Data sheet

Grid feeding monitoring according to DEWA DRRG standard

CM-UFD.M34

The CM-UFD.M34 is a multifunctional grid feeding monitoring relay. It provides different monitoring functions in accordance with DRRG standard of DEWA to detect over- and undervoltage (10-minutes average value, voltage increase and decrease protection) as well as any changes in grid frequency (frequency increase and decrease protection).

The device is connected between the distributed generation and the public grid in order to disconnect the distributed generation in case of problems (e.g. unstable grid), faults or maintenance on the grid. Additionally monitoring of ROCOF (rate of change of frequency) can be configured.



Characteristics

- Monitoring of voltage and frequency in single- and three-phase mains (2-wire, 3-wire or 4-wire AC systems)
- Type tested according to DEWA DRRG standard
- Over- and undervoltage, 10-minutes average value as well as over- and underfrequency monitoring
- Two-level threshold settings for over-/undervoltage and over-/underfrequency
- ROCOF (rate of change of frequency) monitoring and vector shift detection configurable
- Interrupted neutral detection
- Default setting according to DRRG standard of DEWA
- True RMS measuring principle
- All threshold values and tripping delays adjustable
- Error memory for up to 99 entries (incl. cause of error, measured value, relative timestamp)
- Autotest function
- Password setting protection
- 3 control inputs, e.g. for feedback signal, remote trip
- 3 c/o (SPDT) contacts
- Multiline, backlit LCD display

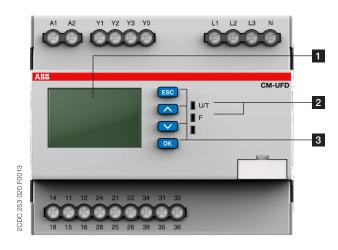
Order data

| Туре | Rated control supply voltage | Measuring range | Order code |
|------------|------------------------------|-----------------------------------|--------------------|
| CM-UFD.M34 | 24-240 V AC/DC | L-L: 0-540 V AC / L-N: 0-312 V AC | 1SVR 560 730 R3403 |



Functions

Operating controls



1 Display

L1N: 229, 7V L2N: 229, 7V L3N: 229, 7V 49, 99 Hz R1 R2 R3 F3 FXT REN

R1 R2 R3 - relay status; in this case R3 is de-energized FB - status feedback loop Y1-Y0; in this case FB is closed EXT - status input external signal; in this case input is closed REM - status remote trip input; in this case input is closed

2 Indication of operational states

U/T: green LED – Control supply voltage applied Timing

F: red LED - Fault message

3 Keypad

ESC: escape / return to previous menu

A: up / value increaseV: down / value decreaseOK: enter / confirm selection

Application

The CM-UFD.M34 is a grid feeding monitoring relay (IP), which is connected between the public grid and the renewable resource generating plant (RRGP) such as photovoltaic systems, wind turbines, block-type thermal power stations. It monitors the voltage and the frequency in the grid and will disconnect the RRGP whenever the measured values are not within the range of the adjusted thresholds. The fault is indicated by LED and the corresponding plain text message is shown on the display.

In conformity with DRRG standard of DEWA, the CM-UFD.M34 relay can be used in all low voltage plants and in medium voltage power plants. The IP relay is mandatory in all low voltage generation plants with power > 10 kW.

Operating mode

The CM-UFD.M34 can be set up to monitor single- and three-phase mains (2-wire, 3-wire as well as 4-wire AC systems). The unit is configurable by front-face push-buttons. A display with the corresponding menu enables the selection of pre-settings as well as the precise adjustment of the different threshold values and corresponding time delays. Furthermore, the display visualizes the measured values clearly. Together with the front-face LEDs, it shows all information about operational states of output relays and control inputs.

The CM-UFD.M34 provides 3 output relays and 3 control inputs. The first output relay R1 $(11_{15}-12_{16}/14_{18})$ is required for disconnection of a distributed generation from the public grid (1st switching unit). The corresponding feedback signal from the external contact is monitored via the first control input Y1-Y0 by the internal logic. The second output relay R2 $(21_{25}-22_{26}/24_{28})$ is redundant to the first one and only activated if output relay R1 has de-energized, but no changed state of the feedback from the external contact has been recognized within the adjusted time delay. In case a feedback signal is present, the redundancy relay does not trip. Once the feedback loop did not change its status after the first output changed the status and the 1st switching unit should disconnect, the CM-UFD.M34 detects this as a failure (e.g. welded contacts of the contactor) and trips the 2nd switching unit.

The third output relay R3 $(31_{35}-32_{36}/34_{38})$ can be used for the closing command of a motor drive for circuit breaker. In case output relay R1 energizes, the adjusted ON-delay starts. When the ON-delay is complete, output relay R3 will be activated for the duration of the ON-time or until R1 de-energizes. In this last case the ON-time is inactive. It is also adjustable to sychronize tripping relay R3 with relay R1.

The operating principle of the relays R2 and R3 is configurable as normally energized (closed-circuit principle) or normally de-energized (open-circuit principle). For safety reasons, the operating principle of R1 is fixed as normally energized (closed-circuit principle).

Two additional control inputs allow to switch from remote between two sets of frequency threshold settings via Y2-Y0 or to trip the grid feeding monitoring relay via the control input Y3-Y0 (remote trip).

Protective functions

If control supply voltage is applied and all phases are present with voltage and frequency values within their permissible range, output relay R1 energizes after the adjusted start-up delay and output relay R2 energizes or de-energizes, depending on the configuration, after a fixed delay of 1 s. Using the default factory setting, both output relays R1 and R2 will be activated synchronously. The green LED U/T flashes while timing and turns steady when the start-up delay is complete.

If a measured value exceeds or falls below the set threshold value, output relay R1 de-energizes after the adjusted delay. The fault is indicated by the red LED F and the type of fault is shown on the display as a plain text message. The event that has caused tripping of the relay is recorded in the event list. The green LED U/T flashes while timing and turns steady when the delay is complete.

As soon as the measured value returns to the tolerance range, taking into account a fixed hysteresis, the red LED F turns off and output relay R1 re-energizes after the adjusted re-start delay. The green LED U/T flashes while timing and turns steady when the delay is complete.

Protective function 34 S1 (10-minutes average value):

The CM-UFD.M34 calculates the sliding average value of the 3 phases over a period of 10 minutes. The voltage values are updated every 3 seconds. If the 10-minutes average value exceeds the threshold value, the output relays trip.

Redundancy functions

The redundancy relay R2 (2nd switching unit) is activated if relay R1 (1st switching unit) has de-energized and if no feedback from the external contact has been recognized by the internal logic via the first control input Y1-Y0 within the adjustable time delay. In case a feedback signal is present, the redundancy relay does not trip.

Output relay R3 (31₃₅-32₃₆/34₃₈)

Output relay R3 can be used for the closing command of a breaker motor. In case output relay R1 energizes, the adjusted ON-delay starts. When timing is complete, output relay R3 will be activated for the duration of the ON-time or until relay R1 de-energizes. In this last case the ON-time is inactive. The operating principle of relay R3 is configurable as closed-circuit, open-circuit principle, disabled or synchronous with relay 1.

ROCOF (Rate of change of frequency df/dt)

This function monitors the rate of change of frequency within a very short time and detects an imminent loss of mains (islanding).

The ROCOF function will detect zero crossings of the grid voltage. It measures the time between the zero crossings and calculates a new frequency after each zero crossing. In case the frequency changes too much since the last zero crossing, the relay will trip. After the adjusted error time the relay de-energizes automatically.

The ROCOF monitoring function is deactivated per default. It can be activated in the menu.

Vector shift detection

This function is another possibility of detecting a loss of mains (islanding).

The vector shift detection is disabled by default and can be manually enabled in the menu. Through zero crossings the device detects the vector shift of mains voltage and de-energizes output relays R1 immediately if the shift exceeds the adjusted threshold value, e.g. 10 °. Only after the set error time the switch-on conditions will be evaluated in order to start an auto reconnection.

Interrupted neutral detection

Interrupted neutral detection is always active when phase-neutral measuring principle is selected in the menu "Nominal voltage". The interruption of the neutral conductor will result in an immediate tripping of output relay R1.

Error memory

The CM-UFD.M34 records and logs the last 99 events that caused tripping of the grid feeding monitoring relay as well as any interruption of the control supply voltage. The type of error as well as the current value of the operation counter is recorded into the internal error list, accessible via the menu "Error memory". The list is stored internally in a non-volatile memory which can be reset by the user.

Local command and external signal

Activation of S1 or S2 thresholds is made by the corresponding combination of the external signal Y2-Y0 and the local command (see tables below).

| Working principle | Input state | Control input |
|-------------------|-------------|---------------|
| normally open | open | 0 |
| normally open | closed | 1 |
| normally closed | open | 1 |
| normally closed | closed | 0 |

Table 1: Truth table for control inputs External Signal Y2-Y0 and Remote trip Y3-Y0

| External signal | Local command | Active thresholds |
|-----------------|---------------|-------------------|
| 0 | disabled | only S2 |
| 1 | disabled | only S2 |
| 0 | enabled | only S2 |
| 1 | enabled | S1 and S2 |

Table 2: Truth table for frequency thresholds

Remote trip

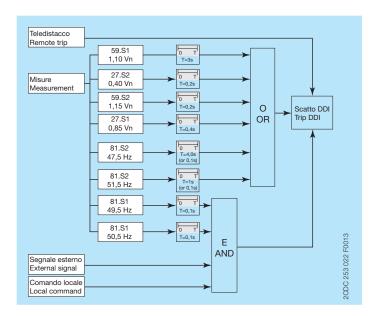
Control input Y3-Y0 allows tripping of the grid feeding monitoring relay from remote. The remote trip input can be configured as normally open or normally closed. If normally closed is configured, the relay trips if Y3-Y0 is opened. If normally open is configured, the relay trips if Y3-Y0 is closed. The output relay 11_{15} - 12_{16} / 14_{18} is tripped by the remote trip within less than 20 ms. When the remote trip input is deactivated, the output relay 11_{15} - 12_{16} / 14_{18} energizes again.

Autotest

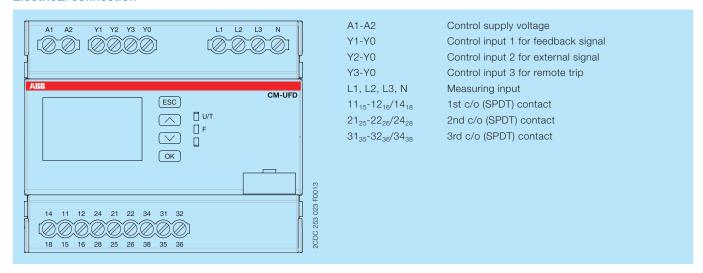
The autotest function allows the verification of the protective functions by increasing the lowest threshold and decreasing the highest threshold respectively, until the measured value for input voltage or frequency equals the threshold. Confirming the start of the autotest routine initiates the threshold sweep with the objective of tripping the relay. For each threshold the device displays the measured switching time up from tripping the output relay till the feedback signal from the external contact of the switching device. If the autotest fails, the cause of error has to be analysed and the test needs to be repeated. Output relay 11_{15} - 12_{16} / 14_{18} remains de-energized as long as the test has not been passed successfully.

Note: The autotest will cause the CM-UFD.M34 to trip four times within a short time. This may lead to voltage fluctuations in the public grid. Therefore, we recommend to disconnect the generating plant manually from the grid before executing the auto test procedure.

Operating principle



Electrical connection

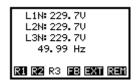


Configuration

The relay is delivered with default settings in accordance to DRRG standard of DEWA. The menu structure starts with the main page that shows the real time measured values. Use the arrow keys to switch between the real time voltages and the 10-minutes average voltages.

Display menu structure, navigation and possible configurations

Main page







Menu navigation

- With a dark display, press any button to light it up
- Press OK button to enter the menu
- Press arrow buttons to move between functions and parameters
- Press OK button to enter the chosen page
- Press arrow buttons to modify the values of the parameters
- Press OK button to confirm the value and proceed
- Press ESC button to return to the previous menu
- Press arrow buttons more than 1 s to scroll through the menu or password menu

Changes of parameters can be cancelled by pressing the ESC button.

Password protection

Every CM-UFD.M34 relay is delivered with the same default password [0000] for protection of its settings and local command. The installer is responsible for the verification of the parameter values and the change of the password with a personal one in order to avoid unwanted modifications.

Visualization of the parameters is always possible, modification only after having entered the password. While entering the password, the password protection is temporarily disabled until the menu is exited.

Only the parameters 'autotest', 'language', 'display switch-off delay' and 'contrast' are not password protected.

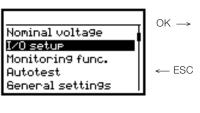
Indication of operational states

| LED | Status information |
|-------------------------|--------------------------------|
| U/T: green LED ON | Control supply voltage applied |
| U/T: green LED flashing | Timing |
| F: red LED ON | Failure |

Menu structure

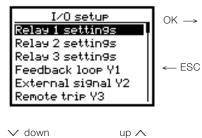
∨ down

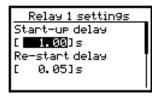




up 🔨

Submenus displays





| Main menu displays | Submenus displays | Options | Configuration possibilities | Step size | DEWA LV | DEWA MV |
|--------------------|--|--------------------------|---|------------|--|-----------------------|
| Nominal | Meas. principle | | [3L-N], [3L-L], [1L-N] | | 3L-N | 3L-L |
| voltage | Nominal voltage | | [57.7] - [230.9] V L-N / [99.9] - [400.0] V L-L | 0.1 V | 230 V L-N | 100 V L-L |
| I/O setup | Relay 1 settings | Start-up delay | [1.00] - [600.00] s | 0.05 s | 1 s | 1 s |
| | | Restart delay | [0.04] - [600.00] s | 0.01 s | 0.05 s | 0.04 s |
| | Relay 2 settings | Working principle | [closed-circuit], [open-circuit] | | closed-circuit | closed-circuit |
| | Relay 3 settings | Working principle | [closed-circuit], [open-circuit], [disabled], [sync. with relay 1] | | sync. with relay 1 | sync. with relay 1 |
| | | ON-delay | [0.00] - [10.00] s | 0.05 s | 0 s | 0 s |
| | | ON-time | [0.05] - [10.00] s | 0.05 s | 0.5 s | 0.5 s |
| | Feedback loop Y1 | Working principle | [normally closed], [normally open], [auto detection] | | normally closed | normally closed |
| | | Trip window | [0.05] - [0.50] s | 0.05 s | 0.5 s | 0.5 s |
| | | Release window | [0.50] - [600.00] s | 0.05 s | 0.5 s | 0.5 s |
| | External signal Y2 | Working principle | [normally closed], [normally open] | | normally closed | normally closed |
| | Remote trip Y3 | Working principle | [normally closed], [normally open] | | normally open | normally open |
| Monitoring | Overvoltage >S1 | Threshold value | [1.00] - [1.20] * Un | 0.01 xUn | 1.1 xUn | 1.1 xUn |
| functions | Overvoltage >S2 | Threshold value | [1.00] - [1.30] * Un | 0.01 xUn | 1.15 xUn | 1.2 xUn |
| | | Tripping delay | [0.05] - [600.00] s | 0.05 s | 0.2 s | 0.6 s |
| | Undervoltage <s1< td=""><td>Threshold value</td><td>[0.20] - [1.00] * Un</td><td>0.01 xUn</td><td>0.85 xUn</td><td>0.85 xUn</td></s1<> | Threshold value | [0.20] - [1.00] * Un | 0.01 xUn | 0.85 xUn | 0.85 xUn |
| | | Tripping delay | [0.05] - [600.00] s | 0.05 s | 0.4 s | 1.5 s |
| | Undervoltage <s2< td=""><td>Threshold value</td><td>[0.05] - [1.00] * Un</td><td>0.01 xUn</td><td>0.4 xUn</td><td>0.3 xUn</td></s2<> | Threshold value | [0.05] - [1.00] * Un | 0.01 xUn | 0.4 xUn | 0.3 xUn |
| | | Tripping delay | [0.05] - [600.00] s | 0.05 s | 0.2 s | 0.2 s |
| | Overfrequency >S1 | Threshold value | [50.0] - [54.0] Hz | 0.1 Hz | 52.5 Hz | 52.5 Hz |
| | | Tripping delay | [0.05] - [600.00] s | 0.05 s | 0.1 s | 0.1 s |
| (| Overfrequency >S2 | Threshold value | [50.0] - [54.0] Hz | 0.1 Hz | 54.0 Hz | 54.0 Hz |
| | | Tripping delay | [0.05] - [600.00] s | 0.05 s | 10.0 s | 10.0 s |
| | Underfrequency <s1< td=""><td>Threshold value</td><td>[46.0] - [50.0] Hz</td><td>0.1 Hz</td><td>47.5 Hz</td><td>47.5 Hz</td></s1<> | Threshold value | [46.0] - [50.0] Hz | 0.1 Hz | 47.5 Hz | 47.5 Hz |
| | | Tripping delay | [0.05] - [600.00] s | 0.05 s | 4.0 s | 4.0 s |
| | Underfrequency <s2< td=""><td>Threshold value</td><td>[46.0] - [50.0] Hz</td><td>0.1 Hz/s</td><td>46.0 Hz</td><td>46.0 Hz</td></s2<> | Threshold value | [46.0] - [50.0] Hz | 0.1 Hz/s | 46.0 Hz | 46.0 Hz |
| | | Tripping delay | [0.05] - [600.00] s | 0.05 s | 10.0 s | 10.0 s |
| | ROCOF | Monitoring | [disabled], [enabled] | | disabled | disabled |
| | | Threshold value | [0.100] - [5.000] Hz/s | 0.005 Hz/s | 2 Hz/s | 2 Hz/s |
| | | Number of cycles | [4] - [50] | 1 | 20 | 20 |
| | | Tripping delay | [0.00] - [600.00] s | 0.01 s | 0.1 s | 0.1 s |
| | | Error-time | [0.05] - [600.00] s | 0.01 s | 1 s | 1 s |
| | Vector Shift VS | Monitoring | [disabled], [enabled] | | disabled | disabled |
| | | Threshold value | [1.0] - [50.0] ° | 0.1 ° | 10 ° | 10 ° |
| | | Error time | [0.05] - [600.00] s | 0.01 s | 1 s | 1 s |
| Autotest | | | [5:55] | | | |
| General | Local command | Local command | [disabled], [enabled] | | enabled 1) | |
| settings | 2000.00111110110 | Change LC password | [****] | | 0.100.00 | |
| | Language | Language | [English], [Italiano] | | English 1) | |
| | Display | Switch-off delay | [10] - [600] s | 1 s | 10 s ¹⁾ | |
| | 2.op.ay | Contrast | [0] - [9] | 1 | 5 ¹⁾ | |
| | Password | Protection | [disabled], [enabled] | | disabled 1) | |
| | . according | Change password | [****] | | 0000 1) | |
| | Load settings | "Setting name" | L 1 | | 0000 | |
| | Save settings | "Setting name" | | | | |
| | Information | Getting name | | | | |
| Error | Error list | | | | | |
| memory | | Pomoto trin | [disabled] [onabled] | | onabled 1) | |
| - , | Error recording | Remote trip Power OFF | [disabled], [enabled] [disabled], [enabled] | | enabled ¹⁾ enabled ¹⁾ | |
| | Reset error memory Operating counter | | | | | |
| | Cumulated OFF- time | | | | | |

¹⁾ Device defaults, not affected by loading a setting

Display and failure messages

L1N: 184. 4V **(Uon** L2N: 184. 7V **(Uon** L3N: 184. 1V **(U1** 49. 99 Hz

R1 R2 R3 Y1 Y2 🚾

The threshold for vector shift detection was exceeded.

L1N: 199.9V L2N: 200.1V L3N: 199.7V 49.99 Hz **[000]**

Error, ROCOF

R1 🔀 R3 FB 🖼 REM

L1N: 260, 2V **351** L2N: 260, 3V **351** L3N: 260, 8V **351** 49, 99 Hz R1 **32** R3 FB **331** REM

Error overvoltage S1 in all three phases detected.

If overvoltage occurs in one phase only, >S1 indicates the phase with overvoltage.

L1N: 199.9V L2N: 200.1V L3N: 199.7V 49.61 Hz **U5**

R1 🔀 R3 FB 🖼 REM

Error, Vector Shift

L1N: 264. 6V \$52 L2N: 264. 9V \$52 L3N: 264. 6V \$52 49. 99 Hz

R1 🔀 R3 FB 🖼 REM

Error overvoltage S2 in all three phases detected.

If overvoltage occurs in one phase only, >S2 indicates the phase with overvoltage.

Neutral conductor is not connected!

R1 R2 R3 FB R REM

4-wire connection

The neutral conductor is disconnected or interrupted.

Please check wiring.

L1N: 190, 3V **(S1** L2N: 190, 5V **(S1** L3N: 190, 1V **(S1** 49, 99 Hz

R1 🔀 R3 FB 🖼 TSC

Error undervoltage S1 in all three phases detected.

If undervoltage occurs in one phase only, <S1 indicates the phase with undervoltage.

L1N: 230. 4V L2N: 230. 6V L3N: 230. 3V 49. 99 Hz R1-FB Press ESC. R1 R2 R3 FB EXT REM Failure in the feedback loop FB. E.g. wiring failure, configuration failure, welded feedback contact in DDI.

Please check configuration and installation for failures. After failure removal, press ESC to restart/reset.

L1N: 90.2V **(52** L2N: 90.3V **(52** L3N: 90.2V **(52** 49.99 Hz

R1 😰 R3 FB 🗺 REM

Error undervoltage S2 in all three phases detected.

If undervoltage occurs in one phase only, <S2 indicates the phase with undervoltage.

L1N: 220, 5V L2N: 220, 6V L3N: 220, 4V 49, 99 Hz R1-FB check loop! R1 R2 R3 FB EXT REM Permanent failure in the feedback loop FB. E.g. wiring failure, configuration failure, welded feedback contact in DDI.

Failure in configuration or installation must be removed before the failure can be receipted with ESC.

L1N: 230, 4V L2N: 230, 5V L3N: 230, 2V 51, 00 Hz **>51**

R1 🔯 R3 FB EXT TSC

Error overfrequency S1 detected

L1N: 229. 9V L2N: 229. 2V L3N: 229. 1V 49. 99 Hz <u>Internal enror</u> R1 **R2** R3 FB EXT REM Failure within the logic or hardware of the device. Remove supply and restart. If failure still occurs, there is a permanent failure in the device.

L1N: 230,3V L2N: 230,5V L3N: 230,1V 51,99 Hz \$52 R1 \$2 R3 FB \$31 TSC Error overfrequency S2 detected

Autotest U> 230.2V 16ms Autotest failed Feedback of DDI interrupted or failure.

L1N: 230, 5V L2N: 230, 7V L3N: 230, 3V 49, 00 Hz **(51**

R1 R2 R3 FB EXT TSC

Error underfrequency S1 detected

L1N: 229, 9V L2N: 230, 2V L3N: 229, 9V 49, 99 Hz Autotest failed R1 **R2** R3 FB **EXT** REM Main display / start display after autotest failure. Restart autotest

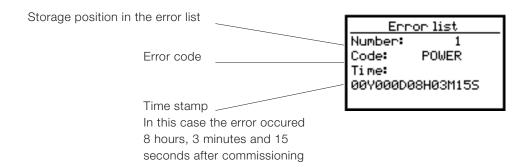
L1N: 230, 6V L2N: 230, 7V L3N: 230, 5V 47, 00 Hz **(52** R1 **[22** R3 FB **[231]** TSC Error underfrequency S2 detected

L1N: 230.0V L2N: 230.3V L3N: 229.7V 49.61 Hz Remote trip R1 R2 R3 V1 V2 V3

Remote trip shows that the remote trip is activated and output relay R1 is de-energized.

Error memory

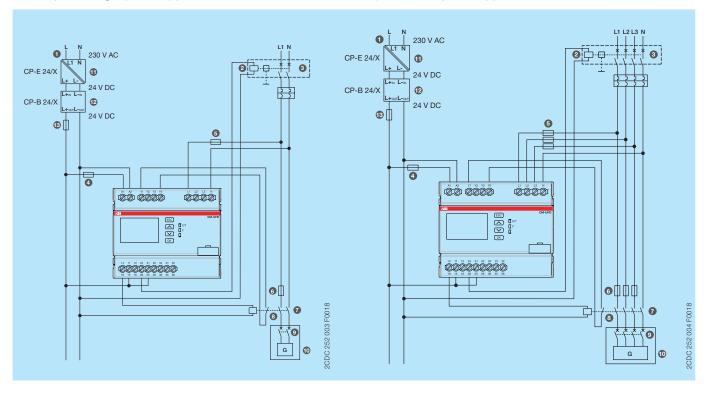
As soon as one of the above errors occurs, subsequent error codes with the corresponding time stamp will be stored in the error memory:



| Error code | Explanation | |
|--|--------------------------------------|--|
| L1N>S1 or L2N>S1 or L3N>S1 | Error, overvoltage S1 | 10-minutes average value |
| L1N>S2 or L2N>S2 or L3N>S2 | Error, overvoltage S2 | |
| L1N <s1 l2n<s1="" l3n<s1<="" or="" td=""><td>Error, undervoltage S1</td><td></td></s1> | Error, undervoltage S1 | |
| L1N <s2 l2n<s2="" l3n<s2<="" or="" td=""><td>Error, undervoltage S2</td><td></td></s2> | Error, undervoltage S2 | |
| L12>S1 or L23>S1 or L31>S1 | Error, overvoltage S1 | 10-minutes average value |
| L12>S2 or L23>S2 or L31>S2 | Error, overvoltage S2 | |
| L12 <s1 l23<s1="" l31<s1<="" or="" td=""><td>Error, undervoltage S1</td><td></td></s1> | Error, undervoltage S1 | |
| L12 <s2 l23<s2="" l31<s2<="" or="" td=""><td>Error, undervoltage S2</td><td></td></s2> | Error, undervoltage S2 | |
| F>S1 | Error, overfrequency S1 | |
| F>S2 | Error, overfrequency S2 | |
| F <s1< td=""><td>Error, underfrequency S1</td><td></td></s1<> | Error, underfrequency S1 | |
| F <s2< td=""><td>Error, underfrequency S2</td><td></td></s2<> | Error, underfrequency S2 | |
| ROCOF | Error, ROCOF | |
| AUTO | Error, autotest | Failure during the autotest routine |
| REMOTE | Error, remote trip | |
| DDI-FB | Error, DDI feedback | Malfunction of the DDI |
| POWER | Error, power | Supply voltage is disconnected or too low |
| NEUTRAL | Error, interrupted neutral detection | |
| Exxx (e.g. E123) | Internal error | Failure within the logic or hardware of the device |

Example of single-phase application

Example of three-phase application



Legend

- 1. Main circuit breaker DG or DGL
- 2. 2nd switching unit: Automatic circuit breaker or contactor equipped with low voltage coil and motor for automatic closure
- 3. Auxiliary contact of 2nd switching unit, necessary for realizing the feedback function (compulsory for CM-UFD.M34)
- 4. Short-circuit protection
- 5. Generator and/or inverter
- 6. Generator (DDG)
- 7. Protection fuse for the measuring circuit of the CM-UFD.M34 (optional)
- 8. Shunt trip coil for feedback function (P>20 kW). This coil can control DG/DGL or DDG devices
- 9. Control supply voltage for CM-UFD.M34 (IP) and tripping device (1st switching unit)
- 10. Device protection fuse for the CM-UFD.M34
- 11. Primary switch mode power supply unit CP-E (230 V AC / 24 V DC) for the buffer module CP-B
- 12. Ultra-capacitor based buffer module CP-B (24 V DC in/out)
- 13. Wire protection fuse for the output of the buffer module CP-B

Technical data

Data at T_a = 25 °C and rated values, unless otherwise indicated

Input circuits

| Process of the second | | |
|---|---|--|
| Supply circuit | | A1-A2 |
| Rated control supply voltage U _s | | 24-240 V AC/DC |
| Rated control supply voltage U _s tolerand | ce | -15+10 % |
| Control supply voltage range | • | 20.4-264 V AC/DC |
| Rated frequency | | DC or 50 Hz |
| Frequency range AC | • | 40-60 Hz |
| Typical current / power consumption | 24 V DC | 64 mA / 1.5 W |
| | 230 V AC | 6.4 mA / 1.5 VA |
| Power failure buffering time | | 200 ms, according to LVFRT (Low Voltage Fault Ride Through) |
| Measuring circuits | | L1, L2, L3, N |
| Monitoring functions acc. to DRRG star | ndard of DEWA | overvoltage av. (59 S1) |
| | | overvoltage (59 S2) |
| | | undervoltage (27 S1) |
| | | undervoltage (27 S2) |
| | | overfrequency (81>S1) |
| | | underfrequency (81 <s1)< td=""></s1)<> |
| | | overfrequency (81>S2) |
| | | underfrequency (81 <s2)< td=""></s2)<> |
| | | Vector shift. configurable |
| | | ROCOF, configurable |
| | | neutral, activated if L-N |
| Measuring ranges | voltage (4-wire system L1, L2, L3-N) | 0-312 V AC |
| | voltage (3-wire system L1, L2, L3) | 0-540 V AC |
| | voltage (2-wire system L-N) | 0-312 V AC |
| | frequency | 40-60 Hz |
| Accuracy of measurements | voltage | ≤ 2 % |
| | frequency | ± 20 mHz |
| | delay times | ≤ 3 % ± 20 ms |
| Accuracy within the temperature range | | ΔU ≤ 0.02 %/°C |
| Threshold values | overvoltage av. (59 S1) | adjustable, 1.00-1.20*U _n in 0.01*U _n steps |
| | overvoltage (59 S2) | adjustable, 1.00-1.30*U _n in 0.01*U _n steps |
| | undervoltage (27 S1) | adjustable, 0.20-1.00*U _n in 0.01*U _n steps |
| | undervoltage (27 S2) | adjustable, 0.05-1.00*U _n in 0.01*U _n steps |
| | overfrequency (81>S1) | adjustable, 50.0-54.0 Hz in 0.1 Hz steps |
| | underfrequency (81 <s1)< td=""><td>adjustable, 46.0-50.0 Hz in 0.1 Hz steps</td></s1)<> | adjustable, 46.0-50.0 Hz in 0.1 Hz steps |
| | overfrequency (81>S2) | adjustable, 50.0-54.0 Hz in 0.1 Hz steps |
| | underfrequency (81 <s2)< td=""><td>adjustable, 46.0-50.0 Hz in 0.1 Hz steps</td></s2)<> | adjustable, 46.0-50.0 Hz in 0.1 Hz steps |
| ROCOF | | adjustable, 0.100-5.000 Hz/s, in 0.005 Hz/s steps |
| | Vector Shift | adjustable, 1.0-50.0 °, in 0.1 ° steps |
| | vootor ormit | |
| Hysteresis related to the threshold value | | 0.95-0.97*U _n |
| Hysteresis related to the threshold value | | 0.95-0.97*U _n 1.03-1.05*U _n |
| Hysteresis related to the threshold value | es overvoltage | |
| Hysteresis related to the threshold value | es overvoltage undervoltage overfrequency | 1.03-1.05*U _n 0.997-0.999*f _n |
| Hysteresis related to the threshold value | es overvoltage undervoltage overfrequency underfrequency | 1.03-1.05*U _n 0.997-0.999*f _n 1.001-1.003*f _n |
| Hysteresis related to the threshold value Rated frequency of the measuring signs Frequency range of the measuring signs | es overvoltage undervoltage overfrequency underfrequency | 1.03-1.05*U _n 0.997-0.999*f _n |

| Measuring circuits | | L1, L2, L3, N |
|---|----------------------------|--|
| Reaction time acc. DRRG standards chapter D.1.4 | overvoltage 1 | adjustable, 0.05-600.00 s in 0.05 s steps, ±3 % ±20 ms |
| and D.2.4 | undervoltage 1 | |
| | undervoltage 2 | |
| | overfrequency 1 | |
| | overfrequency 2 | |
| | underfrequency 1 | |
| | underfrequency 2 | |
| Reaction time neutral interruption | | < 150 ms |
| Measuring cycle at 50 Hz | ROCOF | adjustable, 4 - 50 cycles |
| Control circuits | | Y0, Y1, Y2, Y3 |
| Number | | 3 |
| Type of triggering | | volt-free triggering, signal source Y0 |
| Function of the control inputs | Y1-Y0 control input 1 | DDI feedback, trip and release monitoring times adjustable |
| | Y2-Y0 control input 2 | external signal |
| | Y3-Y0 control input 3 | remote trip |
| Electrical isolation | from the supply voltage | yes |
| | from the measuring circuit | no |
| | from the relay outputs | yes |
| Maximum switching current in the control circuit | 6 mA | |
| No-load voltage at the control inputs (V0-V1, V2, V3) |) | 22-26 V DC |
| Minimum control pulse length | | 20 ms |
| Maximum cable length at the control inputs (unshield | 10 m | |

Timing functions

| Start-up delay R1 (prior to first grid connection or re-connection after interruption) | adjustable, 1.00-600.00 s in 0.05 s steps |
|--|---|
| Restart delay R1 | adjustable, 0.05-600.00 s in 0.05 s steps |
| Start-up delay R2 (prior to first grid connection or re-connection after interruption) | 1 s, fixed |
| ON-delay R3 | adjustable, 0.00-10.00 s in 0.05 s steps |
| ON-time R3 | adjustable, 0.05-10.00 s in 0.05 s steps |
| Trip window, feedback loop Y1 | adjustable, 0.05-0.50 s in 0.05 s steps |
| Release window, feedback loop Y1 | adjustable, 0.50-600.00 s in 0.05 s steps |
| Tripping delays | adjustable, 0.05-600.00 s in 0.05 s steps |
| ROCOF tripping delay | adjustable, 0.00-600.00 s in 0.05 s steps |
| ROCOF error time | adjustable, 0.05-600.00 s in 0.05 s steps |
| Vector Shift error time | adjustable, 0.05-600.00 s in 0.01 s steps |
| | |

User interface

| Indication of operational states | | |
|--|---------------------|--|
| Control supply voltage applied / tripping delay relay 1 active | U/T | LED green on / flashing |
| Fault message | F | LED red on |
| The operational states are additionally displayed through text | on the LCD, details | see table 'Indication of operational states' |
| Display | | |
| Backlight | on | press any button |
| | off | switch-off delay adjustable, 10-600 s (default 10 s) |
| Operating temperature range of the display | clearly visible | -20+60 °C |
| Resolution | • | 112 x 64 pixel |
| Display size | | 36 x 22 mm |
| Operating controls | | |
| 4 push-buttons for menu navigation, setting and entering | | |

Output circuits

| Kind of outputs | 11-12/14 (15-16/18) | 1st c/o (SPDT) contact, tripping relay for DDI |
|---|----------------------------|--|
| Tana or oatpato | 21-22/24 (25-26/28) | <u> </u> |
| | 31-32/34 (35-36/38) | 3rd c/o (SPDT) contact, reading command for breaker motor, also sync. with relay 1 |
| Operating principle | 11-12/14 | closed-circuit principle1) |
| | 21-22/24 | open- or closed-circuit principle1) configurable |
| | 31-32/34 | open- or closed-circuit principle1) configurable |
| Contact material | | AgNi alloy, Cd free |
| Rated operational voltage U _e | | 250 V AC |
| Minimum switching voltage / minimum switching | ching current | 24 V / 10 mA |
| Maximum switching voltage / maximum swi | itching current | see 'Load limit curves' |
| Rated operating current I _e | AC-12 (resistive) at 230 V | 4 A |
| | AC-15 (inductive) at 230 V | 3 A |
| | DC-12 (resistive) at 24 V | 4 A |
| | DC-13 (inductive) at 24 V | 2 A |
| Mechanical lifetime | | 30 x 106 switching cycles |
| Electrical lifetime | at AC-12, 230 V AC, 4 A | 50 x 10 ³ switching cycles |
| Maximum fuse rating to achieve | n/c contact | 10 A fast-acting |
| short-circuit protection | n/o contact | 10 A fast-acting |
| Conventional thermal current I _{th} | | 5 A |

Closed-circuit principle: Output relay de-energizes if a fault is occuring Open-circuit principle: Output relay energizes if a fault is occuring

General data

| MTBF | | on request |
|---------------------------------------|-----------------------|---|
| Repeat accuracy (constant parameters) | | < ± 0.5 % |
| Duty time | | 100 % |
| Dimensions | | see 'Dimensional drawing' |
| Weight | | 0.306 kg (0.675 lb) |
| Material of housing | | PA666FR |
| Mounting | | DIN rail (IEC/EN 60715) TH 35-7.5 and TH 35-15, snap-on mounting without any tool |
| Mounting position | | any |
| Minimum distance to other units | horizontal / vertical | not necessary |
| Degree of protection | housing / terminals | IP20 |

Electrical connection

| Connecting capacity | | 1 x 0.25-4 mm² (1 x 24-12 AWG) 2 x 0.25-0.75 mm² (2 x 24-18 AWG) | |
|---------------------|--------------------------------------|---|--|
| | fine-strand without wire end ferrule | 1 x 0.2-4 mm² (1 x 24-12 AWG) 2 x 0.2-1.5 mm² (2 x 24-16 AWG) | |
| | rigid | 1 x 0.2-6 mm² (1 x 24-10 AWG) 2 x 0.2-1.5 mm² (2 x 24-16 AWG) | |
| Stripping length | | 8 mm (0.315 in) | |
| Tightening torque | | 0.5-0.6 Nm (4.4-5.3 lb.in) | |

Environmental data

| Ambient temperature ranges | • | | |
|----------------------------|--|---|--|
| | storage | -20 °C+80 °C (-4+176 °F) | |
| Damp heat, cyclic | IEC/EN 60068-2-30 6 x 24 h cycle, 55 °C, 95 % RH | | |
| Climatic class | IEC/EN 60721-3-3 | 3K5 (no condensation, no ice formation) | |
| Vibration, sinusoidal | | Class 2 | |
| Shock | | Class 2 | |

Isolation data

| Rated insulation voltage U _i | supply / measuring / output circuits | 600 V |
|--|--------------------------------------|-----------------|
| | output 1 / output 2 / output 3 | |
| Rated impulse withstand voltage U _{imp} | supply / measuring / output circuits | 6 kV; 1.2/50 μs |
| | output 1 / output 2 / output 3 | |
| Basic insulation | supply / measuring / output circuits | |
| | output 1 / output 2 / output 3 | |
| Protective separation (IEC/EN 61140) | supply / measuring / output circuits | 250 V |
| | output 1 / output 2 / output 3 | |
| Pollution degree | | 3 |
| Overvoltage category | | III |

Standards / Directives

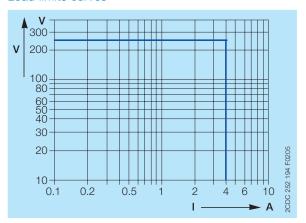
| Standards | IEC/EN 60255-27, EN 50178, DRRG | |
|-----------------------|---------------------------------|--|
| Low Voltage Directive | 2014/35/EU | |
| EMC Directive | 2014/30/EU | |
| RoHS Directive | 2011/65/EU | |

Electromagnetic compatibility

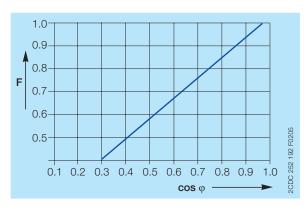
| Interference immunity to | |
|--------------------------|---|
| | Level 3, 6 kV contact discharge, 8 kV air discharge |
| IEC/EN 61000-4-3 | |
| IEC/EN 61000-4-4 | Level 3, 2 kV / 5 kHz |
| IEC/EN 61000-4-5 | Level 3, installation class 3, supply circuit and measuring circuit 1 kV L-L, 2 kV L-N |
| IEC/EN 61000-4-6 | Level 3, 10 V |
| IEC/EN 61000-4-11 | Class 3 |
| IEC/EN 61000-4-13 | |
| Interference emission | |
| IEC/CISPR 22, EN 55022 | |
| IEC/CISPR 22, EN 55022 | Class B |
| | IEC/EN 61000-4-3 IEC/EN 61000-4-4 IEC/EN 61000-4-5 IEC/EN 61000-4-6 IEC/EN 61000-4-11 IEC/EN 61000-4-13 |

Technical diagrams

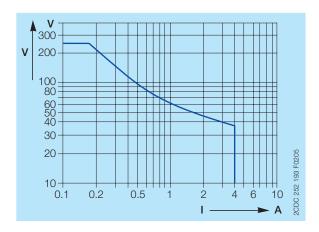
Load limits curves



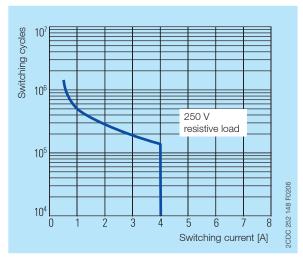
AC load (resistive)



Derating factor F at inductive AC load



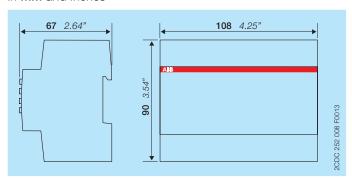
DC load (resistive)



Contact lifetime

Dimensions

in **mm** and inches



Further documentation

| Document title | Document type | Document number |
|--|-------------------|--------------------|
| Electronic relays and controls | Catalog | 2CDC 110 004 C02xx |
| CM-UFD.M34 Grid feeding monitoring relay | Instruction sheet | 1SVC 560 513 M0000 |

You can find the documentation on the internet at www.abb.com/lowvoltage

-> Automation, control and protection -> Electronic relays and controls -> Measuring and monitoring relays.

CAD system files

You can find the CAD files for CAD systems at http://abb-control-products.partcommunity.com

-> Low Voltage Products & Systems -> Control Products -> Electronic Relays and Controls.

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You can find the address of your local sales organisation on the ABB home page http://www.abb.com/contacts -> Low Voltage Products and Systems

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