal for further information.

Please read these assembly and user manual carefully prior to installation.

1.2 Conventions used in these user manual

<Enter> Keys on the device, with their labels

<Ind>, <Loop>

<Menu>, <Enter> Keys available at all times for operator actions.

[P-W] Flashing texts or text fragments from the digital display

P-W, A Texts or text fragments from the digital display

/8/ Reference to numbers in Fig. 3-1

M©, A©, C©

Menu©, Enter©

Menu®, Enter©

Menu®, Enter©

Menu®, Enter©

Light-emitting diodes (LEDs) alongside the keys with the same name are lit.

Light-emitting diodes (LEDs) alongside the keys with the same name are not lit.

Light-emitting diodes (LEDs) alongside the keys with the same name are not lit.

Light-emitting diodes (LEDs) alongside the keys with the same name are not lit.

Sxt External setpopint source

Hand Operating mode





2 Application according to designation, general safety instructions



Important instructions for your safety! Please read and observe.

2.1 Range of application, application according to designation

P100 (Protronic 100) is a 1-loop compact controller (2nd loop cascade and override) P500 (Protronic 500) is a 1...4-loop compact controller.

The devices are designated for the instrumentation of single control loops and for automating small and medium-sized processes in control engineering.

For proper use it is required to observe the "Technical Data section " in the Data Sheets. You will find the technical data in the data Sheets 10/62-6.11 (P100) and 10/62-6.15 (P500).

Any other use is considered improper.

2.2 Safe operation

The technology of the devices is state of the art.





The devices are constructed and tested according to EN 61 010-1 = IEC 1010-1 = DIN VDE 0411 Part 1 "Safety Requirements for Electronic Measurement Apparatus" and have left the factory in a safe condition. To maintain this state and guarantee hazard-free operation, all safety instructions in this manual headed by "Warning, Caution or Notice" must be observed.

Otherwise, personnel might be endangered and the mass flow meter itself or other devices and equipment could be damaged.

Prerequisites for safe operation.

These user manual contain important information about the safe and proper operation of the equipment. Observing these instructions is mandatory for safe operation.

Failure to observe the instructions can cause hazards for life and limb of the user respectively property damages at the devices or the entire system.

Proper and safe operation of the mass flow meter requires proper transportation and storage, installation and commissioning by qualified personnel, operation within its design limits, and careful maintenance observing all information in these user manual.

Qualification of personnel

Only personnel familiar with the installation, commissioning, and maintenance of similar devices and having the required qualifications for their tasks are allowed to work on the device.

Operator

The operator of the plant is fully and solely responsible for proper and workmanlike and, thus, safe operation

The operator must make sure that the user manual have been understood by the target audience.

A copy of the user manual must be stored in a suitable place at the usage location of the device at all times.

Read these user manual prior to commissioning, decommissioning, maintaining, or repairing a device.

National regulations

The regulations, standards, and guidelines mentioned in these user manual are valid for Germany. When using the devices in other countries the appropriate and valid national regulations must be observed.

Notes and regulations to be observed

Observe

- the contents of these user manual and references to other documents and their contents
- the safety regulations affixed to the device
- the appropriate and valid safety instructions for the construction and operation of electrical systems
- the regulations and directives regarding explosion protection.



8

Application according to designation, general safety instructions

During operation

The operator must commission a qualified electrician to inspect and examine the system at defined intervals. The examination intervals must be chosen in such a way that any damages that can be expected can be recognised in time.

The examinations must be performed at least every three years.

The examinations can be skipped if the electrical system is continuously monitored by a responsible engineer

Duties of the operator:

- maintain the system in proper condition
- continuously monitor the system
- execute required maintenance and repair work immediately
- carry out required safety measures

If the devices are used in areas where dusts can cause explosion hazards, you must clean the devices frequently.

Use genuine spare parts, only.



3 Operation

Operating elements on the P100/500 front panel 3.1

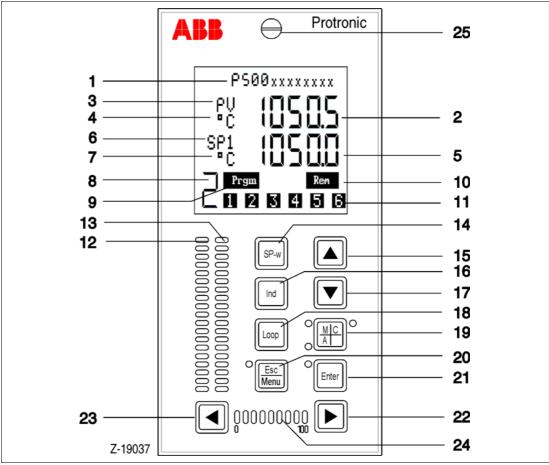


Fig. 3-1 Front panel P100/500 (Protronic 100/500)

- 2 Digital indicator for process value PV
- Designation of the process value Dimension of the process value 3
- 4 5 Digital indicator: indicates setpoint SP in automatic mode and output value OUT in manual mode
- 6 Designation of the indicated value
- Dimension of the value indicated value Number of the control loop displayed, interchanges with display "A" if alarm is output 8
- Indicator for programmer activity Remote control indicator
- 10
- Configurable binary messages (flags)
- Analog display for controlled variable PV 12
- 13 Analog display for set point SP
- Setpoint changeover (see chpt. "Setpoints")
 Button for incrementing the values indicated in 5, 6 and 7 14 15
- Toggle switch for indicators 5, 6 and 7
- Button for decrementing the values indicated in 5, 6 and 7
- 18 Loop transfer switch
- 19 20
- Mode switch for selecting manual or automatic mode, with indicator LEDs Button for accessing the configuration or parameterization level The appropriate LED lights up as soon as the operator control level is exited; at the same time menu symbol is visible in the text line
- 21 22 23 Button for alarm acknowledgement and confirmation of data (configuration and parameters)
- Up button for incrementing in manual mode
- Down button for decrementing in manual mode
- Analog display for controller output "OUT" Srew for fastening display/keypad

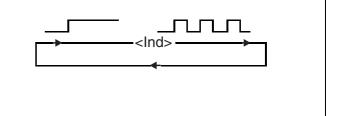
The numbers of the individual control and display elements are used consistently throughout the device documentation.



3.2 LC-Display

The values seen in the "2nd line" column of the table below can be accessed in two different ways:

- From left to right: Press <Ind> button (several times).
- From right to left: Press and hold <Ind>> button



Input circuit/ function		1st line	2nd lin Contro									Progra	ımmer
Fixed value (FV)		PV	SP1-S	P4	Sxt	SPC	P0x	_	Err	OUT	ALi		
Multi components		PV	SP1-S	P4	Sxt	SPC	P0x	_	Err	OUT	ALi		
Multiplication		PV	SP1-S	P4	Sxt	SPC	P0x	_	Err	OUT	ALi		
Ratio (RPV, SR)		RPV	SR1-S	R3	Rxt	SRC	P0x	SR	Err	OUT	ALi		
Ratio (PV,SR*IC2)		PV	SR1-S	R3	Rxt	SRC	P0x	SR	Err	OUT	ALi		
Fixed value/Ratio	FV	RPV	SP1	SR1- SR3	Rxt	SRC	P0x	SR	Err	OUT	ALi		
(RPV, SR)	Ratio	RPV	SP1	SR1- SR3	Rxt	SRC	P0x	SR	Err	OUT	ALi	PS	PGt
Fixed value/ratio	FV	PV	SP1	SR1- SR3	Rxt	SRC	P0x	SR	Err	OUT	ALi		
(PV, SR*IC2)	Ratio	PV	SP1	SR1- SR3	Rxt	SRC	P0x	SR	Err	OUT	ALi		
Extreme value (Max, Mi	n, PV, SP)	PV	SP1-S	P4	Sxt	SPC	P0x	_	Err	OUT	ALi		
Load control – air		same as ratio											
Load control – fuel			same as fixed value										
Manual station		PV	_		_	_	_	_	_	OUT	ALi	-	_
Setpoint station		_	SP1-S	P4	Sxt	SPC	P0x	_	_	-	-		
Ratio station		PV	SR1-S	R3	Rxt	SRC	P0x	SR	_	-	-	PS	PGt
Positioner		PV=OUTfb	SP1-S	P4	Sxt	SPC	P0x	_	Err	OUT	ALi		

Table 3-1 Grayed indicators flash. These values are only displayed, but are currently not active.

PV Measured value (with ratio control: measured value in the quotient numerator)

SP1-SP4 Setpoints 1 to 4
SR1 - SR3 Ratio setpoints 1 -3
Sxt, Rxt External setpoint Setpoint Setpoints are only indicated when they are enabled in the configuration.

SPC, SRC Computer setpoint Programmer setpoint (indicated as P01 to P10)

IC2 With ratio control: measured value in the quotation denominator

SR Setpoint active during ratio control (R* IC2) or (R*IC2)/(1-R)

Err Control deviation
OUT Controller output
OUTfb Position feedback

ALi Alarm limits AL1 to AL4, if enabled

Programmer:

PS Currently executed program segment PS

PGt Program run time since startup

Display color switchover

All Controllers P100 and P500 with a negativ display (illuminated signs on a dark background, new since July 2003) allow to switch the color of the display between red and green if the firmware of the controller is V1.206 or later. The switchover has to be done in the menu. First of all you have to navigate to any subitem of "Service/Display Unit" (if you see at the "Display Unit" you must press once "Enter").

If you are in this subitems and you press the keys <LOOP> and <IND> at once, the color will immediately change. The adjusted color will be stored on non volatile memory.

In the future software library 3.70 (controller firmware 1.3xx or later) the color switchover will be realised as separat item in the menu. The description for this will then be written in the configuration manual.



3.3 Alarm handling



Fig. 3-2 Alarm message z-19000

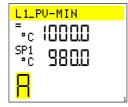


Fig. 3-3 Alarm value is set to 1000.0 z-19001

When an alarm or error occurs or an alarm value is exceeded during an operating cycle,

- a flashing "A" appears in the bottom right corner of the display,
- the error or alarm source is indicated in the first line of the display instead of the TAG name,
- the <Enter> LED is lighted.

Note

Unconfirmed operating instructions displayed in the text line have priority over error codes. As long as the operating instruction is still unconfirmed, the alarm is only indicated by the flashing "A". Alarm acknowledgement is not possible in this situation!

Displaying the exceeded alarm value

Press <Ind> to display the alarm value.

Acknowledging the alarm

press <Enter> (standard configuration):

If there is no other alarm:

The display is reset and the normal values are indicated.

The LED is extinguished, whether the alarm is still active or not.

If there are other alarms

More alarms are indicated in the same way as described above and have to be acknowledged individually.

3.4 Channel switching

If several controllers are configured in one device, <Loop> can be used to switch the control cycles. There are up to 4 Loops (P100 max. 2 loops).

3.5 Automatic mode (A)

Possible operator actions

When the controller is switched over from manual to automatic mode, the active setpoint is seen on the digital indicator. Other values can be selected by pressing the <Ind> button.

<M/A/C>
 <SP-w>
 Switch over from manual to automatic mode
 <SP-w>
 Switch over the setpoint (if configured)
 <▼> <▲>
 Increment/decrement the setpoint
 <Menu>
 Switch over to another menu level



3.6 Manual mode (M)

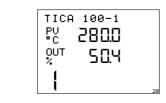


Fig. 3-4 Output OUT is indicated z-19020

The functions of the < $\triangle>$ and < $\nabla>$ buttons are defined either through configuration or, in case of the step controller, through the appropriate wiring. Usually, a more critical state - e.g. a higher furnace temperature - is reached by pressing the < $\triangle>$ button.

After the controller has been changed over from automatic to manual mode, the output variable OUT is shown by the digital indicator. Other values can be selected by pressing the <Ind> button.

In the case of controllers with double output (split range or heating-off-cooling) the display 0...100% corresponds to the full output range of both outputs.

Example:

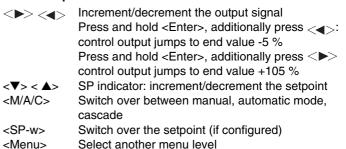
Heating-off-cooling (with normal characteristic curve)

OUT = 0 % corresponds to 100 % cooling

OUT = 50 % corresponds to 0 % cooling and 0 % heating

OUT = 100 % corresponds to 100 % heating

Possible operator actions



3.7 Setpoints

The <SP-w> button can be used to toggle between several setpoint sources, provided that the controller has been configured accordingly.

Possible setpoint sources are:

- setpoints SP1 to SP4 (or ratio setpoints SR1 to SR3) that can be selected on the device by pressing the < ▲> or <▼> button or
- an external setpoint Sxt (Rxt) via analog input or
- a computer setpoint SPC (SRC) via serial interface or
- a programmer with 10 programs P01 to P10

Display in field /6/:

For ratio control:

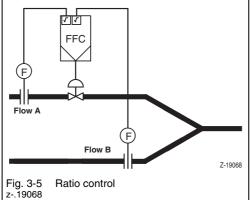
Unconfigured setpoints are suppressed.

Pressing the <SP-w> button will call up the current setpoint for display by the digital indicator, independent of the number of available setpoints.

The setpoint is indicated immediately, but first flashes and becomes active with a delay of 3 seconds. This means that only the last setpoint selected becomes active when the setpoints are switched over quickly.



3.8 Ratio controller



FFICA 4711 RPV 0.998 SR1 (0 10

Fig. 3-6 Display RPV and SR1, z-19018 SR1 is adjustable

The ratio controller controls

RPV(ratio process value) = SR(set ratio) = $\frac{FlowA}{FlowB}$

or, depending on the configuration,

$$RPV = SR = \frac{FlowA}{FlowA + FlowB}$$

The ratio controller can output the actual ratio to an analog output (0/4...20 mA) if configured accordingly.

When the RPV and SR displays are configured, the ratio setpoint is indicated in the fields /5/, /6/ and /7/ of the digital indicator and can be set.

If configured accordingly, several setpoint sources (SR1 to SR3, Rexternal or program generator) can be selected by pressing the <SP-w> button.

The measured actual ratio is indicated in the fields /2/, /3/ and /4/.



Fig. 3-7 Process value PV= flow A and SP = setpoint flow A z-19019

FFICA 4711 PYA 5356 SR1 (0 (0

Fig. 3-8 SR1 is adjustable z-190051

When the PV and SP displays are configured, the calculated setpoint of flow A is indicated in the fields /5/, /6/ and /7/.

The fields /2/, /3/, /4/ indicate the measured actual value of flow A.

Press the <Ind> button to call up the SR1value in the display fields (/5/, /6/, /7/) and then change it.



3.9 Programmer

A programmer can be configured in the controller. Up to 10 different programs with 15 segments each can be saved. Refer to "Configuration instruction" 42/62-50012 for details about setting the values.

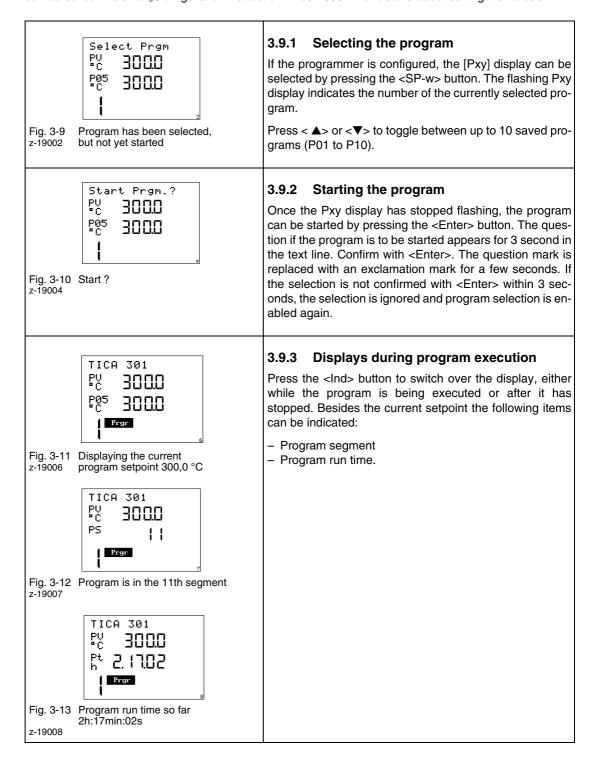






Fig. 3-14 Question: Stop program ? z-19009



Fig. 3-15 Programmer has stopped. z-19011 Program (Prgm) is flashing.

3.9.4 Stopping the program

When the <Enter> button is pressed again once the program is running, the question for the system stop seen here appears.

When the question is answered with yes by pressing the <Enter> button, a confirmation is shown for 3 seconds.

The program is stopped, and the [Prgm] indicator flashes. The question mark is replaced with an exclamation mark for a short time to confirm.

fast forward ! PV 3000 P05 3000

Fig. 3-16 Fast forward indication z-19012



Fig. 3-17 Fast backward indication z-19013

3.9.5 Fast forward/backward

When a program has been stopped, a fast forward/backward run can be achieved by pressing the < ▲> or <▼> button. Actuating the < ▲> button will shift the program forward to values later in time. When this button is pressed, the fast forward action is confirmed in the display.

How far the program has run forward can be derived from the setpoint, the segment indicator or the time indicator.

A fast backward run of the program can be started by pressing the $< \nabla >$ button.

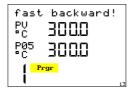


Fig. 3-18 Question: Reset? z19014



Fig. 3-19 During running program switching z19016 to other setpoints is not possible

3.9.6 Resetting (cancelling) the program

If a program is restarted after it has been run down completely, it starts automatically in the 1st segment. No reset is required in this case.

A stopped program ca be reset or cancelled by pressing the <SP-w> button.

If the question is answered with yes by pressing the <Enter> button within 3 seconds, the program is reset to the start. The message "Reset!" appears for a short time.

If the operator attempts to switch during a running program to another setpoint (e.g. SP1) by actuating the <SP-w> button, the warning "Program runs" appears in the display for 3 seconds, see Fig. 3-19.



3.10 Cascade control

3.10.1 Cascade with one slave controller

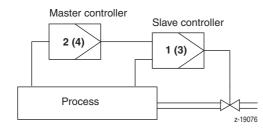


Fig. 3-20 Cascade with a slave controller



Fig. 3-21 Slave controller TICA 100-1 display, (z-19020) Controller output in display

Cascade operation



Fig. 3-22 Master controller TICA 100-2

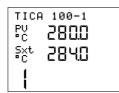


Fig. 3-23 Slave controller TICA 100-1 (z-19022)

Operating mode switching

Switching is always in the sequence below:

Manual operation applies only to the slave controller. Both in manual and automatic mode the master controller is always synchronised in such a manner that the switchover can take place smoothly.

When switching, the selected operating mode does not come into effect until 3 s have elapsed since the last key press.

At the same time as the operating mode is changed, the display also switches to the more important loop. It is always possible to switch manually to the other loop.

OUT always shows the actual output to the final control element or the final control element position reported back.

By switching from automatic to cascade the slave controller switched to **external set point**, the master controller's output. The transition from automatic to cascade is performed smoothly as the master controller's output is synchronised in such manner that the slave controller is not subjected to any control

deviation at the moment of switchover.

When changing from automatic to cascade the system automatically switches to loop 2, the master controller.

Control actions allowed

Display	Keys/Operating mode	Master controller	Slave controller
	Manual M©		
	<sp-w></sp-w>	+	+
Sxt	<▲><▼>	+	+
	<m a="" c=""></m>	operates on slave contr.	+
OUT	<▲><▼>	_	+
	Automatic A©		
	<sp-w></sp-w>	+	+
Sxt	<▲><▼>	+	+
	<m a="" c=""></m>	operates on slave contr.	+
OUT	<▲><▼>	_	-
	Cascade C©		
	<sp-w></sp-w>	+	_
Sxt	<▲><▼>	+	-
	<m a="" c=""></m>	operates on slave contr.	+
OUT	<▲><▼>	_	_

⁺ operative, can be changed, - inoperative in this operating mode



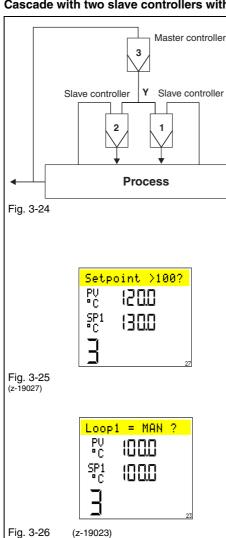
3.10.2 Cascade with several slave controllers (not P100)

The integral controllers in a device in a cascade with several slave controllers have their own mode selector switches which are largely independent.

Thus the operation of such controllers is similar to the operation of the equivalent cascade comprising individual controllers.

For the master controller there is the additional operating mode TRACK in which none of the three LEDs on the <M/A/C> key is lit. This operating mode is imposed through the slave controller's operating mode and cannot be changed at the master controller.

Cascade with two slave controllers with the same set point.



The master controller gives the same set point to both slave controllers. The controller output (OUT = 0...100%) produces the set point range configured in the slave controllers.

The controller output is not displayed on the master controller.

Operating modes available:

Open cascade with

- Manual operation in both slave controllers or
- one slave controller in manual and one in automatic mode or
- both slave controllers in automatic mode

Closed cascade with

- both slave controllers in automatic mode
- just one slave controller in automatic mode

Important

When the first slave controller is switched to cascade the controller is switched to manual. At first the output signal altered, but this can be done manually.

Where there is a large difference between set points following message is displayed before switching over (Fig.

A set point jump can be avoided by:

- Resetting: first set both controllers to automatic mode and then adjust set points to equal.
- Defining a set point ramp

As long as one slave controller is still set to automatic, when the master controller is switched to automatic the following message is issued (Fig. 3-26).

After this message is acknowledged by pressing <Enter>, the intended switchover is performed. The master controller then operates on only one slave controller.

When slave controllers are reset from cascade to automatic the master controller retains its operating mode as long as one slave controller remains in cascade.

Operating modes

Loop 1: Slave controller 1	Loop 2: Slave controller 2	Loop 3: Master controller
Manual	Manual	Track
Automatic	Manual	Track following slave controller 1
Manual	Automatic	Track following slave controller 2
Automatic	Automatic	Track average
Cascade	Manual or Automatic	Manual or Automatic
Manual or Automatic	Cascade	Manual or Automatic
Cascade	Cascade	Manual or Automatic

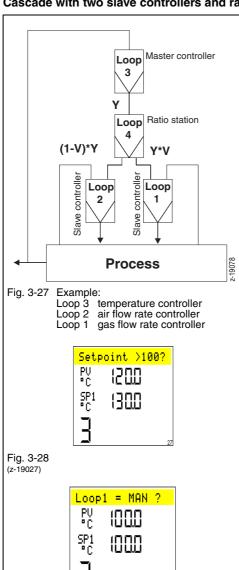
Table 3-2 Track following slave controller: Track average:

(z-19023)

The slave controller's setpoint sychronises the master controller The master controller is synchronised to the average of the slave controller's setpoints.



Cascade with two slave controllers and ratio station (not P100)



A ratio station is connected between the master controller and the slave controllers. Using an adjustable ratio, this distributes the master controller's output signal to the two slave controllers as set points.

Operating modes available:

Open cascade with

- Manual operation in both slave controllers or
- one slave controller in manual and one in automatic mode or
- both slave controllers in automatic mode

Closed cascade with

- both slave controllers in automatic mode
- just one slave controller in automatic mode

The ratio station is always in automatic mode, and the input signal apportioned to both outputs.

Important

When the first slave controller is switched to cascade the master controller is switched to manual. At first the output signal is not altered, but this can be done manually.

If the set point total is > 100%, before actually switching over the system issues the message: Fig. 3-28.

A set point jump can be avoided by:

- Resetting: first set both controllers to automatic mode and then adjust set points to equal.
- Defining a set point ramp

As long as one slave controller is still set to automatic, when the master controller is switched to automatic the following message is issued: Fig. 3-29.

After this message is acknowledged by pressing <Enter>, the intended switchover is performed. The master controller then operates on only one slave controller.

When slave controllers are reset from cascade to automatic the master controller retains its operating mode as long as one slave controller remains in cascade.

Operating modes

Fig. 3-29

Loop 1: Slave controller 1	Loop 2: Slave controller 2	Loop 3: Master controller
Manual	Manual	Track not alterable
Automatic: SP = SP1i	Manual	Track: SP1i/SR
Manual	Automatic: SP = SP2i	Track: SP2i/(1-SR)
Automatic: SP = SP1i	Automatic: SP = SP2i	Track: SP1i + SP2i <100 %
Cascade	Manual or Automatic	Manual or Automatic
Manual or Automatic	Cascade	Manual or Automatic
Cascade	Cascade	Manual or Automatic

Table 3-3

SP1i = current set point on controller 1

SP2i = current set point on controller 2

Track SP1i/SR:

The master controller's output is synchronised to the value of SP1i/SR as long as this value is less than 100 %. Track SP2i/(1-V):

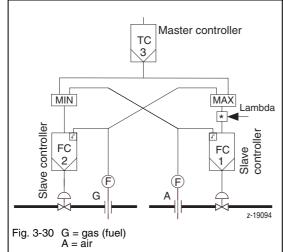
The master controller's output is synchronised to the value of SP2/(1-SR) as long as this value is less than 100 %. Track SP1i +SP2i < 100%

The master controller's output is synchronised to the value of SP1i + SP2 as long as this value is less than 100 %.



3.10.3 Combustion control (not P100)

(Load control)



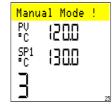


Fig. 3-31 (z-19025)

Load control ensures that as the load changes, a shortage of air is never allowed to occur.

Operating modes available:

Open cascade with

- Manual operation in both slave controllers or
- one slave controller in manual and one in automatic mode or
- both slave controllers in automatic mode

Closed cascade with

both slave controllers in automatic mode

Some of the operation modes can be locked by changing the configuration.

The master controller cannot be switched to manual mode until the slave controllers are operating in cascade mode.

If this is not the case, the following message is issued if an attempt is made to switch the master controller from track to manual or automatic: Fig. 3-31.

This message cannot be suppressed.

When both slave controllers are switched commonly from cascade to automatic the master controller is switched to manual. At first the output signal is not altered, but this can be done manually.

When a slave controller is switched back to manual the master controller is automatically switched to track operation.

Operating modes

Loop 1: Slave controller 1	Loop 2: Slave controller 2	Loop 3: Master controller
Manual	Manual	Track
Automatic: Fixed value A, SP= SP1i	Manual	Track: SP1i/SR
Manual	Automatic: Fixed value G, SP= SP2i	Track: SP2i
Automatic: Fixed value A, SP= SP1i	Automatic: Fixed value G, SP= SP2i	Track: A/R
Cascade	Automatic	Manual
Automatic	Cascade	Manual
Cascade	Cascade	Manual or Automatic

Table 3-4

Controller is locked in Track mode.

Track A/R:

The controller output is synchronised to the air/ratio value

A = Air G = Gas (fuel)

R = Ratio



3.11 Override-control

(Limiting control)

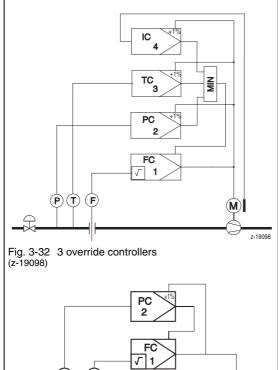


Fig. 3-33 1 Override controller Override control of pressure P Primary controlled variable: flow F

In override control one primary controlled variable is managed. One or more additional controllers make sure that the (limiting) set points are neither over- nor under-stepped. All the controllers here access a single final control element.

Example (Fig. 3-32):

Primary controlled variable: Flow Limitation of: Pressure

Temperature Current drain by the compressor drive

Operating modes available:

The mode selector switches only ever affects loop 1. Every time there is a mode change the system switches automatically to loop 1.

The operation of the limiting controllers is restricted to setting set points.

Manual operation (M©)

The main controller is in manual mode, the limiting controller(s) is/are in automatic mode.

The limiting controllers can't be switched to manual.

Manual operation is carried out only through loop 1. The limiting controllers are not involved.

Automatic (A©)

The main controller is in automatic and is the only unit working on the final control element. The limiting controllers are not involved.

Cascade (CO)

The main controller and limiting controllers are engaged.

If a limiting controller should become temporarily inoperative its set point must be altered to the limit of the range and thus rendered inoperative.



3.12 DDC-Control (Direct Digital Control)

With DDC control a supervisory computer provides for control. In case of a computer failure the Digitric controller bumplessly takes over control via interface RS 485 (MODBUS RTU) or PROFIBUS DP.

The superimposed computer writes via the bus on the variables Lx_YCOMPUTER of the respective loop X and, thus, determines the controller output. In case the superimposed computer should fail, the controller itself bumplessly takes

Possible operating modes

LED is off

☼ LED is on

CR The computer is ready, i.e. there is regular data traffic via the serial interface.

M, A, C LEDs to the side of button 19 on the front panel (Fig. 3-1)

DDC configuration with manual backup mode

		LED				
Operating mode	М	Α	С	CR		
Manual	₩	•	•	0		
Automatic	•	*	•	0		
DDC	disabl	ed		0		
Manual	*	•	\odot	1		
Automatic	•	₩	0	1		
DDC	☆	•	☆	1		
Backup mode						
M-backup	₩	•	8	0		
M-backup	⋫	•	☼	1		

DDC configuration with automatic backup mode

		LED				
Operating mode	М	Α	С	CR		
Manual	‡	•	•	0		
Automatic	•	☆	•	0		
DDC	disabled	k	•	0		
Manual	☆	•	\odot	1		
Automatic	•	\$	\odot	1		
DDC	•	\$	☆	1		
Backup mode						
M-backup	•	\$	\otimes	0		
M-backup	•	‡	\odot	1		

DDC configuration with cascade backup mode

		LED				
Operating mode	М	Α	С	CR		
Manual	☆	•	•	0		
Automatic	•	*	•	0		
Cascade	•	•	☆	0		
DDC	disable	:d		0		
Manual	☆	•	0	1		
Automatic	•	*	0	1		
Cascade	•	•	☆	1		
DDC	•	\$	☆	1		
Backup mode						
M-backup	•	\otimes	*	0		
M-backup	•	\odot	☆	1		

No computer ready signal (CR = 0)

As long as no computer ready (CR) signal is available, the controller cannot be switched to DDC mode.

Computer ready (CR = 1)

The changeover to DDC operation is enabled. In "manual" mode LED A flashes with low frequency. In "automatic" backup mode LED M flashes with low frequency.

It is possible to switch from DDC operation to manual or automatic mode at any time.

Computer not ready

If the CR signal is not received any longer, the controller takes over control in the configured mode. In backup mode "manual" LED A flashes with increased frequency.

In backup mode "automatic" LED M flashes with increased frequency.

It is not possible to switch over to another mode (non-DDC).

The LED of the disabled mode flashes. The LED of the active mode is lighted permanently.



3.13 Stations

3.13.1 Manual station

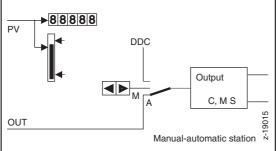


Fig. 3-34

	LED			
Operating mode	М	Α	С	CR
Manual	‡	•	•	0
DDC	disabled			0
Manual	*	•	\odot	1
DDC	*	•	‡	1
Backup mode				
M-backup	☆	•	\otimes	0
M-backup	₩	•	\odot	1

The manual station is a controller that can be used in "manual" mode only.

All indicators that can be selected by pressing <Ind> do not display setpoints or the control deviation in this mode.

The PV indicator can indicate a measured value which can be monitored for limit values.

The operation of the manual station depends on the respective configuration.

Manual station

With the manual station the control output can be set manually. All output types of the controller are possible.

Manual/automatic station (not step controller)

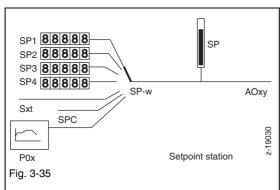
In automatic mode, this station applies an externally fed continuous signal to the output. It is possible to switch over to manual mode and set the output manually.

No step output is possible.

DDC manual station (not step controller)

The DDC manual station combines the functionality of the manual station with the manual function of the DDC controller.

3.13.2 Setpoint station



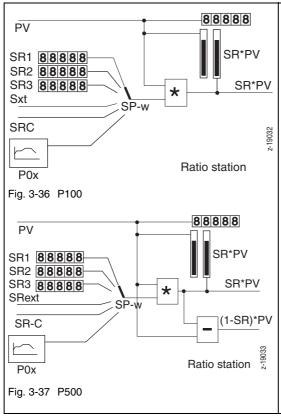
The setpoint station generates setpoints and outputs them as 0/4...20 mA signal.

All indicators for the process value or control deviation are disabled.

The button <Sp-w> can be used to switch between different setpoint sources and the program generator, if configured.



3.13.3 Ratio station



The ratio station multiplies an input signal by an adjustable ratio factor SR. The input signal is treated as a measured value. Limit values may be set.

P100

The signal (SR * input) is available as output signal.

P500

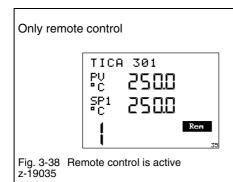
The signal "SR*input" and "(1-SR)*input" are provided for output.

3.13.4 Positioner

The positioner is a motorized valve controller (step controller) which tracks the actuator position (valve position) to an external setpoint. This task requires position feedback.

The returned position is indicated on the controller as the process value PV and the position feedback OUT.

3.14 Remote control (Profibus or Modbus)



The [Rem] indicator is active. The control buttons on the controller front panel are disabled, with some exceptions.

Possible operator actions

<Ind> Permits to switch over the display

<Menu> Accesses the configuration menu,

among other reasons to start remote

control.

Press <Menu> to switch to the menu level from which remote control can be disabled.



4 Error information on the display

Operating notes	Meaning	Configuration
locked by BI	Access to parameterization, configuration, service, and supervisor level is blocked through a binary input.	I-B02-Q01 I-B02-Q02
generate	After configuration the instrument is busy with the program generation.	
locked for ST	Self-tuning is blocked for this control loop. It can only be released via the configuration.	L1- B01-Q05
no adjustment possible	The selected input has not been activated for the type intended for the adjustment (e. g. no Pt100 input). This message is displayed for mA position feedback or remote transmitters fed with constant current, if the difference between start and end value is smaller than 10%.	
no adjustment	The configured module does not permit an adjustment respectively does not require an adjustment.	
local only	The instrument has only been configured for local operation. It cannot be switched to exclusive remote operation.	I-B04-Q01
remote only	The instrument has been configured for remote operation. For local operation it must be enabled via menu "Operate 2" or via the configuration.	I-B04-Q01

Table 4-1 Error information

Error message	Cause	Remedy
Error xxxx	An error occurred while processing the program. The number is intended as help for the service.	If this message does not disappear within a few seconds you can try to initiate a restart by switching off the supply voltage for approximately 60 s. If the error persists, the factory settings must be restored via the "supervisor" menu or the configuration must be reloaded via IBIS_R.
IP stopped!	Processing has been temporarily stopped. This error occurs during downloading.	If this message does not disappear within a few seconds after downloading you can try to initiate a restart by switching off the supply voltage for approximately 60 s. If the error persists, the factory settings must be restored via the "supervisor" menu or the configuration must be reloaded via IBIS-R.
Slot X!	When downloading a configuration the configuration request a module that is located in the instrument.	Insert the correct module in slot Xand register the module (I-B11-Q01 = 1). Note: X = 1 to 4
invalid response	The response entered may be incompatible with other existing settings. Enter is activated together with this message.	Get the invalid response on the display with <enter> and change it.</enter>
Card fault	There was an attempt to read or write the configuration on a defective memory card.	Try again. If fault persits, use another memory card.
No M-card	There was an attempt to read or write the configuration of a memory card which is not available.	Push memory card into the terminal provided on device.
Confi. incomplete	The configuration stored on the memory card is incomplete.	
write protection	There was an attempt to write the configuration on a write-protected memory card.	

Table 4-2 Error information



Menu structure

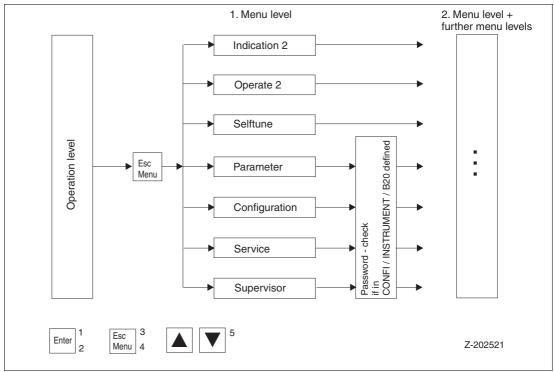


Fig. 5-1 Menu structure

- Confirm selection, go down one menu level
- Change or confirm input, go down one menu level Go up one menu level without change(press 3 s $\,\to\,$ main operating level) 2
- From main operating level to menu
- Move sideways within one menu level

Indication 2

In this menu you can view all parameters, measuring values, and settings of the controller, but you cannot change them (see also chapter 5.1 "Indication 2" on page 26).

In this menu you can toggle between local and remote operation. (See also chapter 5.2 "Operate 2" on page 28.)

Selftune

Self-tuning is enabled in the configuration menu under CONFI / LOOP1 / B01 / Q05

After enabling it can be used without knowing a password .

(See Configuration Instruction 42/62-50012.)

Parameter

This menu contains the settings of the parameters required for the configured functionality. During parameterization the control action stays on. (See Configuration Instruction 42/62-50012.)

Configuration

This menu contains sub-menus for instrument function definition (e. g. actuator output type). During configuration the control action is switched off (actuator outputs are frozen). (See Configuration Instruction 42/62-50012.)

Service

This menu contains sub-menus for calibration, Adjustment, etc. (see also "Configuration Instruction" 42/

Calibration is only required in exceptional cases. If it is not executed in an expert manner, the instrument is rendered unusable.

Supervisor

This menu contains the sub-menus: Master reset, Plausibility, and Template. (See "Configuration Instruction" 42/62-50012.)



5.1 Indication 2

Example navigation in menu "Indication 2"

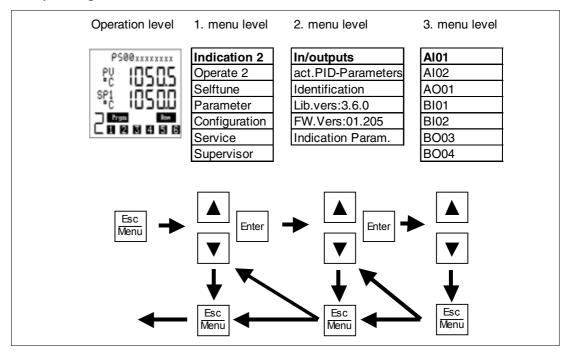
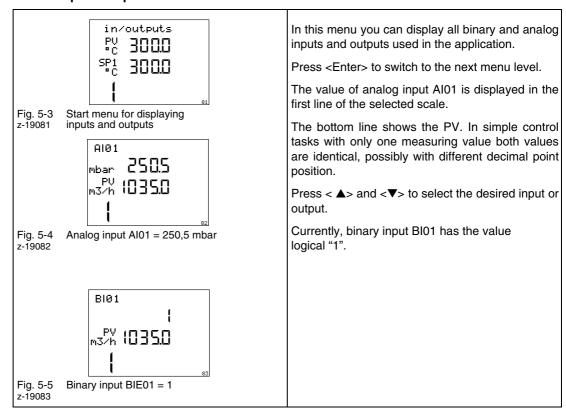


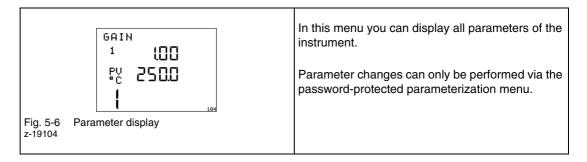
Fig. 5-2 Navigation in menu "Indication 2"

5.1.1 Inputs/outputs

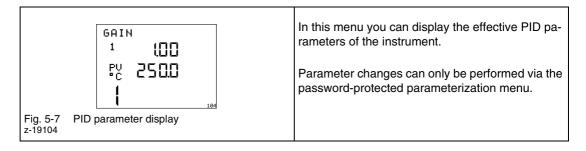




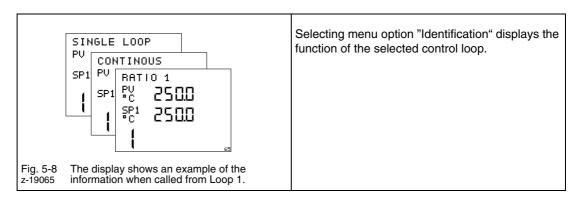
5.1.2 Parameter display



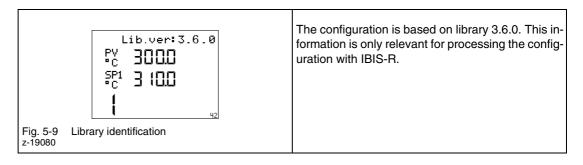
5.1.3 Effective PID parameter



5.1.4 Identification



5.1.5 Library identification





5.1.6 Version display

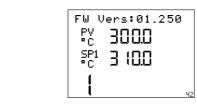


Fig. 5-10 The firmware (instrument software) has the z-19042 Index 01.250

This is the firmware version used in the instrument itself. It may be required to know this version number when using the IBIS-R PC software.

5.2 Operate 2

only local ! PV -250 SP1 -265

Fig. 5-11 Not intended for remote operation z-19041



Fig. 5-12 Remote operation is activated 7-19040



Fig. 5-13 Remote operation is deactivated

If the instrument has been configured exclusively for remote operation, the remote operation can be disabled temporarily – e. g. for emergency intervention – via menu "Operate 2".

Depending on the configuration the following display appears when selecting the menu option:

Not intended for remote operation

The operation cannot be changed.

Note

Remote operation means that values are input to the instrument via Modbus RTU respectively PROFIBUS DP.

Rempote operatiopn is activated

Remote operation "Rem" can be toggled to local operation.

The question "Toggle to local operation?" = "Rem>Local?" is confirmed with <Enter> or negated with <Esc>.

If the instrument is toggled to local operation the keys are enabled and [Rem] starts flashing.

Remote operation is deactivated

Remote operation is – temporarily – switched off. Press <Enter> to restore the operating condition "Remote operation" as defined by the configuration. Then, the instrument can only be remote-operated.

[Rem] stops flashing.



6 Password protection



Fig. 6-1 Input of password. 1st field from the right z-19101



Fig. 6-2 Locking the parameterization and z-19103 configuration level via binary input

If the password protection has been configured (I-B20), you must enter a password to access the protected levels, by changing the predefined value "00000".

The password is a 5-digit number.

- Shift a flashing (= changeable) field: <Ind>
- 2. Change digit:
 - < **▲**> and <**▼**>
- Confirm password: <Enter>

When the password is correct, the desired level is entered. You can now switch between all levels of the menu system without having to re-enter the password

(Question: I-B20-Q01).

If the password is not correct, the main operating level is displayed again.

If a hardware lock has been configured (I-B02-Q01) and the binary input is set, the message "locked by BI" is displayed when attempting to open a protected level.

The message is displayed for 3 s, then the operating level is automatically switched back.

Cancelling the password input

Cancel with<Esc>

Forgotten password

If a password is no longer known, the password can be reset by temporarily rearranging a jumper within the instrument. For this action the control loop must be switched off.



7 Index

	ene
Alarm handling	44
Automatic mode	
C	
Cascade control	16
Cascade with one slave controller	
Cascade with several slave controllers	
Cascade with two slave controllers and ratio station	
Channel switching	
Combustion control	
D	
DDC-Control	. 21
Direct Digital Control	. 21
Display color switchover	. 10
E	
Effective PID parameter	
Error information on the display	. 24
F	
Forgotten password	. 29
Identification	
Indication 2	,
Inputs/outputs	. 26
LC-Display	
Library identification	
Limiting control	
Load control	. IE
Manual mode	10
Manual station	
Menu structure	
N	. 20
navigation in menu "Indication 2"	26
0	
Operate 2	. 28
Operating elements	
Operating modes	
Operation	9
Override-control	
P	
Parameter display	. 27
Password protection	
Positioner	. 23
Programmer	. 14
R	
Ratio controller	
Ratio station	
Remote control	. 23
\$	
Selftune	
Service	
Setpoint station	
Stations	
Supervisor	
Symbols	6
V Version display	00
Version display	. ∠と



42/62-50013 EN Rev. 05

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Printed in the Fed. Rep. of Germany (07.03)

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