DATA SHEET



# Grid feeding monitoring according to CEI 0-21

# CM-UFD.M22 CM-UFD.M22M with Modbus RTU

The CM-UFD.M22(M) is a multifunctional grid feeding monitoring relay. It provides different monitoring functions in accordance with CEI 0-21 to detect over- and undervoltage (10-minutes average value, voltage increase and decrease protection) as well as any changes in grid frequency (frequency increase and decrease protection).

The device is connected between the distributed generation and the public grid in order to disconnect the distributed generation in case of problems (e.g. unstable grid), faults or maintenance on the grid. Additionally, monitoring of ROCOF (rate of change of frequency) can be configured.





0C251003S0017

### **Characteristics**

- Monitoring of voltage and frequency in single- and threephase mains (2-wire, 3-wire or 4-wire AC systems)
- Type-tested in accordance with CEI 0-21
- Pre-settings in accordance with CEI 0-21
- Integrated management of redundancy function (acc. to CEI 0-21, mandatory in plants with P>11.08 kW)
- Modbus RTU communication interface\*
- Multiline, backlit LCD display
- True RMS measuring principle
- Over- and undervoltage, 10-minutes average value as well as over- and underfrequency monitoring
- Two-level threshold settings for over-/undervoltage and over-/underfrequency
- ROCOF (rate of change of frequency) monitoring configurable

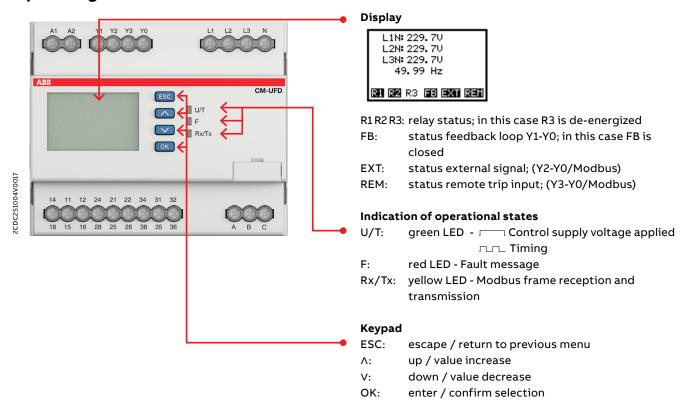
- Interrupted neutral detection
- · All threshold values and tripping delays adjustable
- Error memory for up to 99 entries (incl. cause of error, measured value, relative timestamp)
- · Autotest function
- Password setting protection
- 3 control inputs, e.g. for feedback signal, remote trip
- 3 c/o (SPDT) contacts
- Can be connected to ABB Ability<sup>™</sup> Electrical Distribution Control System\* (see EDCS Getting Started, document no. 1SDC200063B0204)
- Various certifications and approvals (see overview, document no. 2CDC112249D0201)

### Ordering details

Туре	Rated control supply voltage	Measuring range	Order code
CM-UFD.M22	24-240 V AC/DC	L-L: 0-540 V AC / L-N: 0-312 V AC	1SVR 560 730 R3400
CM-UFD.M22M	24-240 V AC/DC	L-L: 0-540 V AC / L-N: 0-312 V AC	1SVR 560 731 R3700

# **Functions**

### **Operating controls**



### **Application**

The CM-UFD.M22(M) is a grid feeding monitoring relay (SPI), which is connected between the public grid and the distributed generation such as photovoltaic systems, wind turbines, block-type thermal power stations. It monitors the voltage and the frequency in the grid and disconnects the distributed generation whenever the measured values are not within the range of the adjusted thresholds. The fault is indicated by LED and the corresponding plain text message is shown on the display. In conformity with CEI 0-21, the CM-UFD.M22(M) relay can be used in all low voltage plants and in medium voltage plants. The SPI relay is mandatory in all low voltage generation plants with power > 11.08 kW or with more than 3 generators (e.g. plants with more than 3 inverters).

### Operating mode

The CM-UFD.M22(M) can be set up to monitor single- and three-phase mains (2-wire, 3-wire as well as 4-wire AC systems). The unit is configurable by front-face push-buttons. A display with the corresponding menu enables the selection of presettings as well as the precise adjustment of the different threshold values and corresponding time delays. Furthermore, the display visualizes the measured values clearly. Together with the front-face LEDs, it shows all information about operational states of output relays and control inputs.

The CM-UFD.M22(M) provides 3 output relays and 3 control inputs. In case an event occurs, the first output relay R1 ( $11_{15}$ - $12_{16}$ / $14_{18}$ ) disconnects the distributed generation from the public grid by means of the first coupling switch (DDI). The second output relay R2 ( $21_{25}$ - $22_{26}$ / $24_{28}$ ) is redundant to the first one. It only trips the second coupling switch (DG) if no change of the state of the first coupling switch (DDI) has been recognized within the adjusted time delay. The third output relay R3 ( $31_{35}$ - $32_{36}$ / $34_{38}$ ) can be used for signalization of an event in the grid or a bus fault or the closing command of a motor drive for circuit breaker. Additionally, it can be configured to act synchronously with R1 or controlled via bus.

The first control input Y1-Y0 monitors the corresponding feedback signal from the DDI contact. Two additional control inputs allow to switch remotely between two sets of frequency threshold settings via Y2-Y0 or to trip the grid feeding monitoring relay via the control input Y3-Y0 (remote trip).

With the Modbus RTU interface, all process values and status information from the CM-UFD.M22M can be read out and control commands can be executed.

### **Protective functions**

If the control supply voltage is applied and all phases are present with voltage and frequency values within their permissible range, output relay R1 (DDI) energizes after the adjusted start-up delay and output relay R2 (DG) energizes or de-energizes, depending on the configuration, after a fixed delay of 1 s. Using the default factory setting, both output relays R1 (DDI) and R2 (DG) will be activated synchronously. The green LED U/T flashes while timing and turns steady when the start-up delay is complete.

If a measured value exceeds or falls below the set threshold value, output relay R1 (DDI) de-energizes after the adjusted delay. The fault is indicated by the red LED F and the type of fault is shown on the display as a plain text message. The event that has caused tripping of the relay is recorded in the event list. The green LED U/T flashes while timing and turns steady when the delay is complete.

As soon as the measured value returns to the tolerance range, taking into account a fixed hysteresis, the red LED F turns off and output relay R1 (DDI) re-energizes after the adjusted re-start delay. The green LED U/T flashes while timing and turns steady when the delay is complete.

### **Redundancy functions**

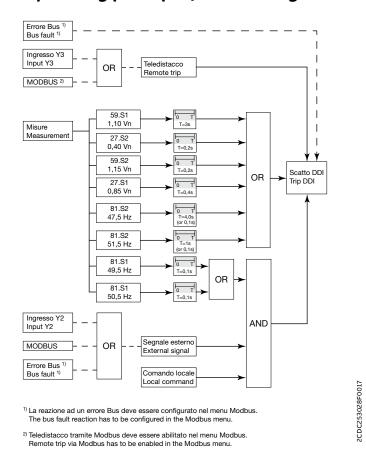
The redundancy relay R2 (DG) is activated if relay R1 (DDI) has de-energized and if no feedback from the external contact has been recognized by the internal logic via the first control input Y1-Y0 within the adjustable time delay. In case a feedback signal is present, the redundancy relay does not trip.

### Output relay R3 (31<sub>35</sub>-32<sub>36</sub>/34<sub>38</sub>)

The output relay R3 can be used for:

- Trip signalization
   R3 reacts synchronously with R1. ON-time of R3 is inactive.
- Closing command of a breaker motor In case output relay R1 (DDI) energizes, the adjusted ON-delay starts. When timing is complete, output relay R3 will be activated for the duration of the ON-time or until relay R1 de-energizes.
- Bus fault signalization
   In case of no bus communication during the adjusted bus timeout, the bus fault is signalized by R3 (e.g. no sign of life from the bus master)
- Additionally the control of R3 via bus or a deactivation is possible. With these configurations the settings for the ON-delay and the ON-time have no influence on the operating function.

### Operating principle / Monitoring functions



The device utilises several separately adjustable monitoring functions for:

- Over voltage protection: U> (59.S1), U>> (59.S2)
- Under voltage protection: U< (27.S1), U<< (27.S2)
- Over frequency protection: f> (81>.S1), f>> (81>.S2)
- Under frequency protection: f< (81<.S1), f<< (81<.S2)

Protective function 59.S1 (10-minutes average value):

The CM-UFD.M22(M) calculates the sliding average value of the 3 phases over a period of 10 minutes. The voltage values are updated every 3 seconds. If the 10-minutes average value exceeds the threshold value, the output relays trip.

### Local command and external signal

The CEI 0-21 standard defines "restrictive thresholds", the under- and overfrequency thresholds S1 (49.5Hz/50.5 Hz), and "permissive thresholds", the under- and overfrequency thresholds S2 (47.5Hz/51.5 Hz). Selection of S1 or S2 thresholds is done by the corresponding combination of the external signal Y2-Y0 or Modbus RTU and the local command (see tables below).

Truth table for control inputs External Signal Y2-Y0 and Remote trip Y3-Y0

Operating principle	Input state	Control input
normally open	open	0
normally open	closed	1
normally closed	open	1
normally closed	closed	0

### Truth table for frequency thresholds

External signal						
Input Y2	MODBUS	Bus fault*	Local command	Active thresholds		
X	Х	X	disabled	S2		
0	0	0	enabled	S2		
One or mor	e = 1		enabled	S1 + S2		

 $<sup>{}^{\</sup>star}\text{The}$  bus fault reaction has to be configured in the Modbus menu.

### Remote trip

The Modbus RTU and the control input Y3-Y0 allow remote tripping of the grid feeding monitoring relay. The remote trip input can be configured as normally open or normally closed. If normally closed is configured, the relay trips if Y3-Y0 is opened. If normally open is configured, the relay trips if Y3-Y0 is closed. The output relay R1 is tripped by the remote trip within less than 20 ms. When the remote trip input is deactivated, the output relay R1 energizes again.

### ROCOF (Rate of change of frequency df/dt)

This function monitors the rate of change of frequency within a very short time and detects an imminent loss of mains (islanding). The ROCOF function detects zero crossings of the grid voltages. It measures the time between the zero crossings and calculates a new frequency after each zero crossing. In case the frequency changes too much since the last zero crossing, the output relay R1 trips. After the adjusted error time the relay de-energizes automatically.

The ROCOF monitoring function is deactivated per default and must be activated in the menu.

### Interrupted neutral detection

Interrupted neutral detection is always active when a phase-neutral measuring principle is selected in the menu "Nominal voltage". The interruption of the neutral conductor will result in an immediate tripping of output relay R1 (DDI).

### **Error memory**

The CM-UFD.M22(M) records and logs the last 99 events that caused tripping of the grid feeding monitoring relay as well as any interruption of the control supply voltage. The type of error as well as the current value of the operation counter is recorded into the internal error list, accessible via the menu. The list is stored internally in a non-volatile memory which can be reset by the user.

### **Autotest**

The autotest function allows the verification of the protective functions by increasing the lowest threshold and decreasing the highest threshold respectively, until the measured value for input voltage or frequency equals the threshold. Confirming the start of the autotest routine initiates the threshold sweep with the objective of tripping the output relay R1. For each threshold the device displays the measured switching time up from tripping the output relay until the feedback signal from the external contact of the switching device. If the autotest fails, the cause of error has to be analysed and the test needs to be repeated. Output relay R1 remains de-energized as long as the test has not been passed successfully.

Note: The autotest will cause the CM-UFD.M22(M) to trip four times within a short time. This may lead to voltage fluctuations in the public grid. Therefore, we recommend to disconnect the generating plant manually from the grid before executing the auto test procedure.

# **Modbus RTU\***

This communication interface enables control commands (remote trip, frequency thresholds S1 or S2) to the CM-UFD.M22M and provides status information as well as actual process values.

### **RS-485 Standard**

RS-485 is a serial interface standard for communication over a twisted-pair cable. The RS-485 standard specifies only the electrical characteristics of the bus system. The RS-485 transmission line consists of three wires: A, B and C. The signal transmission is based on the voltage difference between the wires. The isolated signal ground should be connected to prevent common mode voltage between the network devices from drifting outside the allowable limits. RS-485 bus cable should be terminated with a resistor on both ends to prevent signal reflection.

### **Network characteristics**

Bus termination is required to prevent signal reflections from the bus cable ends. The CM-UFD.M22M is not equipped with internal bus termination, therefore external termination resistors have to be used according to Modbus specifications. The Modbus slave address, baud rate and communication timeout can be set in the CM-UFD.M22M. It is possible to configure a maximal time without telegrams from the master before the CM-UFD.M22M triggers the configured bus fault reaction. Per default, a timeout of 10 s is set. When changing communication parameters, no power cycle is necessary.

Cable type and cable length have to be selected according to the Modbus specification. The use of passive bus sublines should be avoided. For integrating Modbus devices into a Modbus TCP network ABB offers a Serial/Ethernet gateway. The recommended type is eILPH.

### Configuration of the Modbus RTU communication menu

- The bus address can be adjusted with the CM-UFD.M22M menu. The CM-UFD.M22M allows an address to be set between 001 and 247
- For Modbus RTU it is necessary to configure at least the baud rate and the parity

### **Bus fault reaction**

The bus fault reaction can be set the following ways:

- Trip R1 Disconnection of the distributed generation from the grid
- Signalization of a bus fault via R3
- Signalization of a bus fault via fault message in the display
- Force external signal The CEI 0-21 standard defines "restrictive thresholds" and "permissive thresholds" for frequency. In case of a missing communication interface, the restrictive thresholds S1 will be activated additionally (see chapter "Operating principle / Monitoring functions").

### ABB Ability™ Electrical Distribution Control System

Over Modbus RTU the CM-UFD.M22M can be connected to the ABB Ability  $^{\text{\tiny{TM}}}$  Electrical Distribution Control System.

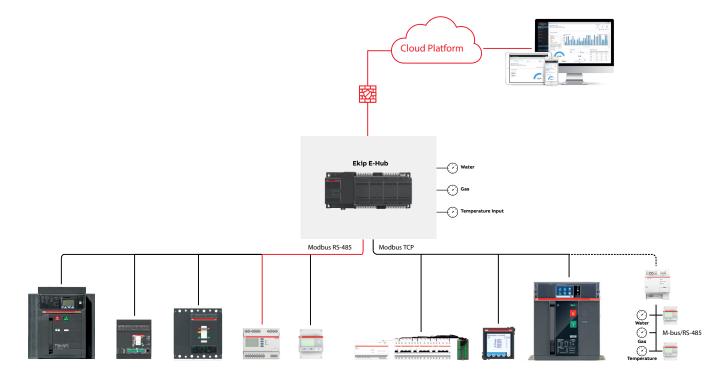
ABB Ability™ Electrical Distribution Control System is built on a state-of-the-art cloud architecture for data collection, processing and storage.

Following information are available in the cloud:

- All measured values (e.g. frequency and voltage)
- I/O Data (e.g. state of relays)
- Diagnostic data (e.g. Last trip reason)

For the initial setup please see "Ekip Com Hub Getting Started" (1SDC200063B0204)

For a detailed integration of the CM-UFD.M22M into ABB Ability™, please see the application note (2CDC112278D0201).



# **Modbus Address Map\***

### Register map

\_

Measuring, read only (FC03, FC04)

Address	Register	Value	Format
0x0000	1	Device Type	22 = CM-UFD.M22M
0x0001	2	Average voltage L1-N	1 Bit = 10 mV
0x0002	3	Average voltage L2-N	1 Bit = 10 mV
0x0003	4	Average voltage L3-N	1 Bit = 10 mV
0x0004	5	Average voltage L1-L2	1 Bit = 10 mV
0x0005	6	Average voltage L2-L3	1 Bit = 10 mV
0x0006	7	Average voltage L3-L1	1 Bit = 10 mV
0x0007	8	Voltage L1-N	1 Bit = 10 mV
0x0008	9	Voltage L2-N	1 Bit = 10 mV
0x0009	10	Voltage L3-N	1 Bit = 10 mV
0x000A	11	Voltage L1-L2	1 Bit = 10 mV
0x000B	12	Voltage L2-L3	1 Bit = 10 mV
0x000C	13	Voltage L3-L1	1 Bit = 10 mV
0x000D	14	Frequency	1 Bit = 10 mHz
0x000E	15	Last trip reason	see table "Last trip reasons Modbus RTU"
0x000F	16	Trip counter	0-65535

\_

Status bits, read only (FC03, FC04)

Address	Register	MSB						Coil n	о.								LSB
0x0010	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
0x0011	18	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17
0x0012	19	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33
0x0013	20	64	63	62	61	60	59	58	57	56	55	54	53	52	51	40	49
0x0014	21	80	79	78	77	76	75	74	73	72	71	70	69	68	67	66	65

Commands, read/write (FC03, FC04, FC06, FC16)

Address	Register	MSB	·			·		Coil n	о.								LSB
0x0015	22	96	95	94	93	92	91	90	89	88	87	86	85	84	83	82	81

\_

Information, read only (FC03, FC04)

Address	Register	Value	Format
0x1000	8	Serial number	Ascii encoded, 2 ascii characters per register
0x1008	1	EKIP Device Identification	Device identification for EKIP
0x1009	2	Software version	Device software version

## Coils map

Status coils at register 17, read only (FC01, FC02)

Address	Coil	CM-UFD.M22M	Description
0x0000	1	Error summary	1, if any coil from 17 to 80 is 1
0x0001	2	Restart delay	No error, restart delay running
0x0002	3	Relay 1	Relay status, 1 = energized
0x0003	4	Relay 2	Relay status, 1 = energized
0x0004	5	Relay 3	Relay status, 1 = energized
0x0005	6	Input Y1	Input status, 1 = closed
0x0006	7	Input Y2	Input status, 1 = closed
0x0007	8	Input Y3	Input status, 1 = closed
0x0008	9	Frequency value invalid	1 = value invalid
0x0009	10	-	-
0x000A	11	-	-
0x000B	12	-	-
0x000C	13	-	-
0x000D	14	-	-
0x000E	15	-	-
0x000F	16	-	-

\_

Status coils at register 18, read only (FC01, FC02)

Address	Coil	CM-UFD.M22M	Description
0x0010	17	OV1 L1-N	Overvoltage 1, L1-N
0x0011	18	OV1 L2-N	Overvoltage 1, L2-N
0x0012	19	OV1 L3-N	Overvoltage 1, L3-N
0x0013	20	OV2 L1-N	Overvoltage 2, L1-N
0x0014	21	OV2 L2-N	Overvoltage 2, L2-N
0x0015	22	OV2 L3-N	Overvoltage 2, L3-N
0x0016	23	UV1 L1-N	Undervoltage 1, L1-N
0x0017	24	UV1 L2-N	Undervoltage 1, L2-N
0x0018	25	UV1 L3-N	Undervoltage 1, L3-N
0x0019	26	UV2 L1-N	Undervoltage 2, L1-N
0x001A	27	UV2 L2-N	Undervoltage 2, L2-N
0x001B	28	UV2 L3-N	Undervoltage 2, L3-N
0x001C	29	-	-
0x001D	30	-	-
0x001E	31	-	-
0x001F	32	-	-

\_

Status coils at register 19, read only (FC01, FC02)

Address	Coil	CM-UFD.M22M	Description
0x0020	33	OV1 L1-L2*	Overvoltage 1, L1-L2
0x0021	34	OV1 L2-L3*	Overvoltage 1, L2-L3
0x0022	35	OV1 L3-L1*	Overvoltage 1, L3-L1
0x0023	36	OV2 L1-L2	Overvoltage 2, L1-L2
0x0024	37	OV2 L2-L3	Overvoltage 2, L2-L3
0x0025	38	OV2 L3-L1	Overvoltage 2, L3-L1
0x0026	39	UV1 L1-L2	Undervoltage 1, L1-L2
0x0027	40	UV1 L2-L3	Undervoltage 1, L2-L3
0x0028	41	UV1 L3-L1	Undervoltage 1, L3-L1
0x0029	42	UV2 L1-L2	Undervoltage 2, L1-L2
0x002A	43	UV2 L2-L3	Undervoltage 2, L2-L3
0x002B	44	UV2 L3-L1	Undervoltage 2, L3-L1
0x002C	45	-	-
0x002D	46	-	-
0x002E	47	-	-
0x002F	48	-	-

<sup>\* 10-</sup>min average

### Status coils at register 20, read only (FC01, FC02)

Address	Coil	CM-UFD.M22M	Description
0x0030	49	OF1	Overfrequency 1
0x0031	50	OF2	Overfrequency 2
0x0032	51	UF1	Underfrequency 1
0x0033	52	UF2	Underfrequency 2
0x0034	53	ROCOF	Rate of change of frequency
0x0035	54	-	-
0x0036	55	REMOTE	Remote trip via Y3
0x0037	56	NEUTRAL	Neutral conductor broken
0x0038	57	DDI-FB	Feedback error Y1
0x0039	58	-	-
0x003A	59	AUTOTEST	Autotest failed
0x003B	60	INTERNAL	Internal error
0x003C	61	-	-
0x003D	62	BUS TRIP	Remote trip via BUS
0x003E	63	BUS FAULT	Bus fault (timeout)
0x003F	64	-	-

### Status coils at register 21, read only (FC01, FC02)

Address	Coil	CM-UFD.M22M
0x0040	65	-
0x0041	66	-
0x0042	67	-
0x0043	68	-
0x0044	69	-
0x0045	70	-
0x0046	71	-
0x0047	72	-
0x0048	73	-
0x0049	74	-
0x004A	75	-
0x004B	76	-
0x004C	77	-
0x004D	78	-
0x004E	79	-
0x004F	80	-

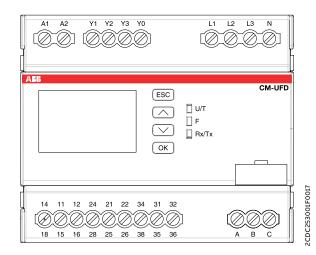
### Command coils at register 22, read/write (FC01, FC02, FC05, FC15)

Address	Coil	CM-UFD.M22M	Description
0x0050	81	TRIP R1	Trip error relays
0x0051	82	TRIP R3	Trip relay R3
0x0052	83	EXT	External signal
0x0053	84	-	-
0x0054	85	-	-
0x0055	86	-	-
0x0056	87	-	-
0x0057	88	-	-
0x0058	89	-	-
0x0059	90	-	-
0x005A	91	-	-
0x005B	92	-	-
0x005C	93	-	-
0x005D	94	-	-
0x005E	95	-	-
0x005F	96	-	-

# Last trip reasons Modbus RTU

	11-1/	
Dezimal	HEX	Comment
0	0x00	Overvoltage L1-N, threshold 1
1	0x01	Overvoltage L2-N, threshold 1
2	0x02	Overvoltage L3-N, threshold 1
3	0x03	Overvoltage L1-N, threshold 2
4	0x04	Overvoltage L2-N, threshold 2
5	0x05	Overvoltage L3-N, threshold 2
6	0x06	Undervoltage L1-N, threshold 1
7	0x07	Undervoltage L2-N, threshold 1
8	0x08	Undervoltage L3-N, threshold 1
9	0x09	Undervoltage L1-N, threshold 2
10	0x0A	Undervoltage L2-N, threshold 2
11	0x0B	Undervoltage L3-N, threshold 2
12	-	-
13	-	-
14	-	-
15	0x0F	Overvoltage L1-L2, threshold 1
16	0x10	Overvoltage L2-L3, threshold 1
17	0x11	Overvoltage L3-L1, threshold 1
18	0x12	Overvoltage L1-L2, threshold 2
19	0x13	Overvoltage L2-L3, threshold 2
20	0x14	Overvoltage L3-L1, threshold 2
21	0x15	Undervoltage L1-L2, threshold 1
22	0x16	Undervoltage L2-L3, threshold 1
23	0x17	Undervoltage L3-L1, threshold 1
24	0x18	Undervoltage L1-L2, threshold 2
25	0x19	Undervoltage L2-L3, threshold 2
26	0x1A	Undervoltage L3-L1, threshold 2
27	-	-
28	-	
29	_	_
30	0x1E	Overfrequency, threshold 1
31	0x1F	Overfrequency, threshold 2
32	0x20	Underfrequency, threshold 1
33	0x21	Underfrequency, threshold 2
34	0x22	ROCOF
35	-	-
36	0x24	Remote trip via Y3
37	0x25	Interrupted neutral detection
38	0x26	Failure in feedback loop 1, DDI feedback
39	-	-
40	0x28	Auto test
	0x28 0x29	Internal error
41	- UX29	- Internal error
42		
43	0x2B	Remote trip via bus
44	0x2C	Bus fault
255	0xFF	No error after power on

# **Electrical connection**



A1-A2
Y1-Y0
Y2-Y0
Y3-Y0
L1, L2, L3, N
11 <sub>15</sub> -12 <sub>16</sub> /14 <sub>18</sub>
21 <sub>25</sub> -22 <sub>26</sub> /24 <sub>28</sub>
31 <sub>35</sub> -32 <sub>36</sub> /34 <sub>38</sub>
A, B, C*

Control supply voltage
Control input 1 for feedback signal
Control input 2 for external signal
Control input 3 for remote trip
Measuring input
Relay R1, c/o (SPDT) contact
Relay R2, c/o (SPDT) contact
Relay R3, c/o (SPDT) contact
Modbus RTU interface\*
A / D0
B / D1
C / Common

# **Configuration**

The CM-UFD.M22(M) is delivered with default settings in accordance to CEI 0-21. The menu structure starts with the main page that shows the real time measured values. Use the arrow keys to switch between the real time voltages and the 10-minutes average voltages.

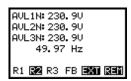
### Display menu structure, navigation and possible configurations

### Main page









### Menu navigation

- · If the display is dark, press any button to light it up
- Press OK button to enter the menu
- Press arrow buttons to move between functions and parameters
- · Press OK button to enter the chosen page
- Press arrow buttons to modify the values of the parameters
- Press OK button to confirm the value and proceed
- Press ESC button to return to the previous menu
- Press arrow buttons more than 1 s to scroll through the menu or password menu

Changes of parameters can be cancelled by pressing the ESC button.

### **Password protection**

Every CM-UFD.M22(M) relay is delivered with the same default password [0000] for protection of its settings and local command. The installer is responsible for the verification of the parameter values and the change of the password with a personal one in order to avoid unwanted modifications.

Visualization of the parameters is always possible, modification only after having entered the password. While entering the password, the password protection is temporarily disabled until the menu is exited.

Only the parameters 'autotest', 'language', 'display switch-off delay' and 'contrast' are not password protected.

# Menu structure

### Main menu

# Nominal voltage I/O setup Monitoring func. Autotest General settings

### Submenu

OK →

← ESC

I/O setup

Relay 1 settings

Relay 2 settings

Relay 3 settings

Feedback loop Y1

External signal Y2

Remote trip Y3

OK →

← ESC

Relay 1 settings
Start-up delay
[ 1.00]s
Re-start delay
[ 0.05]s

V down

ир Л

V down up Λ

Nominal voltage	Menu	Submenu	Options	Configuration possibilities	Step size	CEI 0-21
Relay 1 settings	Nominal voltage Measuring principle		[3L-N], [3L-L], [1L-N]		3L-N	
Relay 2 settings		Nominal voltage		· ·	0.1 V	230 V L-N
Relay 2 settings	/O setup	Relay 1 settings	Start-up delay	[1.00]-[600.00] s	0.05 s	1 s
Eynchronous with relay 1]   Eynchronous with relay 1]   Eynchronous with relay 1], [bus controlled]*, [bus fault]*   Eynchronous with relay 1], [bus fault]*   Eynchronous and the relay 1], [bus fault]*   Eynchronous with relay 1], [bus fault]*   Eynchronous and the relay 1], [bus fault]*   E			Re-start delay	[0.05]-[600.00] s	0.05 s	0.05 s
Synchronous with relay 1], [bus controlled]*, [bus fault]*   Controlled]*, [bus fault]*, [bus fault]*   Controlled]*, [bus fault]*, [bus fault]*   Controlled]*, [bus fault]*, [bus		Relay 2 settings	Working principle			closed-circuit
Peedback loop Y1		Relay 3 settings	Working principle	[synchronous with relay 1], [bus		synchronous with relay 1
Feedback loop Y1			ON-delay	[0.00]-[10.00] s	0.05 s	0 s
Working principle			ON-time	[0.05]-[10.00] s	0.05 s	0.5 s
Trip window   [0.05]-[0.50] s   0.05 s   0.5		Feedback loop Y1	Monitoring	[disabled], [enabled], [tripping only]		enabled
Release window   [0.5]-[600.0] s   0.1 s   0.5 s			Working principle			normally closed
External signal Y2   Working principle   [normally closed], [normally open]   normally open			Trip window	[0.05]-[0.50] s	0.05 s	0.5 s
Remote trip Y3   Working principle   Inormally closed], [normally open]   Normally open			Release window	[0.5]-[6000.0] s	0.1 s	0.5 s
Overvoltage > S1		External signal Y2	Working principle	[normally closed], [normally open]		normally open
Overvoltage > S2		Remote trip Y3	Working principle	[normally closed], [normally open]		normally open
Tripping delay   [0.05]-[600.00] s   0.05 s   0.2 s   0.05 s   0.4 s   0.05 s   0.2 s   0.05 s   0.1 s   0.05 s   0.0 s   0.05 s   0.1 s   0.05 s   0.05 s   0.1 s   0.05 s   0.05 s   0.1 s   0.05 s		Overvoltage >S1	Threshold value	[1.00]-[1.20] xU <sub>n</sub>	0.01 x U <sub>n</sub>	1.1 x U <sub>n</sub>
Undervoltage <\$1	function	Overvoltage >S2	Threshold value	[1.00]-[1.30] xU <sub>n</sub>	0.01 x U <sub>n</sub>	1.15 x U <sub>n</sub>
Tripping delay   [0.05]-[600.00] s   0.05 s   0.4 s			Tripping delay	[0.05]-[600.00] s	0.05 s	0.2 s
Undervoltage <52         Threshold value         [0.05]-[1.00] xUn         0.01 x Un         0.4 x Un           Tripping delay         [0.05]-[600.00] s         0.05 s         0.2 s           Overfrequency >S1         Threshold value         [50.0]-[54.0] Hz         0.1 Hz         50.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Overfrequency >S2         Threshold value         [50.0]-[54.0] Hz         0.1 Hz         51.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s1< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz         49.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s2< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz/s         47.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           ROCOF         Monitoring         [disabled], [enabled]         disabled           Threshold value         [0.100]-[5.000] Hz/s         0.005 Hz/s         1 Hz/s           Number of cycles         [4]-[50]         1         32           Tripping delay         [0.00]-[600.00] s         0.01 s         0.01 s</s2<></s1<>		Undervoltage <s1< td=""><td>Threshold value</td><td>[0.20]-[1.00] xU<sub>n</sub></td><td>0.01 x U<sub>n</sub></td><td>0.85 x U<sub>n</sub></td></s1<>	Threshold value	[0.20]-[1.00] xU <sub>n</sub>	0.01 x U <sub>n</sub>	0.85 x U <sub>n</sub>
Tripping delay         [0.05]-[600.00] s         0.05 s         0.2 s           Overfrequency >S1         Threshold value         [50.0]-[54.0] Hz         0.1 Hz         50.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Overfrequency >S2         Threshold value         [50.0]-[54.0] Hz         0.1 Hz         51.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s1< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz         49.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s2< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz/s         47.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           ROCOF         Monitoring         [disabled], [enabled]         disabled           Threshold value         [0.100]-[5.000] Hz/s         0.005 Hz/s         1 Hz/s           Number of cycles         [4]-[50]         1         32           Tripping delay         [0.00]-[600.00] s         0.01 s         0.01 s</s2<></s1<>			Tripping delay	[0.05]-[600.00] s	0.05 s	0.4 s
Overfrequency >S1         Threshold value         [50.0]-[54.0] Hz         0.1 Hz         50.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Overfrequency >S2         Threshold value         [50.0]-[54.0] Hz         0.1 Hz         51.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s1< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz         49.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s2< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz/s         47.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           ROCOF         Monitoring         [disabled], [enabled]         disabled           Threshold value         [0.100]-[5.000] Hz/s         0.005 Hz/s         1 Hz/s           Number of cycles         [4]-[50]         1         32           Tripping delay         [0.00]-[600.00] s         0.01 s         0.01 s</s2<></s1<>		Undervoltage <s2< td=""><td>Threshold value</td><td>[0.05]-[1.00] xU<sub>n</sub></td><td>0.01 x U<sub>n</sub></td><td>0.4 x U<sub>n</sub></td></s2<>	Threshold value	[0.05]-[1.00] xU <sub>n</sub>	0.01 x U <sub>n</sub>	0.4 x U <sub>n</sub>
Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Overfrequency >S2         Threshold value         [50.0]-[54.0] Hz         0.1 Hz         51.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s1< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz         49.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s2< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz/s         47.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           ROCOF         Monitoring         [disabled], [enabled]         disabled           Threshold value         [0.100]-[5.000] Hz/s         0.005 Hz/s         1 Hz/s           Number of cycles         [4]-[50]         1         32           Tripping delay         [0.00]-[600.00] s         0.01 s         0.01 s</s2<></s1<>			Tripping delay	[0.05]-[600.00] s	0.05 s	0.2 s
Overfrequency >S2         Threshold value         [50.0]-[54.0] Hz         0.1 Hz         51.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s1< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz         49.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s2< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz/s         47.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           ROCOF         Monitoring         [disabled], [enabled]         disabled           Threshold value         [0.100]-[5.000] Hz/s         0.005 Hz/s         1 Hz/s           Number of cycles         [4]-[50]         1         32           Tripping delay         [0.00]-[600.00] s         0.01 s         0.01 s</s2<></s1<>		Overfrequency >S1	Threshold value	[50.0]-[54.0] Hz	0.1 Hz	50.5 Hz
Tripping delay [0.05]-[600.00] s 0.05 s 0.1 s  Underfrequency <s1 0.005="" 0.01="" 0.05="" 0.1="" 1="" 32="" 47.5="" 49.5="" <s2="" [0.00]-[600.00]="" [0.05]-[600.00]="" [0.100]-[5.000]="" [46.0]-[50.0]="" [4]-[50]="" [disabled],="" [enabled]="" cycles="" delay="" disabled="" hz="" monitoring="" number="" of="" rocof="" s="" s<="" td="" threshold="" tripping="" underfrequency="" value=""><td></td><td></td><td>Tripping delay</td><td>[0.05]-[600.00] s</td><td>0.05 s</td><td>0.1 s</td></s1>			Tripping delay	[0.05]-[600.00] s	0.05 s	0.1 s
Underfrequency <s1< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz         49.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           Underfrequency <s2< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz/s         47.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           ROCOF         Monitoring         [disabled], [enabled]         disabled           Threshold value         [0.100]-[5.000] Hz/s         0.005 Hz/s         1 Hz/s           Number of cycles         [4]-[50]         1         32           Tripping delay         [0.00]-[600.00] s         0.01 s         0.1 s</s2<></s1<>		Overfrequency >S2	Threshold value	[50.0]-[54.0] Hz	0.1 Hz	51.5 Hz
Tripping delay [0.05]-[600.00] s 0.05 s 0.1 s  Underfrequency <s2 0.005="" 0.01="" 0.05="" 0.1="" 1="" 32="" 47.5="" [0.00]-[600.00]="" [0.05]-[600.00]="" [0.100]-[5.000]="" [46.0]-[50.0]="" [4]-[50]="" [disabled],="" [enabled]="" cycles="" delay="" disabled="" hz="" monitoring="" number="" of="" rocof="" s="" s<="" td="" threshold="" tripping="" value=""><td></td><td></td><td>Tripping delay</td><td>[0.05]-[600.00] s</td><td>0.05 s</td><td>0.1 s</td></s2>			Tripping delay	[0.05]-[600.00] s	0.05 s	0.1 s
Underfrequency <s2< td="">         Threshold value         [46.0]-[50.0] Hz         0.1 Hz/s         47.5 Hz           Tripping delay         [0.05]-[600.00] s         0.05 s         0.1 s           ROCOF         Monitoring         [disabled], [enabled]         disabled           Threshold value         [0.100]-[5.000] Hz/s         0.005 Hz/s         1 Hz/s           Number of cycles         [4]-[50]         1         32           Tripping delay         [0.00]-[600.00] s         0.01 s         0.1 s</s2<>		Underfrequency <s1< td=""><td>Threshold value</td><td>[46.0]-[50.0] Hz</td><td>0.1 Hz</td><td>49.5 Hz</td></s1<>	Threshold value	[46.0]-[50.0] Hz	0.1 Hz	49.5 Hz
Tripping delay [0.05]-[600.00] s 0.05 s 0.1 s  ROCOF Monitoring [disabled], [enabled] disabled  Threshold value [0.100]-[5.000] Hz/s 0.005 Hz/s 1 Hz/s  Number of cycles [4]-[50] 1 32  Tripping delay [0.00]-[600.00] s 0.01 s 0.1 s			Tripping delay	[0.05]-[600.00] s	0.05 s	0.1 s
Monitoring         [disabled], [enabled]         disabled           Threshold value         [0.100]-[5.000] Hz/s         0.005 Hz/s         1 Hz/s           Number of cycles         [4]-[50]         1         32           Tripping delay         [0.00]-[600.00] s         0.01 s         0.1 s		Underfrequency <s2< td=""><td>Threshold value</td><td>[46.0]-[50.0] Hz</td><td>0.1 Hz/s</td><td>47.5 Hz</td></s2<>	Threshold value	[46.0]-[50.0] Hz	0.1 Hz/s	47.5 Hz
Threshold value       [0.100]-[5.000] Hz/s       0.005 Hz/s       1 Hz/s         Number of cycles       [4]-[50]       1       32         Tripping delay       [0.00]-[600.00] s       0.01 s       0.1 s			Tripping delay	[0.05]-[600.00] s	0.05 s	0.1 s
Number of cycles       [4]-[50]       1       32         Tripping delay       [0.00]-[600.00] s       0.01 s       0.1 s		ROCOF	Monitoring	[disabled], [enabled]		disabled
Tripping delay [0.00]-[600.00] s 0.01 s 0.1 s			Threshold value	[0.100]-[5.000] Hz/s	0.005 Hz/s	1 Hz/s
			Number of cycles	[4]-[50]	1	32
Error-time [0.05]-[600.00] s 0.01 s 30 s			Tripping delay	[0.00]-[600.00] s	0.01 s	0.1 s
			Error-time	[0.05]-[600.00] s	0.01 s	30 s

<sup>\*</sup> For CM-UFD.M22M only

Menu	Submenu	Options	Configuration possibilities	Step size	CEI 0-21
General settings	Local Command	Local Command	[disabled], [enabled]		enabled*
		Change LC password	[****]		
	Language	Language	[English], [Italian]		Italian*
	Display	Switch-off delay	[10]-[600]s	1 s	10 s*
		Contrast	[0]-[9]	1	5*
	Password	Protection	[disabled], [enabled]		disabled*
		Change password	[****]		0000*
	Load settings	"Setting name"			
	Save settings	"Setting name"			
	Information				
Modbus**	Bus mode	Communication	[disabled], [enabled]		disabled*
		Remote trip via bus	[disabled], [enabled]		disabled*
		Fault reaction	[trip R1], [fault message], [force external signal]		fault message*
		Timeout	1-600 s	1 s	10 s*
	Bus config.	Slave address	1-247	1	1*
		Baud rate	[1200], [2400], [4800], [9600], [19200], [38400], [57600], [115200]		19200*
		Parity	[EVEN, ODD, NONE]		EVEN*
Error memory	Error list				
	Error recording	Remote trip via Y3	[disabled], [enabled]		enabled*
		Remote trip via bus	[disabled], [enabled]		enabled*
		Power OFF	[disabled], [enabled]		enabled*
	Reset error memory				
	Operating counter				
	Cumulated OFF-time				
	Trip counter				

<sup>\*</sup> Device default, not affected by loading a setting \*\* For CM-UFD.M22M only

# Display and failure messages

Password
Enter Password
E4W3

When entering, the password is required, in this case E4W3

L1N: 199. 9V L2N: 200. 1V L3N: 199. 7V 49. 99 Hz **[3000]** 

R1 🔯 R3 FB 🖼 REM

Error, ROCOF

L1N: 260. 2V **>51** L2N: 260. 3V **>51** L3N: 260. 0V **>51** 49. 99 Hz Error overvoltage S1 in all three phases detected. If overvoltage occurs in one phase only, >S1 indicates the phase with overvoltage.

Neutral conductor is not connected! R1 R2 R3 FB EXT REM 4-wire connection
The neutral conductor is disconnected or interrupted.
Please check wiring.

L1N: 264.6V 352 L2N: 264.9V 352 L3N: 264.6V 352 49.99 Hz

R1 😰 R3 FB 🖼 REM

R1 🔀 R3 FB EXTREM

Error overvoltage S2 in all three phases detected. If overvoltage occurs in one phase only, >S2 indicates the phase with overvoltage.

L1N: 230. 4V L2N: 230. 5V L3N: 230. 3V 49. 99 Hz R1-F3 Press E50. R1 R2 R3 FB EXT REM Failure in the feedback loop FB. E.g. wiring failure, configuration failure, welded feedback contact in DDI. Please check configuration and installation for failures. After failure removal, press ESC to restart/reset.

L1N: 190, 3V **(51** L2N: 190, 5V **(51** L3N: 190, 1V **(51** 49, 99 Hz

R1 🔀 R3 FB 🖼 TSC

Error undervoltage S1 in all three phases detected. If undervoltage occurs in one phase only, <S1 indicates the phase with undervoltage.

L1N: 220. 5V L2N: 220. 6V L3N: 220. 4V 49. 99 Hz R1-FB Check loop. R1 R2 R3 FB EXT REM Permanent failure in the feedback loop FB. E.g. wiring failure, configuration failure, welded feedback contact in DDI. Failure in configuration or installation must be removed before the failure can be receipted with ESC.

L1N: 90.2V **(52** L2N: 90.3V **(52** L3N: 90.2V **(52** 49.99 Hz

R1 🔀 R3 FB 🖼 REM

Error undervoltage S2 in all three phases detected. If undervoltage occurs in one phase only, <S2 indicates the phase with undervoltage.

L1N: 229. 9U L2N: 229. 2U L3N: 229. 1U 49. 99 Hz Internal error R1 R2 R3 FB EXT REM Failure within the logic or hardware of the device. Remove supply and restart. If failure still occurs, there is a permanent failure in the device.

L1N: 230, 4V L2N: 230, 5V L3N: 230, 2V 51, 00 Hz ▶51

R1 R2 R3 FB EXT TSC

Autotest
U> 230.2V 16ms
Autotest failed

Feedback of DDI interrupted or failure during test.

L1N: 230, 3V L2N: 230, 5V L3N: 230, 1V 51, 99 Hz \$52 R1 \$2 R3 FB \$31 TSC Error overfrequency S2 detected.

Error overfrequency S1 detected.

L1N: 229. 9V L2N: 230. 2V L3N: 229. 9V 49. 99 Hz **Putotes: failed** R1 **[22** R3 FB **EXT** REM Main display / start display after autotest failure. Restart autotest

L1N: 230; 5V L2N: 230; 7V L3N: 230; 3V 49; 00 Hz **(51** 

R1 🔀 R3 FB EXT TSC

Error underfrequency S1 detected.

L1N: 229. 9V L2N: 239. 3V L3N: 229. 7V 49. 99 Hz Remote trip via Y3 R1 [22] R3 FB EXT [25] Remote trip via Y3 Shows that the remote trip is activated via control input Y3 and output relay R1 is de-energized.

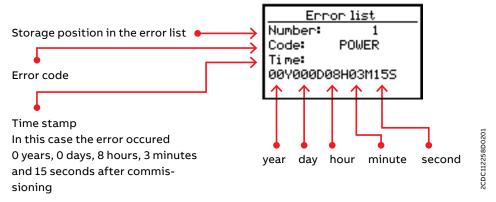
L1N: 230, 6V L2N: 230, 7V L3N: 230, 5V 47, 00 Hz **(SS2**) R1 **[32]** R3 FB **[33]** TSC Error underfrequency S2 detected.

L1N: 229. 9V L2N: 230. 3V L3N: 229. 7V 49. 99 Hz Remote trip via bus R1 22 R3 FB EXT REM Remote trip via Bus Shows that the remote trip is achieved via Bus and output relay R1 is de-energized.

L1N: 229. 9V L2N: 230. 3V L3N: 229. 7V 49. 99 Hz Ext. signal via bus R1 [22] R3 FB EXT REM Device has received an external signal via Bus, to select restrictive threshold for under- and over-frequency. L1N: 229.9V L2N: 230.3V L3N: 229.7V 49.99 Hz Bus fault R1 22 R3 FB EXT REM Error Bus fault Device has detected a bus fault, e.g a cyclic bus master is missing.

### **Error memory**

As soon as one of the above errors occurs, subsequent error codes with the corresponding time stamp will be stored in the error memory:



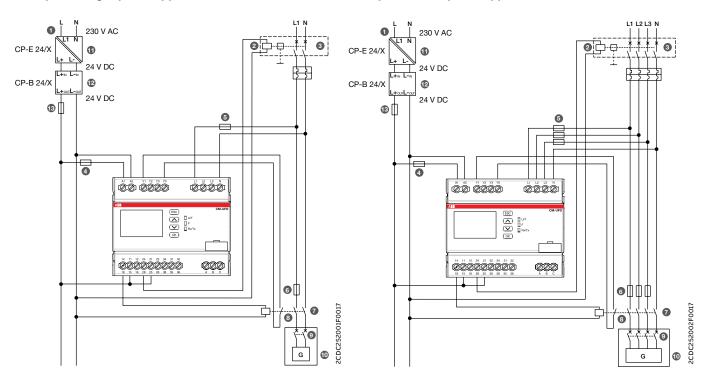
Error code	Explanation	
L1N>S1 or L2N>S1 or L3N>S1	Error, overvoltage S1	10-minutes average value
L1N>S2 or L2N>S2 or L3N>S2	Error, overvoltage S2	
L1N <s1 l2n<s1="" l3n<s1<="" or="" td=""><td>Error, undervoltage S1</td><td></td></s1>	Error, undervoltage S1	
L1N <s2 l2n<s2="" l3n<s2<="" or="" td=""><td>Error, undervoltage S2</td><td></td></s2>	Error, undervoltage S2	
L12>S1 or L23>S1 or L31>S1	Error, overvoltage S1	10-minutes average value
L12>S2 or L23>S2 or L31>S2	Error, overvoltage S2	
L12 <s1 l23<s1="" l31<s1<="" or="" td=""><td>Error, undervoltage S1</td><td></td></s1>	Error, undervoltage S1	
L12 <s2 l23<s2="" l31<s2<="" or="" td=""><td>Error, undervoltage S2</td><td></td></s2>	Error, undervoltage S2	
F>S1	Error, overfrequency S1	
F>S2	Error, overfrequency S2	
F <s1< td=""><td>Error, underfrequency S1</td><td></td></s1<>	Error, underfrequency S1	
F <s2< td=""><td>Error, underfrequency S2</td><td></td></s2<>	Error, underfrequency S2	
ROCOF	Error, ROCOF	
AUTO	Error, autotest	Failure during the autotest routine
REMOTE Y3*	Error, remote trip via control input Y3	
REMOTE BUS*	Error, remote trip via Bus	
BUS FAULT*	Error, Bus fault	CM-UFD.M22M has detected a bus fault (e.g. cyclic bus master is missing)
DDI-FB	Error, DDI feedback	Malfunction of the DDI
POWER	Error, power	Supply voltage is disconnected or too low
NEUTRAL	Error, interrupted neutral detection	
Exxx (e.g. E123)	Internal error	Failure within the logic or hardware of the device

<sup>\*</sup> For CM-UFD.M22M only

# **Connection and wiring**

### Example of single-phase application

### Example of three-phase application



### Legend

- Control supply voltage for CM-UFD.M22(M) (SPI) and tripping device (DDI)\*
- 2. Shunt trip coil for feedback function (P>20 kW). This coil can control DG/DGL or DDG devices
- 3. Main circuit breaker DG or DGL
- 4. Device protection fuse for the CM-UFD.M22(M)
- 5. Protection fuse for the measuring circuit of the CM-UFD.M22(M) (optional)
- 6. DDI short-circuit protection
- 7. DDI: Automatic circuit breaker or contactor equipped with low voltage coil and motor for automatic closure
- 8. Auxiliary contact of DDI, necessary for realizing the feedback function (compulsory for CM-UFD.M22(M))
- 9. Generator (DDG)
- 10. Generator and/or inverter
- 11. Primary switch mode power supply unit CP-E (230 V AC / 24 V DC) for the buffer module CP-B\*
- 12. Ultra-capacitor based buffer module CP-B (24 V DC in/out)
- 13. Wire protection fuse for the output of the buffer module CP-B

In accordance to CEI 0-21 regulation, in case of loss of control supply voltage it's asked to guarantee, at least for 5 seconds, the functionality of the CM-UFD.M22(M), the operability of the DDI and when present the command coil for operating the redundancy device. This function has to be realized by external buffer or UPS devices.

# **Technical data**

Data at  $T_a$  = 25 °C and rated values, unless otherwise indicated

### Input circuits\*

Supply circuit	A1-A2
Rated control supply voltage U <sub>s</sub>	24-240 V AC/DC
Rated control supply voltage U <sub>s</sub> tolerance	-15+10 %
Rated frequency	DC or 50/60 Hz
Frequency range AC	40-70 Hz
Typical current / power consumption 24 \	DC 60 mA / 1.4 W
230	/ AC 22 mA / 5.0 V A
Power failure buffering time	200 ms, acc. LVFRT (110-240 V AC)
	10 ms, acc. IEC/EN 60255-26 (24 V AC/DC)
	1000 ms (230 V AC, 24°C - typical value)

Measuring circuits		L1, L2, L3, N
Nominal voltage of the distribution system U <sub>n</sub>		100.0-230.9 V AC / 173.2-400.0 V AC
Measuring ranges	voltage: line to neutral	0-312 V AC
	voltage: line to line	0-540 V AC
	frequency	40-70 Hz
Accuracy within the temperature range	voltage	≤ 0,5 % ± 0,5 V
	frequency	± 20 mHz
	delay times	≤ 0,1 % ± 20 ms (unless otherwise specified)
Monitoring functions	overvoltage av. (59 S1)	threshold adjustable, 1.00-1.20 x U <sub>n</sub> in 0.01 x U <sub>n</sub> steps
	overvoltage (59 S2)	threshold adjustable, 1.00-1.30 x U <sub>n</sub> in 0.01 x U <sub>n</sub> steps
	undervoltage (27 S1)	threshold adjustable, 0.20-1.00 x U <sub>n</sub> in 0.01 x U <sub>n</sub> steps
	undervoltage (27 S2)	threshold adjustable, 0.05-1.00 x U <sub>n</sub> in 0.01 x U <sub>n</sub> steps
	overfrequency (81>S1)	threshold adjustable, 50.0-54.0 Hz in 0.1 Hz steps
	overfrequency (81>S2)	
	underfrequency (81 <s1) td="" threshold<=""></s1)>	
	underfrequency (81 <s2)< td=""><td></td></s2)<>	
	ROCOF	threshold adjustable, 0.1-5 Hz/s in 0.005 Hz/s steps
Hysteresis related to the threshold values	overvoltage av.	4 %
	overvoltage	
	undervoltage	
	overfrequency	0.1 Hz
	underfrequency	
Measuring method		true RMS
Measuring cycle	ROCOF	adjustable between 4 and 50 periods

Control circuits		Y0, Y1, Y2, Y3	
Number of control inputs		3	
Type of triggering		volt-free triggering, signal source Y0	
Control function	Y1-Y0 control input 1	DDI feedback, trip and release monitoring times adjustable	
	Y2-Y0 control input 2	external signal	
	Y3-Y0 control input 3	remote trip	
Electrical isolation	from the supply voltage	yes	
	from the measuring circuit	no	
	from the relay outputs	yes	
	from the communication interface**	yes	
Maximum switching current in the c	ontrol circuit	6 mA	
No-load voltage at the control inputs		typ. 24 V DC	
Minimum control pulse length		20 ms	
Maximum cable length at the control inputs		10 m	

<sup>\*</sup>Voltage transformers may be used in low voltage applications to transform and adapt the measuring input to ensure the voltage agnitude applied to the input terminals fall within the beforementioned voltage range. This to allow for the effective application of the Under-/Overvoltage and Under-/Overfrequency monitoring functions.

\*\* For CM-UFD.M22M only

### **Timing functions**

Start-up delay R1		adjustable, 1.00-600.00 s in 0.05 s steps
Re-start delay R1 (re-connection after interruption)		adjustable, 0.05-600.00 s in 0.05 s steps
Start-up delay R2		1 s, fixed
ON-delay R3		adjustable, 0.00-10.00 s in 0.05 s steps
ON-time R3		adjustable, 0.05-10.00 s in 0.05 s steps
Trip window, feedback loop		adjustable, 0.05-0.50 s in 0.05 s steps
Release window, feedback loop		adjustable, 0.5-6000.0 s in 0.1 s steps
Tripping delay	overvoltage	adjustable, 0.05-600.00 s in 0.05 s steps; ± 20 ms
	undervoltage	
	overfrequency	
	underfrequency	
ROCOF		adjustable, 0.00-600.00 s in 0.01 s steps; ± 20 ms
Error time ROCOF		adjustable, 0.05-600.00 s in 0.01 s steps
Reaction time	overvoltage av.	max. 3 s
	interrupted neutral conductor	< 150 ms

### User interface

Indication of operational states			
Control supply voltage applied / timing	U/T	LED green on / flashing	
Fault message	F	LED red on	
Modbus frame reception and transmission*	Rx/Tx	LED yellow flashing	
For details see the message on the display	·	, ,	

Display		
Backlight	on	press any button
	off	switch-off delay adjustable, 10-600 s (default 10 s)
Resolution		112 x 64 pixel
Display size		36 x 22 mm

Operating controls		
4 push-buttons for menu navigation, setting and entering		

### Communication interface\*

Supported communication protocol	Modbus RTU
Physical interface	3-wire RS-485
Integrated termination resistors	no
Possible bus addresses	1-247
Baud rates	1.2 / 2.4 / 4.8 / 9.6 /19.2 / 38.4 / 57.6 / 115.2 kBit/s
Typical response time	< 10 ms
Timeout	1-600 s (default 10 s)
RS-485 unit load	1/4 unit load (max. 128 devices)

<sup>\*</sup> For CM-UFD.M22M only

### **Output circuits**

Kind of outputs	11-12/14 (15-16/18)	relay R1, c/o (SPDT) contact, tripping relay for DDI
	21-22/24 (25-26/28)	relay R2, c/o (SPDT) contact, redundancy relay for DG, configurable
	31-32/34 (35-36/38)	relay R3, c/o (SPDT) contact, configurable
Operating principle	11-12/14	closed-circuit principle*
	21-22/24	configurable (open-circuit, closed-circuit, sync. with R1)*
	31-32/34	configurable (disabled, open-circuit, closed-circuit, sync. with R1, bus-controlled, bus fault)*
Contact material		AgNi alloy, Cd-free
Minimum switching voltage / minimum switching current		24 V / 10 mA
Maximum switching voltage / maximum swit	ching current	see "Load limit curves"
Rated operational voltage U <sub>e</sub> and	AC-12 (resistive) at 230 V	4 A
rated operational current I <sub>e</sub>	AC-15 (inductive) at 230 V	3 A
	DC-12 (resistive) at 24 V	4 A
	DC-13 (inductive) at 24 V	2 A
Mechanical lifetime		30 x 10 <sup>6</sup> switching cycles
Electrical lifetime	at AC-12, 230 V AC, 4 A	0.1 x 10 <sup>6</sup> switching cycles
Maximum fuse rating to achieve short-circuit protection	n/c contact	10 A fast-acting
	n/o contact	10 A fast-acting
Conventional thermal current I <sub>th</sub>		5 A

<sup>\*</sup> Closed-circuit principle: Output relay de-energizes if a fault is occuring Open-circuit principle: Output relay energizes if a fault is occuring

### General data

МТВБ		on request
Duty cycle		100 %
Dimensions		see "Dimensional drawing"
Weight	net	0.312 kg (0.687 lb)
Mounting		DIN rail (IEC/EN 60715) TH 35-7.5 and TH 35-15, snap-on mounting without any tool
Mounting position		any
Minimum distance to other units	horizontal / vertical	not necessary
Degree of protection	housing / terminals	IP20

### **Electrical connection**

Connecting capacity	fine-strand with wire end ferrule	1 x 0.25-4 mm² (1 x 24-12 AWG) 2 x 0.25-0.75 mm² (2 x 24-18 AWG)
	fine-strand without wire end ferrule	1 x 0.2-4 mm² (1 x 24-12 AWG) 2 x 0.2-1.5 mm² (2 x 24-16 AWG)
	rigid	1 x 0.2-6 mm² (1 x 24-10 AWG) 2 x 0.2-1.5 mm² (2 x 24-16 AWG)
Stripping length		8 mm (0.31 in)
Tightening torque		0.5-0.6 Nm (4.4-5.3 lb.in)
Recommended screw driver		PH1 / Ø 4.0 mm

### **Environmental data**

Ambient temperature ranges	operation	-20 °C+60 °C (-4+140 °F)
	storage	-20 °C+80 °C (-4+176 °F)
Damp heat, cyclic	IEC/EN 60068-2-30	6 x 24 h cycle, 55 °C, 95 % RH
Climatic class	IEC/EN 60721-3-3	3K5 (no condensation, no ice formation)
Vibration, sinusoidal		class 2
Shock		class 2

\_

### Isolation data

Rated insulation voltage U <sub>i</sub> , overvoltage category		
basic insulation	measuring (L1/L2/L3/N)	300 V, IV 600 V, III
	output 1 / output 2 / output 3	300 V, III
reinforced/doubled insulation	supply / control inputs / outputs / com.interface	300 V, III
	measuring (L1/L2/L3/N) / (supply / outputs / com.interface)	300 V, IV
Rated impulse withstand voltage U <sub>imp</sub>	output 1 / output 2 / output 3	4 kV; 1.2/50 μs
	supply / control inputs / outputs / com.interface	6 kV; 1.2/50 μs
	measuring (L1/L2/L3/N) / (supply / outputs / com.interface)	8 kV; 1.2/50 μs
Pollution degree		3

\_

### Standards/Directives

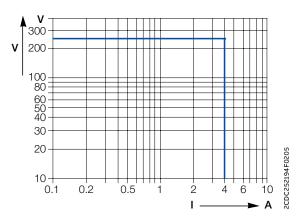
Standards	IEC/EN 60255-1, IEC/EN 60255-26, IEC/EN 60255-27, CEI 0-21
Low Voltage Directive	2014/35/EU
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU

### **Electromagnetic compatibility**

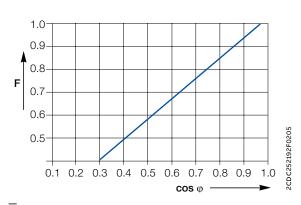
terference immunity to		IEC/EN 60255-26
electrostatic discharge	IEC/EN 61000-4-2	level 3, 6 kV contact discharge, 8 kV air discharge
radiated, radio-frequency, electromagnetic field	IEC/EN 61000-4-3	level 3, 10 V/m; 2.7 GHz
electrical fast transient / burst	IEC/EN 61000-4-4	zone B / level 3, 2 kV / 5 kHz
surge	IEC/EN 61000-4-5	supply circuit and measuring circuit zone B / level 3; 1 kV L-L
conducted disturbances, induced by radio-frequency fields	IEC/EN 61000-4-6	level 3, 10 V
voltage dips, short interruptions and voltage variations	IEC/EN 61000-4-11	class 3
terference emission		IEC/EN 61000-6-3
high-frequency radiated		fulfilled
high-frequency conducted		fulfilled

# **Technical diagrams**

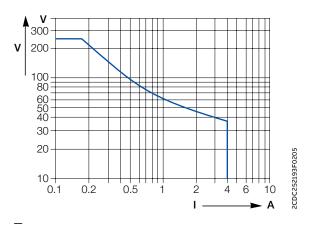
### Load limits curves



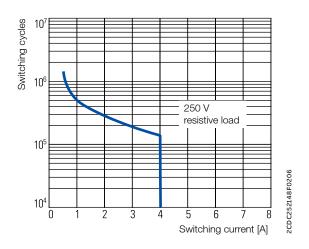
AC load (resistive)



Derating factor F at inductive AC load



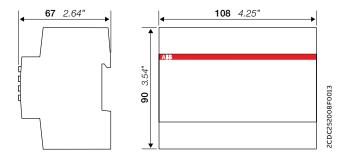
— DC load (resistive)



Contact lifetime

# **Dimensional drawings**

in mm and inches



# **Further documentation**

Document title	Document type	Document number
CM-UFD.M22(M) Grid feeding monitoring relay	Instruction sheet	1SVC 560 514 M0000
How to integrate the grid feeding monitoring relay CM-UFD into ABB Ability	Application note	2CDC 112 278 D0201

You can find the documentation on the internet at www.abb.com/lowvoltage

-> Automation, control and protection -> Electronic relays and controls -> Measuring and monitoring relays.

# **CAD** system files

You can find the CAD files for CAD systems at http://abb-control-products.partcommunity.com -> Low Voltage Products & Systems -> Control Products -> Electronic Relays and Controls.

# **Cyber security**

### Legal disclaimer

The CM-UFD.MxxM is designed to be connected in the ABB and 3rd party products and communicate information data via network interface. It is the user's sole responsibility to provide and continuously ensure a secure connection between the product and the user's network or any other. The user shall establish and maintain any appropriate measures (such as but not limited to the installation of fire-walls, application of authentication measures, encryption of data, installation of antivirus programs, etc.) to protect the product, the network, its system, and the interface against any kind of security breaches, unauthorized access, interference, intrusion, leakage and/or theft of data or information. ABB and its affiliates are not liable for damages and/or losses related to such security breaches, any unau-thorized access, interference, intrusion, leakage and/ or theft of data or information. The data, exam-ples and diagrams in this manual are included solely for the concept or product description and are not to be deemed as a statement of guaranteed properties. All people responsible for applying the equip-ment addressed in this manual must satisfy themselves that each intended application is suitable and acceptable, including that any applicable safety or other operational requirements are complied with. Any risks in applications where a system failure and/or product failure would create a risk for harm to property or persons (including but not limited to personal injuries or death) shall be the sole responsi-bility of the person or entity applying the equipment, and those so responsible are hereby requested to ensure that all measures are taken to exclude or mitigate such risks. This document has been carefully checked by ABB, but deviations cannot be completely ruled out. In case any errors are detected, the reader is kindly requested to notify the manufacturer. Other than under explicit contractual commit-ments, in no event shall ABB be responsible or liable for any loss or damage resulting from the use of this manual or the application of the equipment.

### **Enhancing network security**

The implementation of the following measures is highly recommended in order to enhance the security of networks:

- 1. Network Isolation separate the OT network (operation technology) from the IT network (information technology). This helps prevent any attack reaching the IT network from spread-ing to the OT network.
- 2. Use of firewalls Implement firewalls to prevent unauthorized access to the OT network.
- 3. Use of access control Implement access controls to restrict the human and device access to the OT network.
- 4. Keep software up to date Make sure all software/firmware of the devices are up to date to have the latest security updates installed.
- 5. Reduce attack surface on devices Disable device functions, services and ports not need-ed.
- 6. Replace default passwords Replace all default passwords of the devices to prevent at-tacker from getting access using default credentials.
- 7. Monitor network activity Monitor the OT network for any malicious activities that could be a sign of an attack. Example of network monitoring tool is intrusion detection system (IDS).
- 8. Train employees Train operators and service people on IT and OT security best practices.
- 9. Train employees Train operators and service people on IT and OT security best practices.



We reserve the right to make technical

changes or modify the contents of this