



Relion® Protection and Control

# 615 series ANSI Operation Manual





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The data, examples and diagrams in this manual are included solely for the concept or product description and are not to be deemed as a statement of guaranteed properties. All persons responsible for applying the equipment addressed in this manual must satisfy themselves that each intended application is suitable and acceptable, including that any applicable safety or other operational requirements are complied with. In particular, any risks in applications where a system failure and/or product failure would create a risk for harm to property or persons (including but not limited to personal injuries or death) shall be the sole responsibility of the person or entity applying the equipment, and those so responsible are hereby requested to ensure that all measures are taken to exclude or mitigate such risks.

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## Conformity

This product complies with the directive of the Council of the European Communities on the approximation of the laws of the Member States relating to electromagnetic compatibility (EMC Directive 2004/108/EC) and concerning electrical equipment for use within specified voltage limits (Low-voltage directive 2006/95/EC). This conformity is the result of tests conducted by ABB in accordance with the product standards EN 50263 and EN 60255-26 for the EMC directive, and with the product standards EN 60255-1 and EN 60255-27 for the low voltage directive. The IED is designed in accordance with the international standards of the IEC 60255 series and ANSI C37.90.

## Safety information



Dangerous voltages can occur on the connectors, even though the auxiliary voltage has been disconnected.



Non-observance can result in death, personal injury or substantial property damage.



Only a competent electrician is allowed to carry out the electrical installation.



National and local electrical safety regulations must always be followed.



The frame of the IED has to be carefully grounded.



When the plug-in unit has been detached from the case, do not touch the inside of the case. The IED case internals may contain high voltage potential and touching these may cause personal injury.



The IED contains components which are sensitive to electrostatic discharge. Unnecessary touching of electronic components must therefore be avoided.



Whenever changes are made in the IED, measures should be taken to avoid inadvertent tripping.



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## Section 1 Introduction

### 1.1 This manual

The operation manual contains instructions on how to operate the IED once it has been commissioned. The manual provides instructions for monitoring, controlling and setting the IED. The manual also describes how to identify disturbances and how to view calculated and measured power grid data to determine the cause of a fault.

### 1.2 Intended audience

This manual addresses the operator, who operates the IED on a daily basis.

The operator must be trained in and have a basic knowledge of how to operate protection equipment. The manual contains terms and expressions commonly used to describe this kind of equipment.

## 1.3 Product documentation

### 1.3.1 Product documentation set

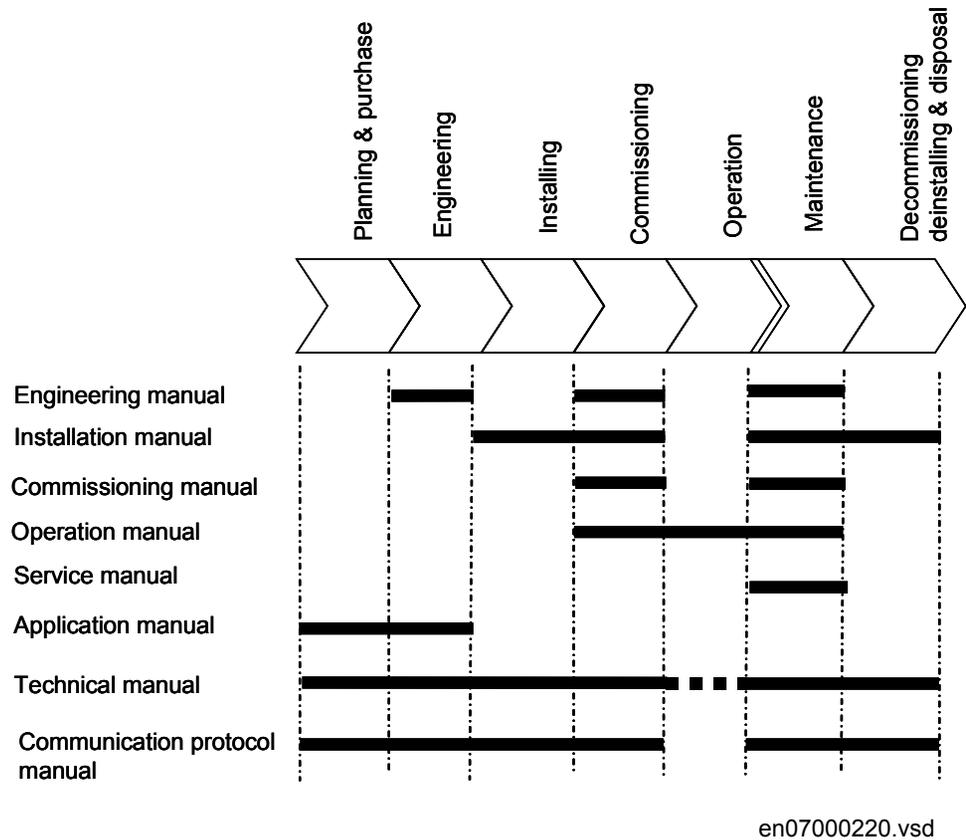


Figure 1: The intended use of manuals in different lifecycles

The engineering manual contains instructions on how to engineer the IEDs using the different tools in PCM600. The manual provides instructions on how to set up a PCM600 project and insert IEDs to the project structure. The manual also recommends a sequence for engineering of protection and control functions, LHMI functions as well as communication engineering for IEC 61850 and other supported protocols.

The installation manual contains instructions on how to install the IED. The manual provides procedures for mechanical and electrical installation. The chapters are organized in chronological order in which the IED should be installed.

The commissioning manual contains instructions on how to commission the IED. The manual can also be used by system engineers and maintenance personnel for assistance

during the testing phase. The manual provides procedures for checking of external circuitry and energizing the IED, parameter setting and configuration as well as verifying settings by secondary injection. The manual describes the process of testing an IED in a substation which is not in service. The chapters are organized in chronological order in which the IED should be commissioned.

The operation manual contains instructions on how to operate the IED once it has been commissioned. The manual provides instructions for monitoring, controlling and setting the IED. The manual also describes how to identify disturbances and how to view calculated and measured power grid data to determine the cause of a fault.

The service manual contains instructions on how to service and maintain the IED. The manual also provides procedures for de-energizing, de-commissioning and disposal of the IED.

The application manual contains application descriptions and setting guidelines sorted per function. The manual can be used to find out when and for what purpose a typical protection function can be used. The manual can also be used when calculating settings.

The technical manual contains application and functionality descriptions and lists function blocks, logic diagrams, input and output signals, setting parameters and technical data sorted per function. The manual can be used as a technical reference during the engineering phase, installation and commissioning phase, and during normal service.

The communication protocol manual describes a communication protocol supported by the IED. The manual concentrates on vendor-specific implementations.

The point list manual describes the outlook and properties of the data points specific to the IED. The manual should be used in conjunction with the corresponding communication protocol manual.



Some of the manuals are not available yet.

## 1.3.2

### Document revision history

Document revision/date	Product series version	History
A/2010-01-20	2.0	First release
B/2011-04-15	4.0	Content updated to correspond to the product series version



Download the latest documents from the ABB web site <http://www.abb.com/substationautomation>.

### 1.3.3 Related documentation

Product series- and product-specific manuals can be downloaded from the ABB web site <http://www.abb.com/substationautomation>.

## 1.4 Symbols and conventions

### 1.4.1 Safety indication symbols



The electrical warning icon indicates the presence of a hazard which could result in electrical shock.



The warning icon indicates the presence of a hazard which could result in personal injury.



The caution icon indicates important information or warning related to the concept discussed in the text. It might indicate the presence of a hazard which could result in corruption of software or damage to equipment or property.



The information icon alerts the reader to important facts and conditions.



The tip icon indicates advice on, for example, how to design your project or how to use a certain function.

Although warning hazards are related to personal injury, it should be understood that operation of damaged equipment could, under certain operational conditions, result in degraded process performance leading to personal injury or death. Therefore, comply fully with all warning and caution notices.

## 1.4.2 Manual conventions

Conventions used in IED manuals. A particular convention may not be used in this manual.

- Abbreviations and acronyms in this manual are spelled out in the glossary. The glossary also contains definitions of important terms.
- Push button navigation in the LHMI menu structure is presented by using the push button icons, for example:  
To navigate between the options, use  and .
- HMI menu paths are presented in bold, for example:  
Select **Main menu/Settings**.
- Menu names are shown in bold in WHMI, for example:  
Click **Information** in the WHMI menu structure.
- LHMI messages are shown in Courier font, for example:  
To save the changes in non-volatile memory, select Yes and press .
- Parameter names are shown in italics, for example:  
The function can be enabled and disabled with the *Operation* setting.
- Parameter values are indicated with quotation marks, for example:  
The corresponding parameter values are "Enabled" and "Disabled".
- IED input/output messages and monitored data names are shown in Courier font, for example:  
When the function picks up, the PICKUP output is set to TRUE.
- Dimensions are provided both in inches and mm. If it is not specifically mentioned then the dimension is in mm.

## 1.4.3 Functions, codes and symbols

All available functions are listed in the table. All of them may not be applicable to all products.

Function	IEC 61850	IEC 60617	REF615	REM615	RET615
<b>Protection</b>					
Three-phase non-directional overcurrent protection, low stage	PHLPTOC1	3I> (1)	51P-1	51P	51P (1)
	PHLPTOC2	3I> (2)	51P-2		51P (2)
Three-phase non-directional overcurrent protection, high stage	PHHPTOC1	3I>> (1)	50P-1	50P	50P-1 (1)
	PHHPTOC2	3I>> (2)	50P-2		50P-1 (2)
	PHHPTOC3	3I>> (3)	50P-4		50P-2 (1)
	PHHPTOC4	3I>> (4)	50P-5		50P-2 (2)
Three-phase non-directional overcurrent protection, instantaneous stage	PHIPTOC1	3I>>> (1)	50P-3		
Table continues on next page					

# Section 1 Introduction

Function	IEC 61850	IEC 60617	REF615	REM615	RET615
Three-phase non-directional long time overcurrent protection, low stage	PHLPTOC1	3I> (3)	51LT		
Three-phase directional overcurrent protection, low stage	DPHLPDOC1	3I> -> (1)	67/51P		67/51P (2)
	DPHLPDOC2	3I> -> (2)			67/51P (1)
Three-phase directional overcurrent protection, high stage	DPHHPDOC1	3I>> -> (1)	67/50P-1		
	DPHHPDOC2	3I>> -> (2)	67/50P-2		
Non-directional earth-fault protection, low stage	EFLPTOC1	Io> (1)	51G	51G	51G
	EFLPTOC2	Io> (2)	51N-1		51N (1)
	EFLPTOC3	Io> (3)	51N-2		51N (2)
	EFLPTOC4	Io> (4)	50SEF		
Non-directional earth-fault protection, high stage	EFHPTOC1	Io>> (1)	50G-1	50G	50G-1
	EFHPTOC2	Io>> (2)	50G-2		50G-2
	EFHPTOC3	Io>> (3)	50N-1		50N-1 (1)
	EFHPTOC4	Io>> (4)	50N-2		50N-1 (2)
	EFHPTOC5	Io>> (5)	50N-4		50N-2 (1)
	EFHPTOC6	Io>> (6)	50N-5		50N-2 (2)
Non-directional earth-fault protection, instantaneous stage	EFIPTOC1	Io>>> (1)	50G-3		
	EFIPTOC2	Io>>> (2)	50N-3		
Directional earth-fault protection, low stage	DEFLPDEF1	Io> -> (1)	67/51N	67/51N	67/51N (2)
	DEFLPDEF2	Io> -> (2)			67/51N (1)
Directional earth-fault protection, high stage	DEFHPDEF1	Io>> -> (1)	67/50N-1		
	DEFHPDEF2	Io>> -> (2)	67/50N-2		
Three phase directional power protection	DPSRDIR1	I1-> (1)	32P-1		
	DPSRDIR2	I1-> (2)	32P-2		
Ground directional power protection	DNZSRDIR1	I2 ->, Io-> (1)	32N-1		
	DNZSRDIR2	I2 ->, Io-> (2)	32N-2		
Negative-sequence overcurrent protection	NSPTOC1	I2> (1)	46-1		46 (1)
	NSPTOC2	I2> (2)	46-2		46 (2)
Phase discontinuity protection	PDNSPTOC1	I2/I1>	46PD		
Residual overvoltage protection	ROVPTOV1	Uo> (1)	59G	59G	59G (2)
	ROVPTOV2	Uo> (2)	59N-1	59N	59N (2)
	ROVPTOV3	Uo> (3)	59N-2		59N (1)
	ROVPTOV4	Uo> (4)			59G (1)
Three-phase undervoltage protection	PHPTUV1	3U< (1)	27-1	27	27 (2)
	PHPTUV2	3U< (2)	27-2		27 (1)
Three-phase overvoltage protection	PHPTOV1	3U> (1)	59-1	59	59 (2)
	PHPTOV2	3U> (2)	59-2		59 (1)

Table continues on next page

Function	IEC 61850	IEC 60617	REF615	REM615	RET615
Positive-sequence undervoltage protection	PSPTUV1	$U1 < (1)$		27PS	
	PSPTUV2	$U1 < (2)$			
Negative-sequence overvoltage protection	NSPTOV1	$U2 > (1)$	47-1	47	47 (2)
	NSPTOV2	$U2 > (2)$	47-2		47 (1)
Frequency protection	FRPFRQ1	$f > / f <, df/dt (1)$	81-1	81	81-1 (2)
	FRPFRQ2	$f > / f <, df/dt (2)$	81-2		81-2 (2)
	FRPFRQ3	$f > / f <, df/dt (3)$			81-1 (1)
	FRPFRQ4	$f > / f <, df/dt (4)$			81-2 (1)
Voltage per hertz protection	OEPVPH1	$U/f > (1)$	24		24-1 (2)
	OEPVPH2	$U/f > (2)$			24-2 (2)
	OEPVPH3	$U/f > (3)$			24-1 (1)
	OEPVPH4	$U/f > (4)$			24-2 (1)
Three-phase thermal protection for feeders, cables and distribution transformers	T1PTTR1	$3I_{th} > F (1)$	49F-1		
	T1PTTR2	$3I_{th} > F (2)$	49F-2		
Three-phase thermal overload protection for power transformers, two time constants	T2PTTR1	$3I_{th} > T$			49T (1)
Negative-sequence overcurrent protection for motors	MNSPTOC1	$I2 > M (1)$		46M-1	
	MNSPTOC2	$I2 > M (2)$		46M-2	
Loss of load supervision	LOFLPTUC1	$3I < (1)$		37M-1	
	LOFLPTUC2	$3I < (2)$		37M-2	
Motor load jam protection	JAMPTOC1	$I_{st} >$		51LR	
Motor start-up supervision	STTPMSU1	$I_{st} > n <$		66/51LRS	
Phase reversal protection	PREVPTOC1	$I2 >>$		46R	
Thermal overload protection for motors	MPTR1	$3I_{th} > M$		49M	
Motor differential protection	MPDIF1	$3dI > M$		87M	
Stabilized and instantaneous differential protection for 2W –transformers	TR2PTDF1	$3dI > T$			87T
Numerical stabilized low impedance restricted earth-fault protection	LREFPND1	$dI_{oLo} >$	87LOZREF		87LOZREF (2)
Circuit breaker failure protection	CCBRBRF1	$3I > / I_o > BF (1)$	50BF-1	50BF	50BF (1)
	CCBRBRF2	$3I > / I_o > BF (2)$	50BF-2		50BF (2)
Three-phase inrush detector	INRPHAR1	$3I2f > (1)$	INR-1		
	INRPHAR2	$3I2f > (2)$	INR-2		
Master trip	TRPPTRC1	Master Trip (1)	86/94-1	86/94-1	86/94-1
	TRPPTRC2	Master Trip (2)	86/94-2	86/94-2	86/94-2

Table continues on next page

Function	IEC 61850	IEC 60617	REF615	REM615	RET615
Arc protection	ARCSARC1	ARC (1)	AFD-1	AFD-1	AFD-1 (2)
	ARCSARC2	ARC (2)	AFD-2	AFD-2	AFD-2 (2)
	ARCSARC3	ARC (3)	AFD-3	AFD-3	AFD-3 (2)
High impedance fault detection	PHIZ1	PHIZ1	HIZ		
Multi-purpose protection <sup>1)</sup>	MAPGAPC1	MAP (1)		MAP (1)	MAP (1)
	MAPGAPC2	MAP (2)		MAP (2)	MAP (2)
	MAPGAPC3	MAP (3)		MAP (3)	MAP (3)
Load shedding and restoration	LSHDPFRQ1	UFLS/R (1)	81LSH-1		81LSH-1 (2)
	LSHDPFRQ2	UFLS/R (2)	81LSH-2		81LSH-2 (2)
	LSHDPFRQ3	UFLS/R (3)			81LSH-1 (1)
	LSHDPFRQ4	UFLS/R (4)			81LSH-2 (1)
Loss of phase	PHPTUC1	3I< (1)	37-1		37 (1)
	PHPTUC2	3I< (2)	37-2		
<b>Control</b>					
Circuit-breaker control	CBXCBR1	I <-> O CB (1)	52-1	52	52 (1)
	CBXCBR2	I <-> O CB (2)	52-2		52 (2)
Emergency startup	ESMGAPC1	ESTART		62EST	
Auto-reclosing	DARREC1	O -> I	79		
Tap changer position indication	TPOSSLTC1	TPOSM			84T
Synchronism and energizing check	SECRSYN1	SYNC	25		
<b>Condition monitoring</b>					
Circuit-breaker condition monitoring	SSCBR1	CBCM (1)	52CM-1	52CM	52CM (1)
	SSCBR2	CBCM (2)	52CM-2		52CM (2)
Trip circuit supervision	TCSSCBR1	TCS (1)	TCM-1	TCM-1	TCM-1
	TCSSCBR2	TCS (2)	TCM-2	TCM-2	TCM-2
Current circuit supervision	CCRDIF1	MCS 3I	CCM	CCM	
Advanced current circuit supervision for transformers	CTSRCTF1	MCS 3I, I2			MCS 3I, I2
Fuse failure supervision	SEQRFUF1	FUSEF (1)	60-1	60	60 (1)
	SEQRFUF2	FUSEF (2)	60-2		60 (2)
Cable fault detection	RCFD1	RCFD1	CFD		
Runtime counter for machines and devices	MDSOPT1	OPTS (1)		OPTM-1	
	MDSOPT2	OPTS (2)		OPTM-2	
<b>Measurement</b>					
Three-phase current measurement	CMMXU1	3I	IA, IB, IC	IA, IB, IC	IA, IB, IC (1)
	CMMXU2	3I(B)	IA, IB, IC (2)	IA, IB, IC (2)	IA, IB, IC (2)
Table continues on next page					

Function	IEC 61850	IEC 60617	REF615	REM615	RET615
Sequence current measurement	CSMSQI1	I1, I2, I0	I1, I2, I0	I1, I2, I0	I1, I2, I0 (1)
	CSMSQI2	I1, I2, I0(B)	I1, I2, I0 (2)	I1, I2, I0 (2)	I1, I2, I0 (2)
Residual current measurement	RESCMMXU1	I <sub>o</sub>	IG	IG	IG
Three-phase voltage measurement	VMMXU1	3U	VA, VB, VC	VA, VB, VC	VA, VB, VC (1)
	VMMXU2	3U(B)	VA, VB, VC (2)		VA, VB, VC (2)
Residual voltage measurement	RESVMMXU1	U <sub>o</sub>	VG	VG	VG
	RESVMMXU2	U <sub>o</sub>	VG	VG	VG
Sequence voltage measurement	VSMSQI1	U1, U2, U0	V1, V2, V0	V1, V2, V0	V1, V2, V0 (1)
	VSMSQI2	U1, U2, U0(B)	V1, V2, V0 (2)		V1, V2, V0 (2)
Single-phase power and energy measurement	SPEMMXU1	SP, SE	SP, SE-1	SP, SE	SP, SE (1)
	SPEMMXU2	SP, SE(B)	SP, SE-2		SP, SE (2)
Three-phase power and energy measurement	PEMMXU1	P, E	P, E-1	P, E	P, E (1)
	PEMMXU2	P, E(B)	P, E-2		P, E (2)
Current total demand distortion	CMHAI1	PQM3I	PQI-1		
	CMHAI2	PQM3I(B)	PQI-2		
Voltage total harmonic distortion	VMHAI1	PQM3U	PQVPH-1		
	VMHAI2	PQM3U(B)	PQVPH-2		
Voltage variation	PHQVVR1	PQ 3U<>	PQSS-1		
	PHQVVR2	PQ 3U<>(B)	PQSS-2		
Load profile	LDPMSTA1	-	LoadProf		
2 RTD +1 mA	XARGGIO130	X130 (AIM+RTD)			
6 RTD + 2 mA measurement	XRGGIO130	X130 (RTD)			
Frequency measurement	FMMXU1	f	f	f	f
	FMMXU2	f			f
<b>Other</b>					
Minimum pulse timer (2 pcs)	TPGAPC1	TP (1)	TP (1)	TP (1)	TP (1)
	TPGAPC2	TP (2)	TP (2)	TP (2)	TP (2)
	TPGAPC3	TP (3)	TP (3)	TP (3)	TP (3)
	TPGAPC4	TP (4)	TP (4)	TP (4)	TP (4)
Minimum pulse timer (2 pcs, second resolution)	TPSGAPC1	TPS (1)	62CLD-1		
	TPSGAPC2	TPS (2)	62CLD-3		
Minimum pulse timer (2 pcs, minute resolution)	TPMGAPC1	TPM (1)	62CLD-2		
	TPMGAPC2	TPM (2)	62CLD-4		
Pulse timer (8 pcs)	PTGAPC1	PT (1)	PT-1	PT-1	PT-1
	PTGAPC2	PT (2)	PT-2	PT-2	PT-2
Table continues on next page					

Function	IEC 61850	IEC 60617	REF615	REM615	RET615
Time delay off (8 pcs)	TOFGAPC1	TOF (1)	TOF-1	TOF-1	TOF-1
	TOFGAPC2	TOF (2)	TOF-2	TOF-2	TOF-2
Time delay on (8 pcs)	TONGAPC1	TON (1)	TON -1	TON -1	TON -1
	TONGAPC2	TON (2)	TON -2	TON -2	TON -2
Set reset (8 pcs)	SRGAPC1	SR (1)	SR-1	SR-1	SR-1
	SRGAPC2	SR (2)	SR-2	SR-2	SR-2
Move (8 pcs)	MVGAPC1	MV (1)	MV-1	MV-1	MV-1
	MVGAPC2	MV (2)	MV-2	MV-2	MV-2
<b>Logging functions</b>					
Disturbance recorder	RDRE1	-	DFR	DFR	DFR
Fault recorder	FLMSTA1	-	FR	FR	FR
Sequence event recorder	SER	-	SER	SER	SER
Fault location	DRFLO1	FLO	FLO		

1) Multi-purpose protection is used for, for example, RTD/mA based protection.

## Section 2 Environmental aspects

### 2.1 Sustainable development

Sustainability has been taken into account from the beginning of the product design including the pro-environmental manufacturing process, long life time, operation reliability and disposing of the IED.

The choice of materials and the suppliers have been made according to the EU RoHS directive (2002/95/EC). This directive limits the use of hazardous substances which are the following:

**Table 1:** *Maximum concentration values by weight per homogeneous material*

Substance	Proposed maximum concentration
Lead - Pb	0.1%
Mercury - Hg	0.1%
Cadmium - Cd	0.01%
Hexavalent Chromium Cr (VI)	0.1%
Polybrominated biphenyls - PBB	0.1%
Polybrominated diphenyl ethers - PBDE	0.1%

Operational reliability and long life time have been assured with extensive testing during the design and manufacturing processes. Moreover, long life time is supported by maintenance and repair services as well as by the availability of spare parts.

Design and manufacturing have been done under a certified environmental system. The effectiveness of the environmental system is constantly evaluated by an external auditing body. We follow environmental rules and regulations systematically to evaluate their effect on our products and processes.

### 2.2 Disposing of the IED

Definitions and regulations of hazardous materials are country-specific and change when the knowledge of materials increases. The materials used in this product are typical for electric and electronic devices.

All parts used in this product are recyclable. When disposing of an IED or its parts contact a local waste handler who is authorized and specialized in disposing electronic waste. These handlers can sort the material by using dedicated sorting processes and dispose of the product according to the local requirements.

**Table 2: Materials of the IED parts**

IED	Parts	Material
Case	Metallic plates, parts and screws	Steel
	Plastic parts	PC <sup>1)</sup> , LCP <sup>2)</sup>
	Electronics plug in module	Various
Plug-in unit	Electronics plug in modules	Various
	Electronics LHMI module	Various
	Plastic parts	PC, PBT <sup>3)</sup> , LCP, PA <sup>4)</sup>
	Metallic parts	Aluminium
Package	Box	Cardboard
Attached material	Manuals	Paper

- 1) Polycarbonate
- 2) Liquid crystal polymer
- 3) Polybutylene terephthalate
- 4) Polyamide

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## Section 3      615 series overview

### 3.1              Overview

615 series is a product family of IEDs designed for protection, control, measurement and supervision of utility substations and industrial switchgear and equipment. The design of the IEDs has been guided by the IEC 61850 standard for communication and interoperability of substation automation devices.

The IEDs feature draw-out-type design with a variety of mounting methods, compact size and ease of use. Depending on the product, optional functionality is available at the time of order for both software and hardware, for example, autoreclosure and additional I/Os.

The 615 series IEDs support a range of communication protocols including IEC 61850 with GOOSE messaging, Modbus<sup>®</sup> and DNP3.

## 3.2 Local HMI

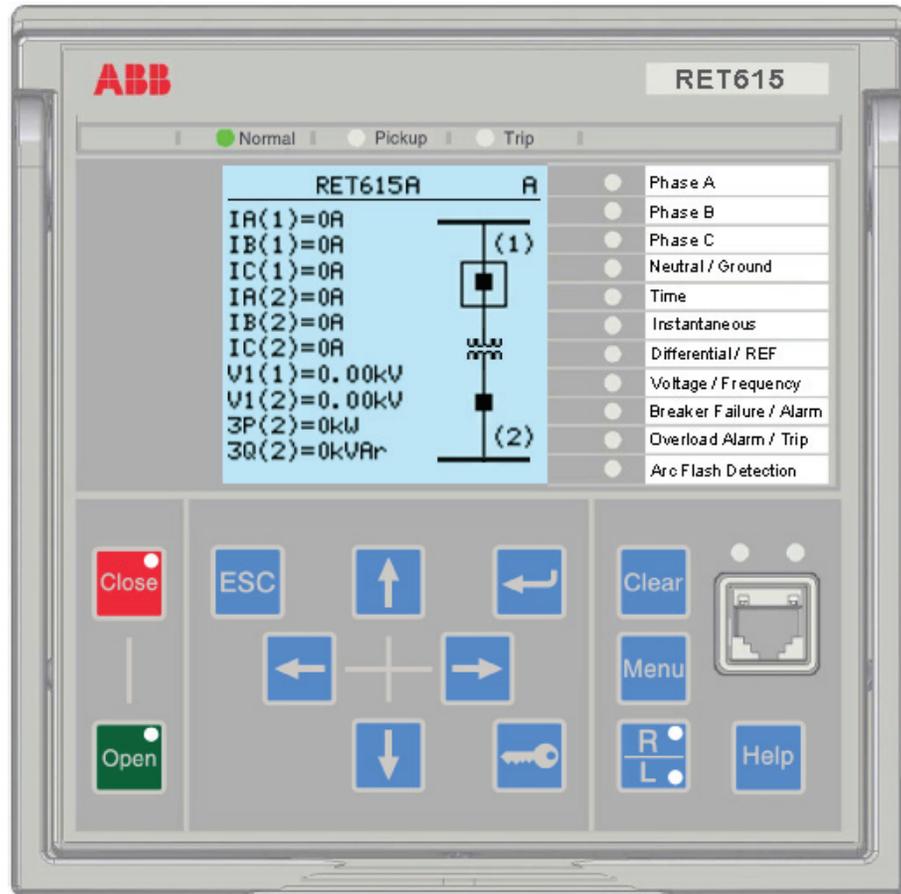


Figure 2: LHMI

The LHMI of the IED contains the following elements:

- Display
- Buttons
- LED indicators
- Communication port

The LHMI is used for setting, monitoring and controlling.

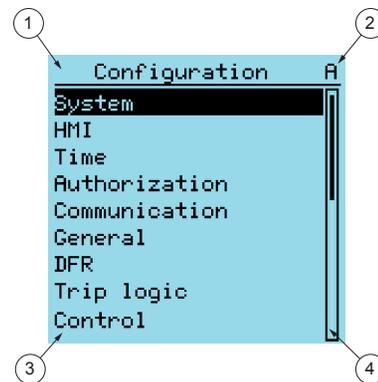
### 3.2.1 Display

The LHMI includes a graphical display that supports two character sizes. The character size depends on the selected language.

**Table 3:** *Characters and rows on the view*

Character size	Rows in view	Characters on row
Small, mono-spaced (6x12 pixels)	10 rows with large screen	20

The display view is divided into four basic areas.



**Figure 3:** *Display layout*

- 1 Header
- 2 Icon
- 3 Content
- 4 Scroll bar (displayed when needed)

- The header area at the top of the display view shows the current location in the menu structure.
- The icon area at the upper right corner of the display shows the current action or user level.

Current action is indicated by the following characters:

- U: Font/Firmware is being updated
- S: Parameters are being stored
- !: Warning and/or indication

Current user level is indicated by the following characters:

- V: Viewer
  - O: Operator
  - E: Engineer
  - A: Administrator
- The content area shows the menu content.
  - If the menu contains more rows than the display can show at a time, a scroll bar is displayed on the right.

The display is updated either cyclically or based on changes in the source data such as parameters or events.

### 3.2.2 LEDs

The LHMI includes three protection indicators above the display: Normal, Pickup and Trip.

There are also 11 matrix programmable LEDs on front of the LHMI. The LEDs can be configured with PCM600 and the operation mode can be selected with the LHMI, WHMI or PCM600.

There are two additional LEDs which are embedded into the control buttons  and . They represent the status of breaker 1 (CBXCBR1).

### 3.2.3 Keypad

The LHMI keypad contains push-buttons which are used to navigate in different views or menus. With the push-buttons you can give open or close commands to one object in the primary circuit, for example, a circuit breaker, a contactor or a disconnecter. The push-buttons are also used to acknowledge alarms, reset indications, provide help and switch between local and remote control mode.

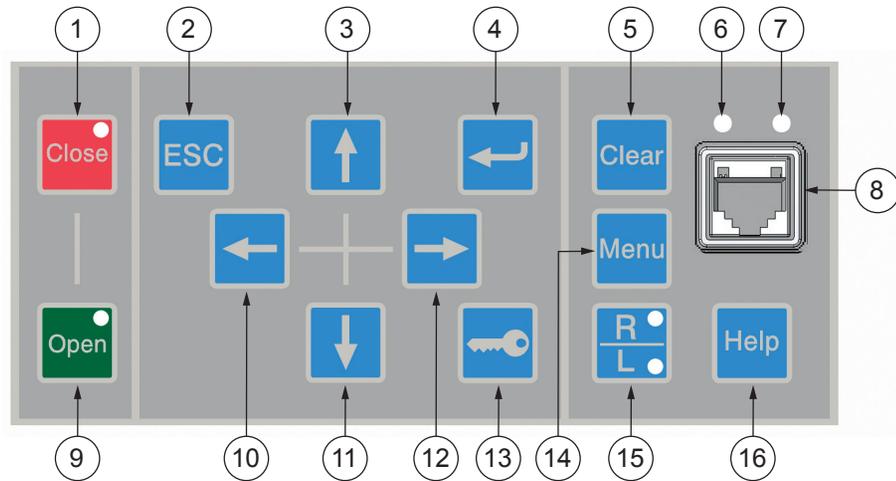


Figure 4: LHM1 keypad with object control, navigation and command push-buttons and RJ-45 communication port

- 1 Close
- 2 Escape
- 3 Up
- 4 Enter
- 5 Clear
- 6 Uplink LED
- 7 Communication LED
- 8 Communication port
- 9 Open
- 10 Left
- 11 Down
- 12 Right
- 13 Key
- 14 Menu
- 15 Remote/Local
- 16 Help

### Object control

If the control position of the IED is set to local with the R/L button, the IED can be controlled using the object control buttons.

**Table 4:** *Object control push-buttons*

Name	Description
 Close	Closing the object. The LED indicates the current object state.
 Open	Opening the object. The LED indicates the current object state.

## Navigation

The arrow buttons are used for navigation. To scroll information, press the arrow button several times or simply keep it pressed down.

**Table 5:** *Navigation push-buttons*

Name	Description
 ESC	<ul style="list-style-type: none"> <li>Leaving setting mode without saving the values.</li> <li>Cancelling certain actions.</li> <li>Adjusting the display contrast in combination with  or .</li> <li>Changing the language in combination with .</li> <li>Running the display test in combination with .</li> <li>Deleting a character in combination with  when editing a string.</li> <li>Inserting a space in combination with  when editing a string.</li> </ul>
 Enter	<ul style="list-style-type: none"> <li>Entering parameter setting mode.</li> <li>Confirming a new value of a setting parameter.</li> </ul>
 Up  Down	<ul style="list-style-type: none"> <li>Moving up and down in menus.</li> <li>Scrolling active digits of a parameter when entering a new setting value.</li> </ul>
 Left  Right	<ul style="list-style-type: none"> <li>Moving left and right in menus.</li> <li>Changing the active digit of a parameter when entering a new setting value.</li> </ul>
 Key	<ul style="list-style-type: none"> <li>Activating the authorization procedure, when the user is not logged in.</li> <li>Logging out, when the user is currently logged in.</li> </ul>

## Commands

**Table 6:** *Command push-buttons*

Name	Description
 Menu	<ul style="list-style-type: none"> <li>Moving directly to main menu, if currently in any other menu.</li> <li>Moving between main menu, measurements and single-line diagram views.</li> </ul>
 R/L	<p>Changing the control position (remote or local) of the device.</p> <ul style="list-style-type: none"> <li>When the R LED is lit, remote control is enabled and local control disabled.</li> <li>When the L LED is lit, local control is enabled and remote control disabled.</li> <li>When none of the LEDs are lit, both control positions are disabled.</li> </ul>
 Clear	<ul style="list-style-type: none"> <li>Activating the Clear/Reset view.</li> <li>Clearing indications and LEDs. The first three-second press clears the indications. The second three-second press clears the programmable LEDs. Requires appropriate user rights.</li> </ul>
 Help	Showing context sensitive help messages.

### 3.2.4

## Local HMI functionality

#### 3.2.4.1

### Protection and alarm indication

#### Protection indicators

The protection indicator LEDs are Normal, Pickup and Trip.

**Table 7:** *Normal LED*

LED state	Description
Off	Auxiliary supply voltage is disconnected.
On	Normal operation.
Flashing	Internal fault has occurred or the IED is in test mode. Internal faults are accompanied by an indication message.

**Table 8:** Pickup LED

LED state	Description
Off	Normal operation.
On	<p>A protection function has picked up and an indication message is displayed.</p> <ul style="list-style-type: none"> <li>If several protection functions pick up within a short time, the last pickup is indicated on the display.</li> </ul>
Flashing	<p>A protection function is blocked.</p> <ul style="list-style-type: none"> <li>The blocking indication disappears when the blocking is removed or when the protection function is reset.</li> </ul>

**Table 9:** Trip LED

LED state	Description
Off	Normal operation.
On	<p>A protection function has tripped and an indication message is displayed.</p> <ul style="list-style-type: none"> <li>The trip indication is latching and must be reset via communication or by pressing <b>Clear</b>.</li> <li>If several protection functions trip within a short time, the last trip is indicated on the display.</li> </ul>

## Alarm indicators

The 11 matrix programmable LEDs are used for alarm indication.

**Table 10:** Alarm indications

LED state	Description
Off	Normal operation. All activation signals are off.
On	<ul style="list-style-type: none"> <li>Non-latched mode: activation signal is still on.</li> <li>Latched mode: activation signal is still on, or it is off but has not been acknowledged.</li> <li>Latched flashing mode: activation signal is still on but has been acknowledged.</li> </ul>
Flashing	<ul style="list-style-type: none"> <li>Non-latched flashing mode: activation signal is still on.</li> <li>Latched flashing mode: activation signal is still on, or it is off but has not been acknowledged.</li> </ul>

### 3.2.4.2 Parameter management

The LHMI is used to access the IED parameters. Three types of parameters can be read and written.

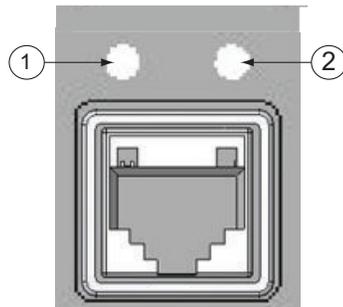
- Numerical values
- String values
- Enumerated values

Numerical values are presented either in integer or in decimal format with minimum and maximum values. Character strings can be edited character by character. Enumerated values have a predefined set of selectable values.

### 3.2.4.3 Front communication

The RJ-45 port in the LHMI enables front communication. Two LEDs are located above the communication port.

- The green uplink LED on the left is lit when the cable is successfully connected to the port.
- The yellow communication LED on the right flashes when the IED communicates with the connected device.



*Figure 5: RJ-45 communication port and indication LEDs*

- 1 Uplink LED
- 2 Communication LED

When a computer is connected to the IED, the IED's DHCP server for the front interface assigns an IP address to the computer. The fixed IP address for the front port is 192.168.0.254.

---

## 3.3 Web HMI

The WHMI enables the user to access the IED via a web browser. The supported web browser version is Internet Explorer 7.0 or later.



WHMI is enabled by default. To disable the WHMI, select **Main Menu/Configuration/HMI/Web HMI mode** via the LHMI. Reboot the IED for the change to take effect.

WHMI offers several functions.

- Programmable LEDs and event lists
- System supervision
- Parameter settings
- Measurement display
- DFR records
- Phasor diagram
- Single-line diagram

The menu tree structure on the WHMI is almost identical to the one on the LHMI.

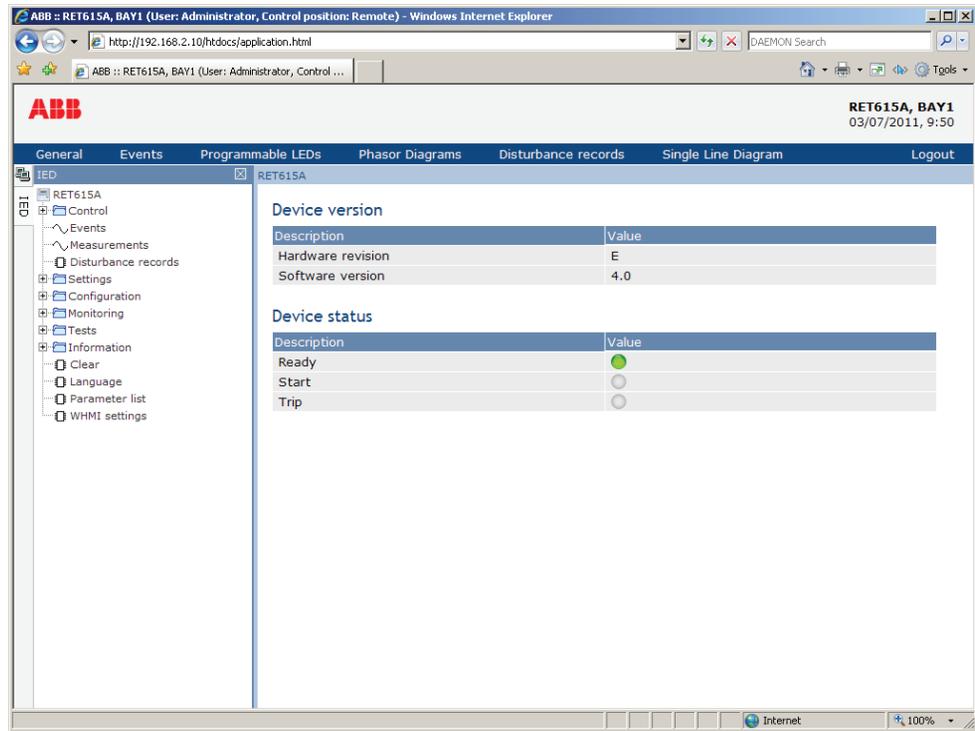


Figure 6: Example view of the WHMI

The WHMI can be accessed locally and remotely.

- Locally by connecting your laptop to the IED via the front communication port.
- Remotely over LAN/WAN.

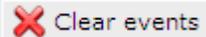
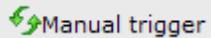
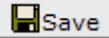
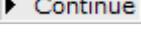
### 3.3.1 Command buttons

Command buttons can be used to edit parameters and control information via the WHMI.

Table 11: Command buttons

Name	Description
Enable Write	Enabling parameter editing.
Disable Write	Disabling parameter editing.
Write to IED	Writing parameters to the IED.
Refresh Values	Refreshing parameter values.

Table continues on next page

Name	Description
 Print	Printing out parameters.
 Commit	Committing changes to IED's non-volatile flash memory.
 Reject	Rejecting changes.
	Showing context sensitive help messages.
	Error icon.
 Clear events	Clearing events.
 Manual trigger	Triggering the DFR manually.
 Save	Saving values to CSV file format.
 Freeze	Freezing the values so that updates are not displayed.
 Continue	Receiving continuous updates to the monitoring view.
 Delete	Deleting the DFR.
 Delete all	Deleting all DFRs.
	Uploading part one of a DFR.
	Uploading part two of a DFR.

## 3.4 Authorization

The user categories have been predefined for the LHMI and the WHMI, each with different rights and default passwords.

The default passwords can be changed with Administrator user rights.



User authorization is disabled by default for LHMI and can be enabled via the LHMI or the WHMI **Main Menu/Configuration/Authorization**. WHMI always requires authentication.

**Table 12:** *Predefined user categories*

Username	User rights
VIEWER	Read only access
OPERATOR	<ul style="list-style-type: none"> <li>Selecting remote or local state with  (only locally)</li> <li>Changing setting groups</li> <li>Controlling</li> <li>Clearing indications</li> </ul>
ENGINEER	<ul style="list-style-type: none"> <li>Changing settings</li> <li>Clearing event list</li> <li>Clearing DFRs and load profile record</li> <li>Changing system settings such as IP address, serial baud rate or DFR settings</li> <li>Setting the IED to test mode</li> <li>Selecting language</li> </ul>
ADMINISTRATOR	<ul style="list-style-type: none"> <li>All listed above</li> <li>Changing password</li> <li>Factory default activation</li> </ul>



For user authorization for PCM600, see PCM600 documentation.

## 3.5 Communication

The IED supports different communication protocols: IEC 61850, Modbus<sup>®</sup> and DNP3 Level 2 - all using TCP/IP. DNP3 and Modbus also support serial communication. Operational information and controls are available through these protocols.

The IED utilizes Ethernet communication extensively for different purposes. The exact services depend on the ordered product variant and enabled functionality.

**Table 13:** *TCP and UDP ports used for different services*

Service	Port
IEC 61850	102
MODBUS	x
DNP	x
FTP	x
HTTP	x

The IEC 61850 communication implementation supports all monitoring and control functions. Additionally, parameter setting and DFR records can be accessed using the IEC 61850 protocol. Oscillographic files are available to any Ethernet-based application in the standard COMTRADE format. The IED can send and receive binary signals from other IEDs (so called horizontal communication) using the IEC61850-8-1 GOOSE profile, where the highest performance class with a total transmission time of 3 ms is supported. Further, the IED supports sending and receiving of analog values using GOOSE messaging. The IED meets the GOOSE performance requirements for tripping applications in distribution substations, as defined by the IEC 61850 standard. The IED can simultaneously report events to five different clients on the station bus.

All communication connectors, except for the front port connector, are placed on integrated optional communication modules. The IED can be connected to Ethernet-based communication systems via the RJ-45 connector (100Base-TX) or the fiber-optic LC connector (100Base-FX).

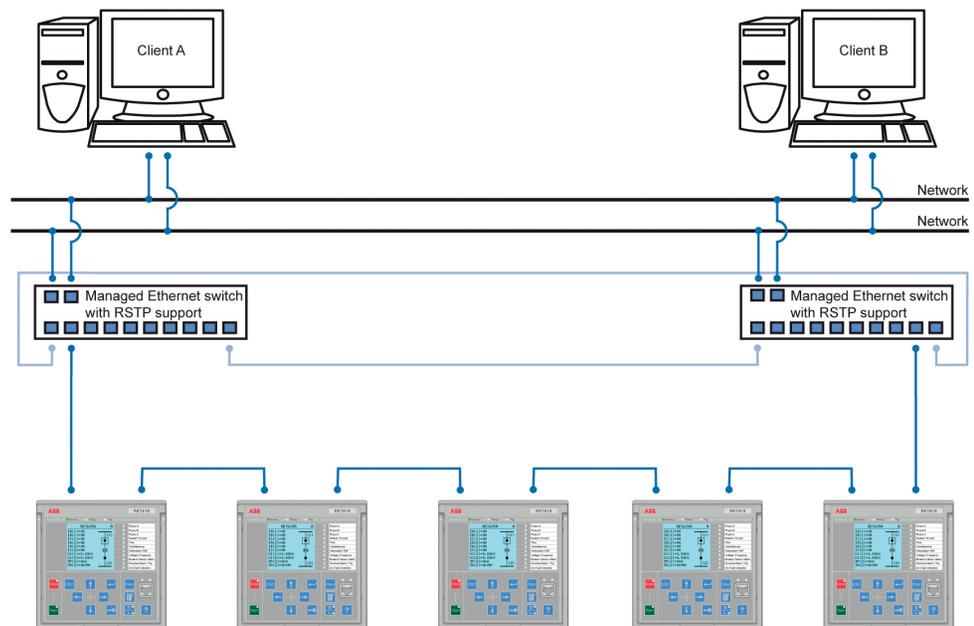


Figure 7: Self-healing Ethernet ring solution

## 3.6 PCM600 tool

Protection and Control IED Manager PCM600 offers all the necessary functionality to work throughout all stages of the IED life cycle.

- Planning
- Engineering
- Commissioning
- Operation and disturbance handling
- Functional analysis

With the individual tool components, you can perform different tasks and functions and control the whole substation. PCM600 can operate with many different topologies, depending on the customer needs.



The system settings must be set before a new PCM600 project is started. For more information, see PCM600 documentation.

### 3.6.1

## Connectivity packages

Connectivity package is a collection of software and information related to a specific protection and control terminal providing system products and tools to connect and interact with the IED. Connectivity packages are used to create configuration structures in PCM600. The latest PCM600 and connectivity packages are backward compatible with older IED versions.

Update Manager is a tool that helps in defining the right connectivity package versions for different system products and tools. Update Manager is included in products supporting the connectivity concept.

In addition to other products supporting the connectivity concept, the connectivity packages for PCM600 contain a description of IED's internal parameters and their properties (such as data format, unit, setting range, visibility and access rights) as well as software components that adapt the IED-specific interfaces to the standard interfaces of system products and tools, such as IED-specific dispatchers for tools. This means that there is a protocol-specific adaptation for the parameter setting and disturbance handling tool components, for example, DFR file uploading according to COMTRADE. The description texts can be translated into other languages as well.

### 3.6.2

## PCM600 and IED connectivity package version

- Protection and Control IED Manager PCM600 Ver. 2.3 (plus PCM600 Rollup 20110126 2.3) or later
- IED Connectivity Package REF615 ANSI Ver. 4.0 or later
- IED Connectivity Package REM615 ANSI Ver. 4.0 or later
- IED Connectivity Package RET615 ANSI Ver. 4.0 or later



Download connectivity packages from the ABB web site [http://  
www.abb.com/substationautomation](http://www.abb.com/substationautomation)

## Section 4 Using the HMI

### 4.1 Using the local HMI

You must be logged in and authorized to use the LHMI. Password authorization is disabled by default and can be enabled via the LHMI or WHMI.



To enable password authorization, select **Main menu/Configuration/Authorization/Local override**. Set the parameter to *False*.

#### 4.1.1 Logging in

1. Press  to activate the login procedure.
2. Press  or  to select the user level.

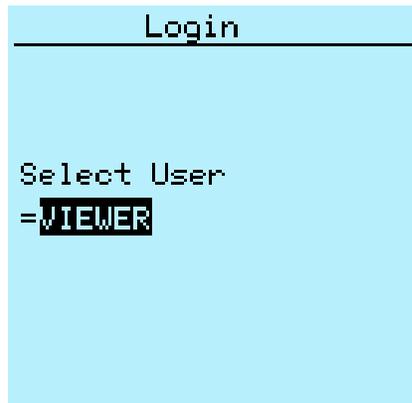


Figure 8: Selecting access level

3. Confirm the selection with .
4. Enter the password when prompted digit by digit.
  - Activate the digit to be entered with  and .
  - Enter the character with  and .

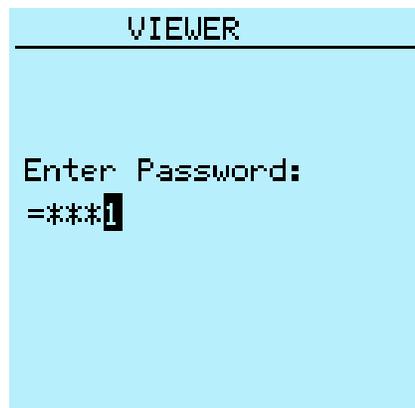


Figure 9: Entering password

5. Press  to confirm the login.
  - To cancel the procedure, press .



Figure 10: Error message indicating wrong password



The current user level is shown on the display's upper right corner in the icon area.

## 4.1.2 Logging out

The user is automatically logged out 30 seconds after the backlight timeout.

1. Press .
2. To confirm logout, select Yes and press .

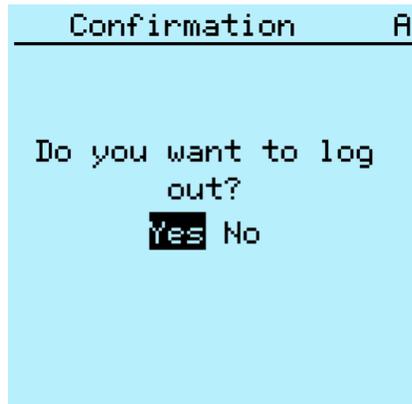


Figure 11: Logging out

- To cancel logout, press .

### 4.1.3 Turning the display backlight on

The display backlight is normally off. It turns on during the display test at power up.

- To turn on the backlight manually, press any LHMI push button.  
The backlight turns on and the panel is ready for further operations.

If the panel has not been used for a predefined timeout period, the backlight is switched off. The user is logged out from the current user level 30 seconds after the display backlight has turned off.

The display returns to the default view and all unconfirmed operations such as parameter editing and breaker selection are cancelled.



Change the backlight timeout period in **Main menu/Configuration/HMI/Backlight timeout.**

### 4.1.4 Selecting local or remote use

The control position of the IED can be changed with the R/L button. In local position primary equipment, such as circuit breakers or disconnectors, can be controlled via the

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LHMI. In remote position, control operations are possible only from a higher level, that is from a control center.

- Press  for two seconds.
  - When the L LED is lit, local control is enabled and remote control disabled.
  - When the R LED is lit, remote control is enabled and local control disabled.
  - When neither of the LEDs is lit, both control positions are disabled.



The control position cannot be simultaneously local and remote but it can be disabled when neither of the positions is active.



To control the IED, log in with the appropriate user rights.

## 4.1.5

### Identifying the device

The IED information includes detailed information about the device, such as revision and serial number.

The IED information is shown on the display for a few seconds when the device starts up. The same information is also found in the IED menu.

1. Select **Main menu/Information**.
2. Select a submenu with  and .

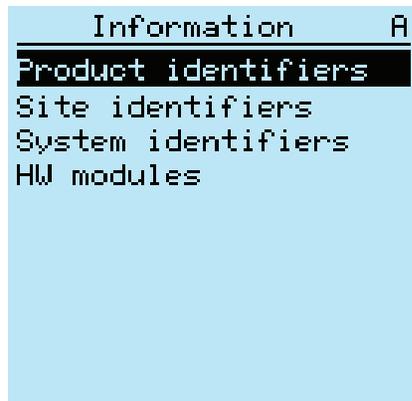


Figure 12: Selecting a submenu

3. Enter the submenu with .
4. Browse the information with  and .



Figure 13: IED information

### 4.1.6 Adjusting the display contrast

Adjust the display contrast anywhere in the menu structure to obtain optimal readability.

- To increase the contrast, press simultaneously  and .
- To decrease the contrast, press simultaneously  and .

The selected contrast value is stored in the non-volatile memory if you are logged in and authorized to control the IED. After an auxiliary power failure, the contrast is restored.

## 4.1.7 Changing the local HMI language

1. Select **Main menu/Language** and press .
2. Change the language using  or .
3. Press  to confirm the selection.
4. Commit the changes.



Figure 14: Changing the LHMI language



To change the language using a shortcut, press  and  simultaneously anywhere in the menu.

## 4.1.8 Changing display symbols

To switch between the display symbols IEC 61850, IEC 60617 and ANSI:

1. Select **Main Menu/Configuration/HMI/FB naming convention** and press .
2. Change the display symbols with  or .
3. Press  to confirm the selection.



The IED has to be rebooted if the WHMI display symbols are changed. With the LHMI, the change takes effect immediately.

## 4.1.9 Navigating in the menu

Navigate the menus and change the display views on the screen with the keypad.

- To navigate between main menu, measurements and single-line diagram, press .
- To move up or down in a menu, press  or .
- To move downwards in the menu tree, press .
- To move upwards in the menu tree, press .
- To enter setting mode, press .
- To leave setting mode without saving, press .

### 4.1.9.1 Menu structure

The Main menu contains main groups which are divided further into more detailed submenus.

- Events
- Measurements
- DFR records
- Settings
- Configuration
- Monitoring
- Tests
- Information
- Clear
- Language
- Control

### 4.1.9.2 Scrolling the display

If a menu contains more rows than the display can show at a time, a scroll bar is displayed on the right.

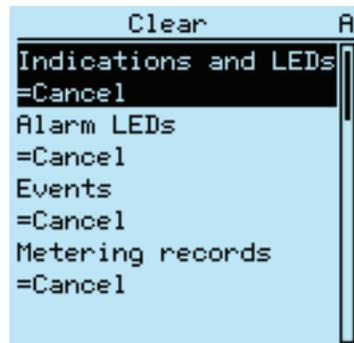


Figure 15: Scroll bar on the right

- To scroll the view upwards, press .
- To scroll the view downwards, press .
- To jump from the last row to the first row, press  again.
  - Press  to jump from the first row to the last row.
- To scroll parameter names and values that do not fit the screen, press . Press  once to return to the beginning.

### 4.1.9.3

#### Changing the default view

The default view of the display is **Measurements** unless set otherwise.

1. Select **Main menu/Configuration/HMI/Default view** and press .
2. Change the default view with  or .
3. Press  to confirm the selection.

### 4.1.10

#### Viewing single-line diagram

The single-line diagram is created with PCM600. The single-line diagram is active only when the large screen is used.

- Select **Main menu/Control/SLD** to view the single-line diagram or press  to navigate between main menu, measurement and single-line diagram.

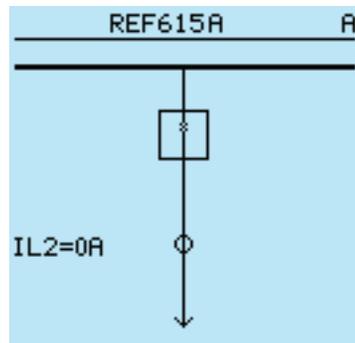


Figure 16: Single-line diagram with one breaker and IEC symbols

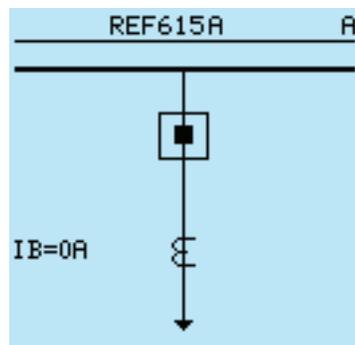


Figure 17: Single-line diagram with one breaker and ANSI symbols



Select the single-line diagram for the default view in **Main menu/Configuration/HMI/Default view**.

#### 4.1.10.1

#### Changing single-line diagram symbol formats

1. Select **Main menu/Configuration/HMI/SLD symbol format** and press .
2. Change symbol format with  or .
3. Press  to confirm the selection.

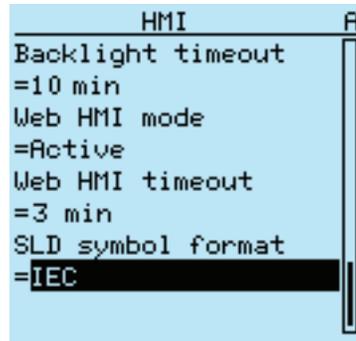


Figure 18: Selecting IEC as single-line diagram symbol format

### 4.1.11

## Browsing setting values

1. Select **Main menu/Settings/Settings** and press .
2. Select the setting group to be viewed with  or .



Figure 19: Selecting a setting group

3. Press  to confirm selection.
4. To browse the settings, scroll the list with  and  and to select a submenu press . To move back to the list, press .

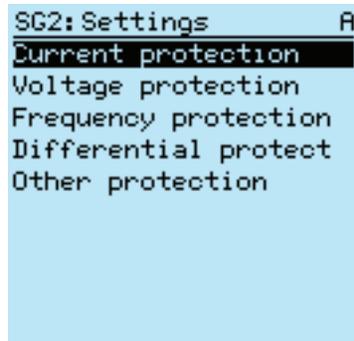


Figure 20: Example of submenus in the Settings menu

## 4.1.12 Editing values

- To edit values, log in with the appropriate user rights.

### 4.1.12.1 Editing numerical values

1. Select **Main menu/Settings** and then a setting.  
The last digit of the value is active.
  - When the symbol in front of the value is ↑, the active value can only be increased.
  - When the symbol is ↓, the active value can only be decreased.
  - When the symbol in front of the value is ⇅, the active value can either be increased or decreased.



Figure 21: Last digit is active and it can only be increased

2. Press  to increase or  to decrease the value of an active digit.

One press increases or decreases the value by a certain step. For integer values, the change is 1, 10, 100 or 1000 (...) depending on the active digit. For decimal values, the change can be fractions 0.1, 0.01, 0.001 (...) depending on the active digit.



For parameters with defined steps, digits smaller than the step value cannot be edited.

3. Press  or  to move the cursor to another digit.
4. To select the minimum or maximum value, select the arrow symbol in front of the value.
  - To set the value to the maximum, press .
  - To set the value to the minimum, press .



Figure 22: Arrow symbol is active, the value is set to the maximum

After pressing , the previous value can be restored by pressing  once, and vice versa. Another press of  or  sets the value to the lower or higher limit. The symbol in front of the value is  $\updownarrow$ , when the previous value is shown.



Figure 23: Restoring the previous value

### 4.1.12.2 Editing string values

1. Activate the setting mode and select a setting.  
When editing string values, the cursor moves to the first character.
2. Press  or  to change the value of an active character.  
One press changes the value by one step.
3. Press  or  to move the cursor to another character.
  - To insert characters or space, press simultaneously  and .
  - To delete characters, press simultaneously  and .

### 4.1.12.3 Editing enumerated values

1. Activate the setting mode and select a setting.  
When editing an enumerated value, the selected value is shown inverted.
2. Press  or  to change the value of an active enumerated value.  
One press changes the enumerated value by one step in the parameter specific order.

### 4.1.13 Committing settings

Editable values are stored either in RAM or in non-volatile flash memory. Values stored in flash memory are in effect also after reboot.

Some parameters have an edit-copy. If editing is cancelled, the values with an edit-copy are immediately restored to the original value. The values without an edit-copy, such as string values, are restored to the original value only after a reboot even though the edited value is not stored in the flash memory.

1. Press  to confirm any changes.
2. Press  to move upwards in the menu tree or  to enter the Main Menu.
3. To save the changes in non-volatile memory, select Yes and press .

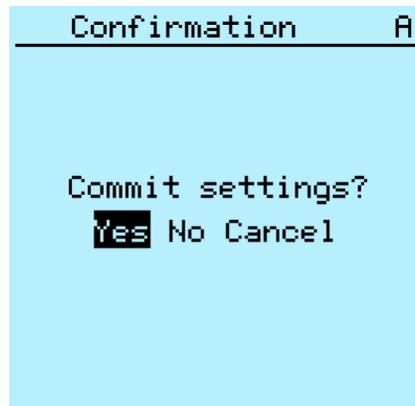


Figure 24: Confirming settings

- To exit without saving changes, select **No** and press .
- If the parameter has an edit-copy, the original parameter value is restored.
- If the parameter does not have an edit-copy, the edited parameter value remains visible until you reboot the IED. However, the edited value is not stored in non-volatile memory and the reboot restores the original value.
- To cancel saving settings, select **Cancel** and press .



After certain parameters are changed, the IED has to be restarted.

#### 4.1.14

### Clearing and acknowledging

The Clear button is used to reset, acknowledge or clear all messages and indications, including LEDs and latched outputs as well as registers and recordings. Press the Clear button to activate a selection menu, and select the wanted clearance or reset function. Events and alarms assigned to programmable LEDs are cleared with the Clear button as well.

1. Press  to activate the Clear view.

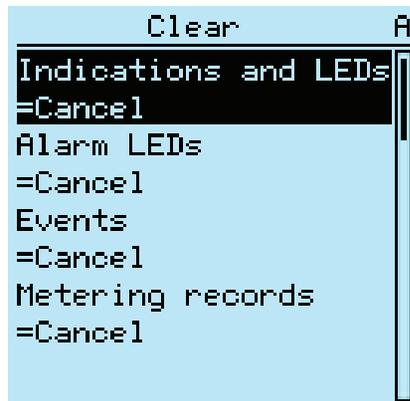


Figure 25: Clear view

2. Select the item to be cleared with  or .
3. Press , change the value with  or  and press  again.  
The item is now cleared.
4. Repeat steps 2 and 3 to clear other items.



Use the  button as a shortcut for clearing. The first three-second press clears the indications. The second three-second press clears the programmable LEDs.

### 4.1.15 Using the local HMI help

1. Press  to open the help view.
2. Scroll the text with  or  if the help text exceeds the display area.
3. To close the help, press .

## 4.2 Using the Web HMI

WHMI is enabled by default. Log in with the proper user rights to use the WHMI.

1. To enable the WHMI, select **Main menu/Configuration/HMI/Web HMI mode** via the LHMI.
2. Reboot the IED for the change to take effect.

## 4.2.1 Logging in

1. Enter the username with capital letters.
2. Enter the password.
3. Click **OK**.



*Figure 26: Entering username and password to use the WHMI*

## 4.2.2 Logging out

The user is logged out after session timeout. The timeout can be set in **Main menu/Configuration/HMI/Web HMI timeout**.

- To log out manually, click **Logout** on the menu bar.

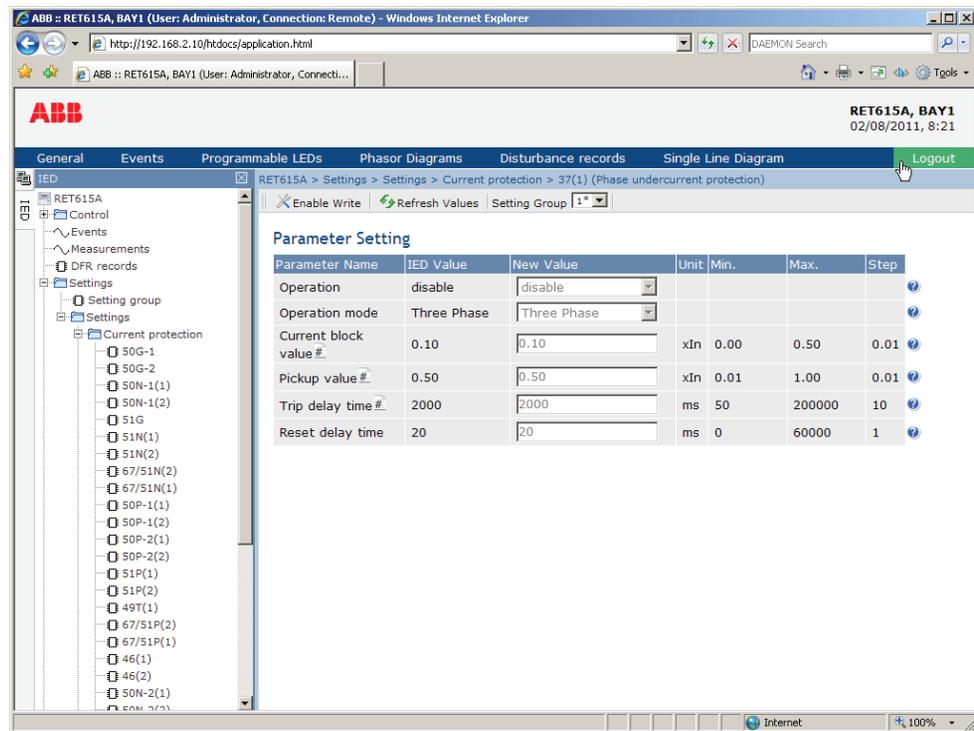


Figure 27: WHMI logout

## 4.2.3 Identifying the device

The IED information includes detailed information about the device, such as revision and serial number.

1. Click **Information** in the WHMI menu structure.
2. Click a submenu to see the data.

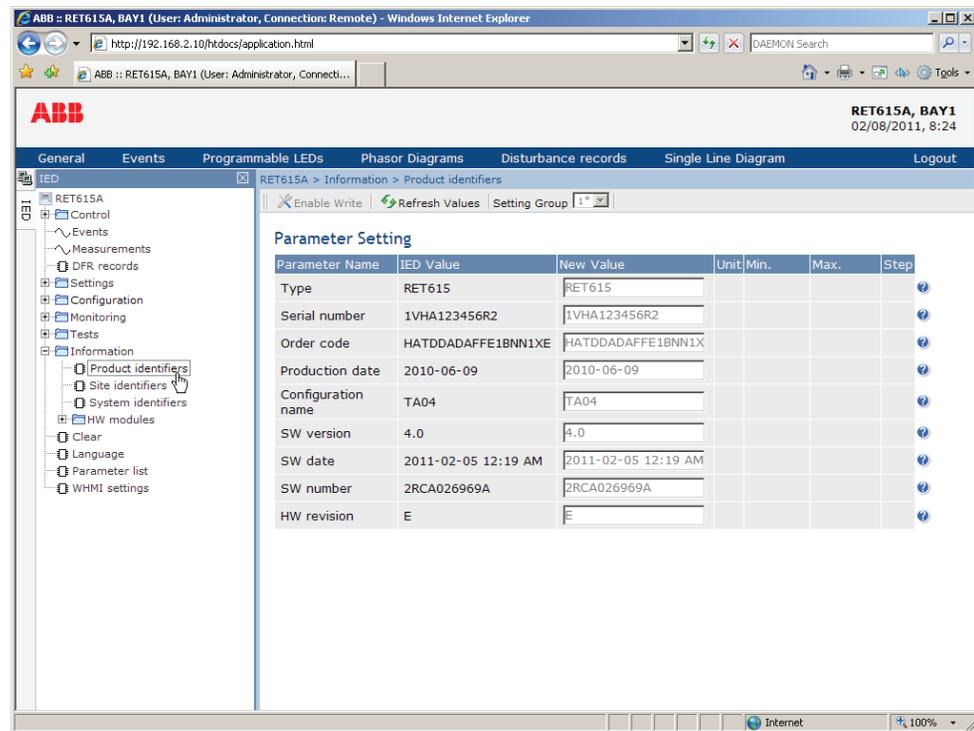


Figure 28: Device information

## 4.2.4 Navigating in the menu

The menu tree structure on the WHMI is almost identical to the one on the LHMI. Use the menu bar to access different views.

- The **General** view shows the IED version and status.
- The **Events** view contains a list of events produced by the application configuration.
- The **Programmable LEDs** view shows the status of programmable LEDs.
- The **Phasor diagrams** view shows phasor diagrams.
- The **DFR records** view shows the list of disturbance records.
- The **Single Line Diagram** view shows the single-line diagram.
- **Logout** ends the session.

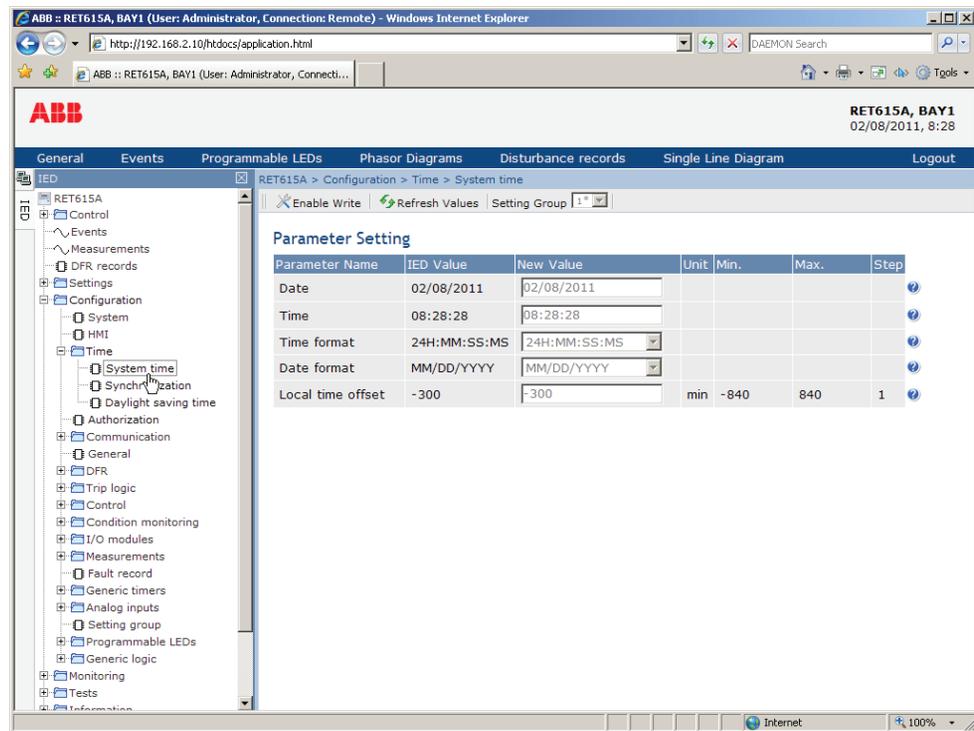


Figure 29: Navigating in the WHMI menus

#### 4.2.4.1

### Menu structure

The Main menu contains main groups which are divided further into more detailed submenus.

- Events
- Measurements
- DFR records
- Settings
- Configuration
- Monitoring
- Tests
- Information
- Clear
- Language
- Control
- Parameter list
- WHMI settings

## 4.2.5 Selecting single-line diagram

The single-line diagram is active only when the large screen is used.

- Select **Control/SLD** in the main menu or click **Single Line Diagram** in the menu bar to view the single-line diagram.

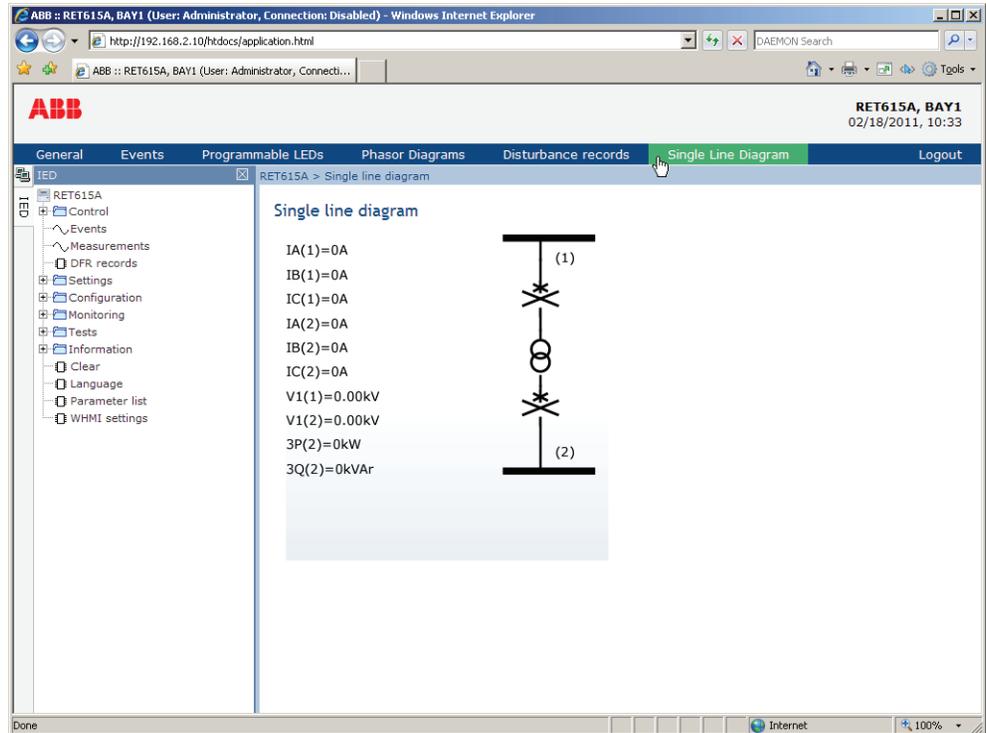


Figure 30: Viewing the single-line diagram with IEC symbols

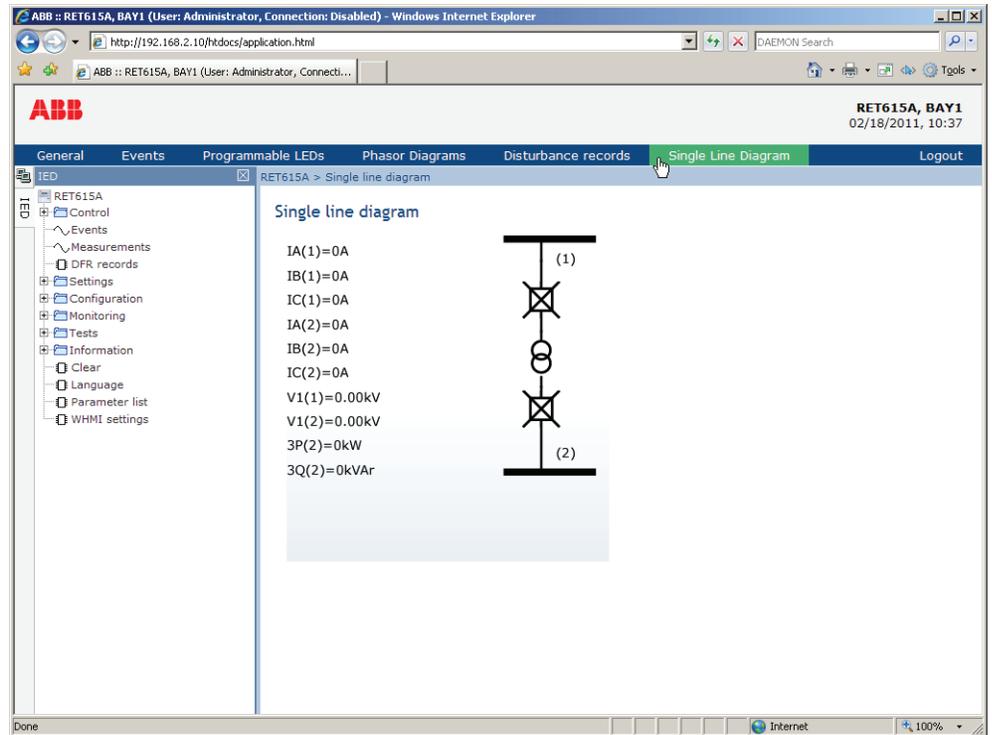


Figure 31: Viewing the single-line diagram with ANSI symbols

## 4.2.6 Showing all parameters

1. Click **Parameter list** in the main menu.

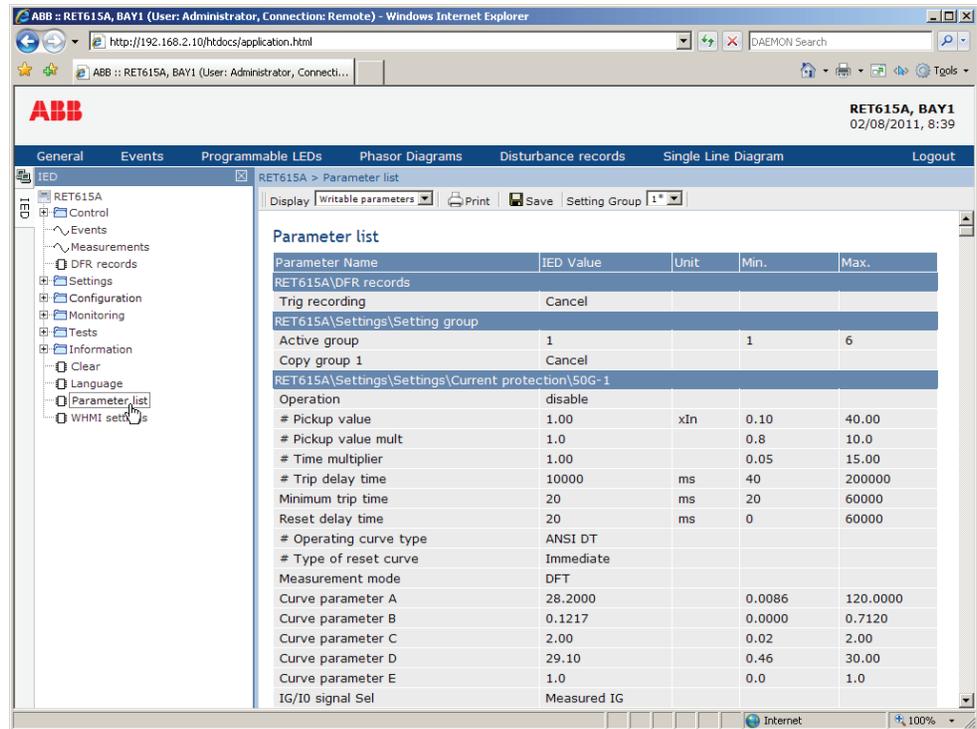


Figure 32: Show all parameters

2. Click **Print** to print out all parameters on paper.
3. Click **Save** to save all parameters in CSV file format.

## 4.2.7

### Editing values

1. Click the menu in the WHMI tree.
2. Click the submenu to see function blocks.
3. Click a function block to see the setting values.
4. Click **Enable Write**.



Some parameters, for example the IED test mode, cannot be set via the WHMI.

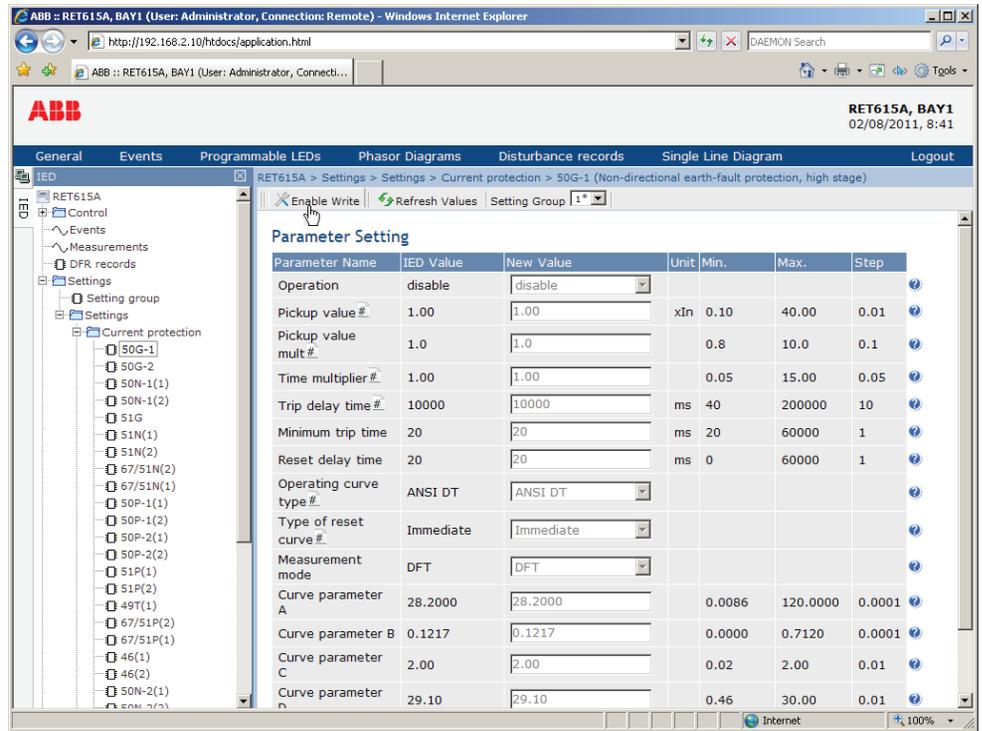


Figure 33: Enable writing to edit a value

The selected setting group is shown in the Setting Group drop-down list. The active setting group is indicated with an asterisk \*.

5. Edit the value.
  - The minimum and maximum values for a parameter are shown in the Min. and Max. columns.
  - Setting group values are indicated with #.

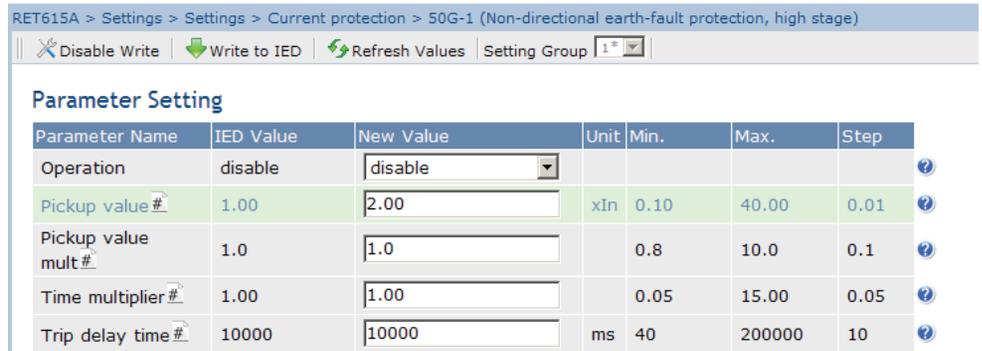


Figure 34: Editing a value

- If the entered value is within the accepted value range, the selection is highlighted in green. If the value is out of range, the row is highlighted in red and a warning dialog box is displayed. **Write to IED** button is disabled.

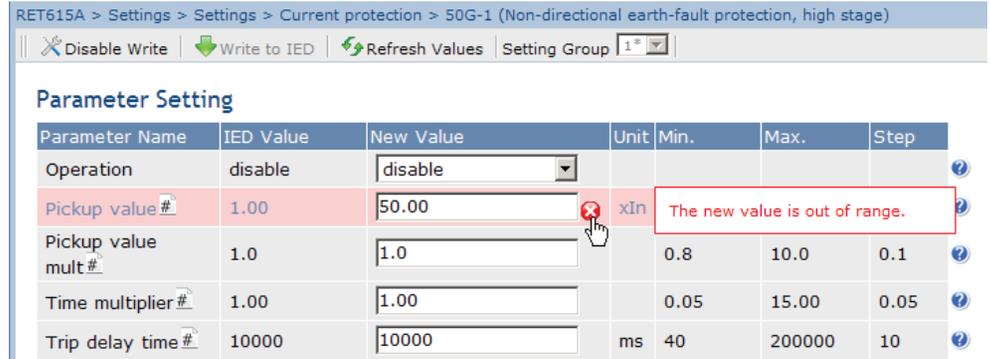


Figure 35: Warning indicating that the entered value is incorrect

- If writing values fails, a warning dialog box is displayed.

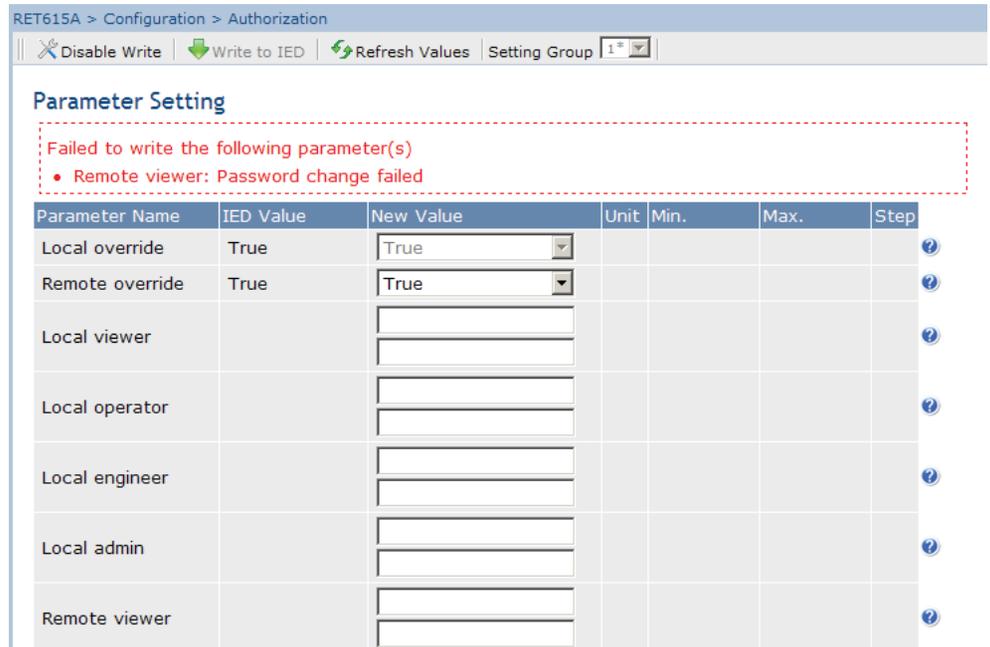


Figure 36: Warning indicating that the values were not written to the IED



If writing is enabled accidentally, click **Disable Write**. **Disable Write** cannot be selected, when a value has already been written to the IED. After clicking **Write to IED**, click either **Commit** or **Reject**.

## 4.2.8 Committing settings

Editable values are stored either in RAM or in non-volatile flash memory. Values stored in flash memory are in effect also after reboot.

Some parameters have an edit-copy. If editing is cancelled, the values with an edit-copy are immediately restored to the original value. The values without an edit-copy, such as string values, are restored to the original value only after a reboot even though the edited value is not stored in the flash memory.

1. Click **Write to IED** after editing parameter values to put the values into IED's database for use.

Parameter Name	IED Value	New Value	Unit	Min.	Max.	Step
Operation	disable	disable				
Pickup value #	1.00	2.00	xIn	0.10	40.00	0.01
Pickup value mult #	1.0	1.0		0.8	10.0	0.1
Time multiplier #	1.00	1.00		0.05	15.00	0.05
Trip delay time #	10000	10000	ms	40	200000	10

Figure 37: Writing values to IED

The values are not stored to the flash memory.

2. Click **Commit** to write the values to the flash memory.
  - Click **Reject** to cancel saving settings.
    - If the parameter has an edit-copy, the original parameter value is restored.
    - If the parameter does not have an edit-copy, the edited parameter value remains visible until you reboot the IED. However, the edited value is not stored in non-volatile memory and thus the reboot restores the original value.

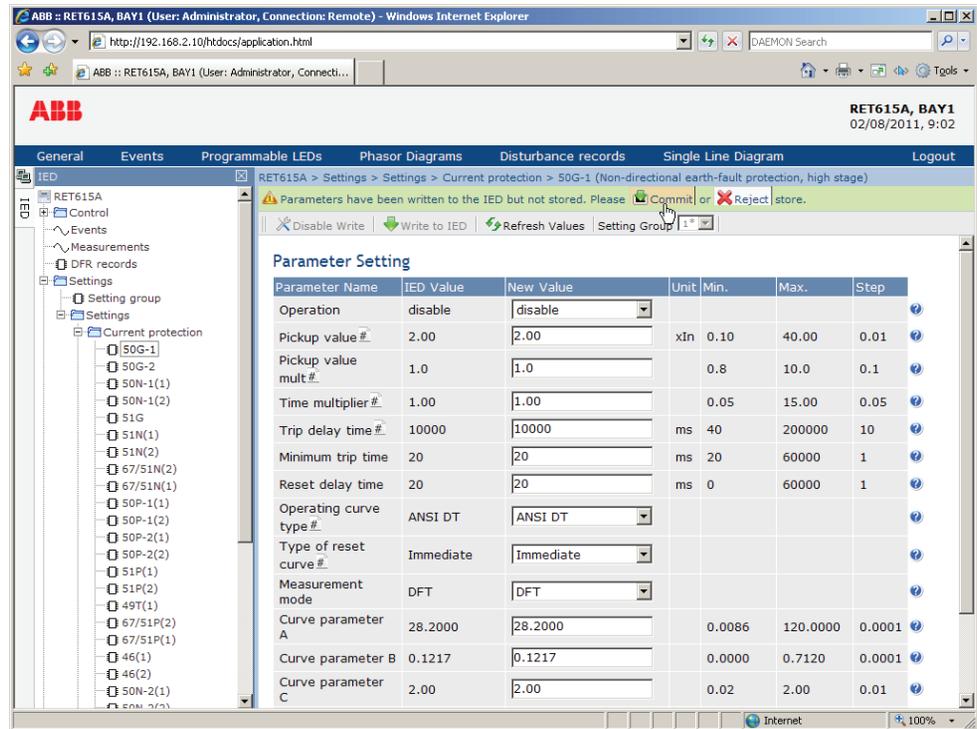


Figure 38: Committing changes



Committing values will take a few seconds.



If the values are not committed, they are not taken into use and they are lost after a reboot.

## 4.2.9

### Clearing and acknowledging

Reset, acknowledge or clear all messages and indications, including LEDs and latched outputs as well as registers and recordings, in the Clear menu.

1. Click the **Clear** menu.

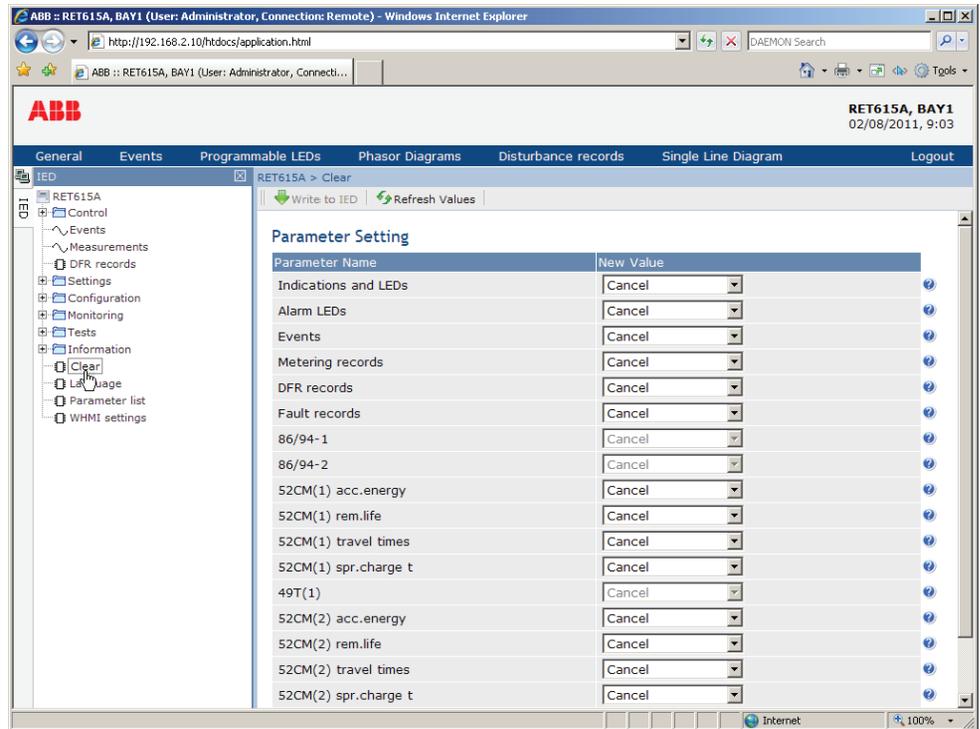


Figure 39: Selecting clear menu

2. In the **New Value** box, click **Clear** to select the item to be cleared.
3. Click **Write to IED**.

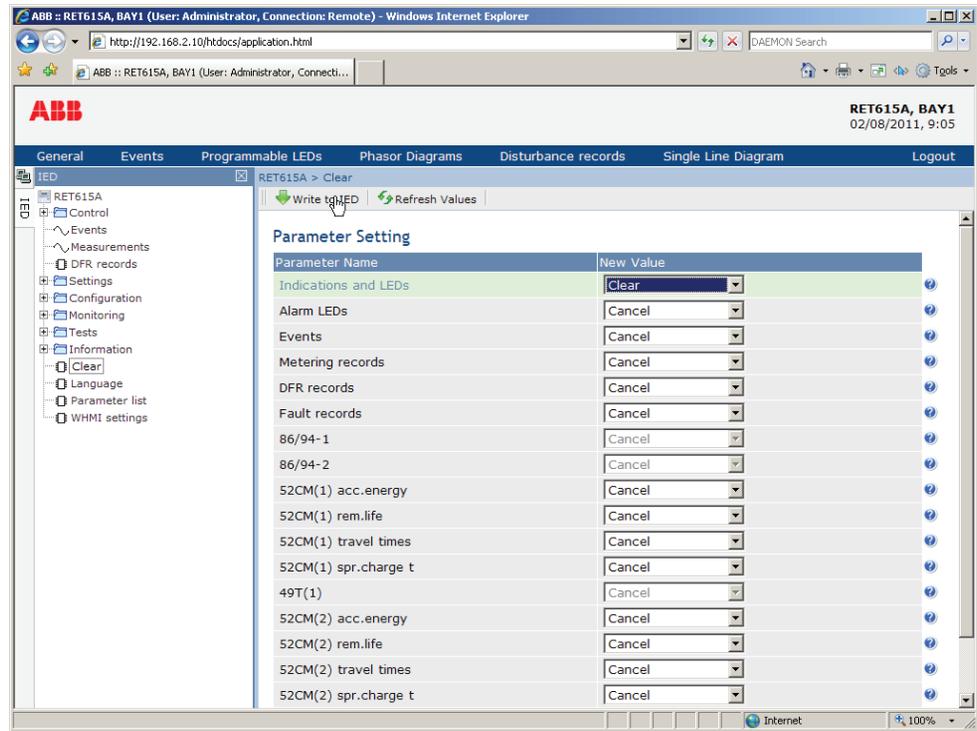


Figure 40: Clearing indications and LEDs

#### 4.2.10

### Selecting the programmable LEDs view

The programmable LEDs view shows the status of the programmable LEDs. These are the same LEDs that are located on the upper right side of the LHMI panel.

- Click **Programmable LEDs** in the menu bar.

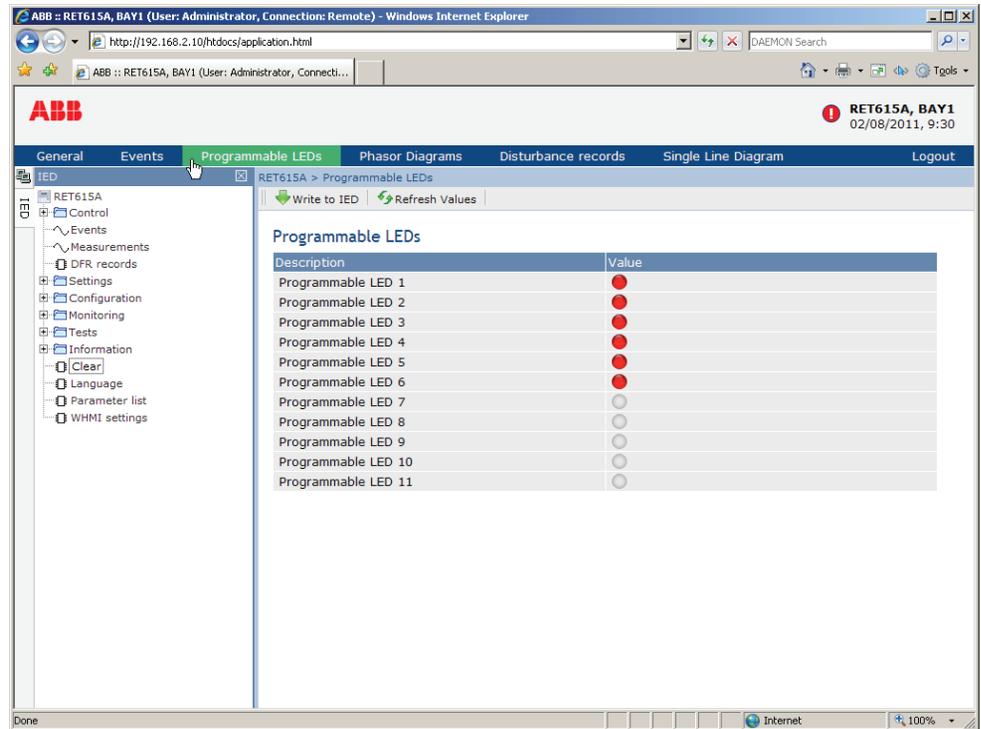


Figure 41: Monitoring alarms

## 4.2.11 Selecting the event view

The event view contains a list of events produced by the application configuration. When event page is opened it displays up to 100 latest events at one time. The event list is updated automatically.

1. Click **Events** in the menu bar.

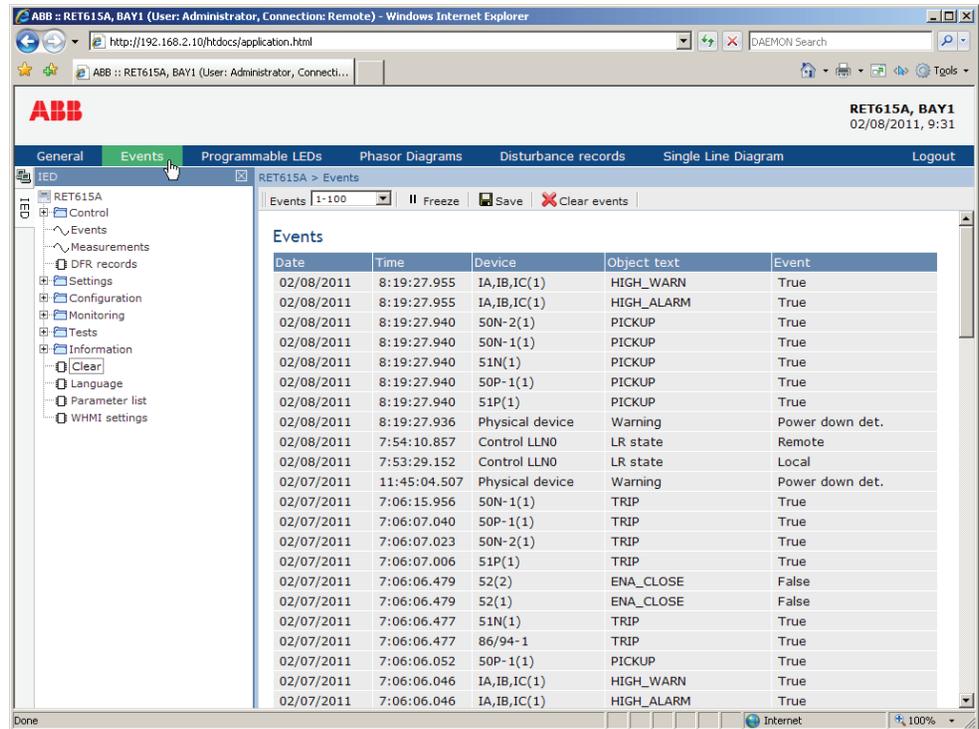


Figure 42: Monitoring events

2. Click **Freeze** to stop updating the event list.
3. Select a page from the drop-down menu to view older documents.

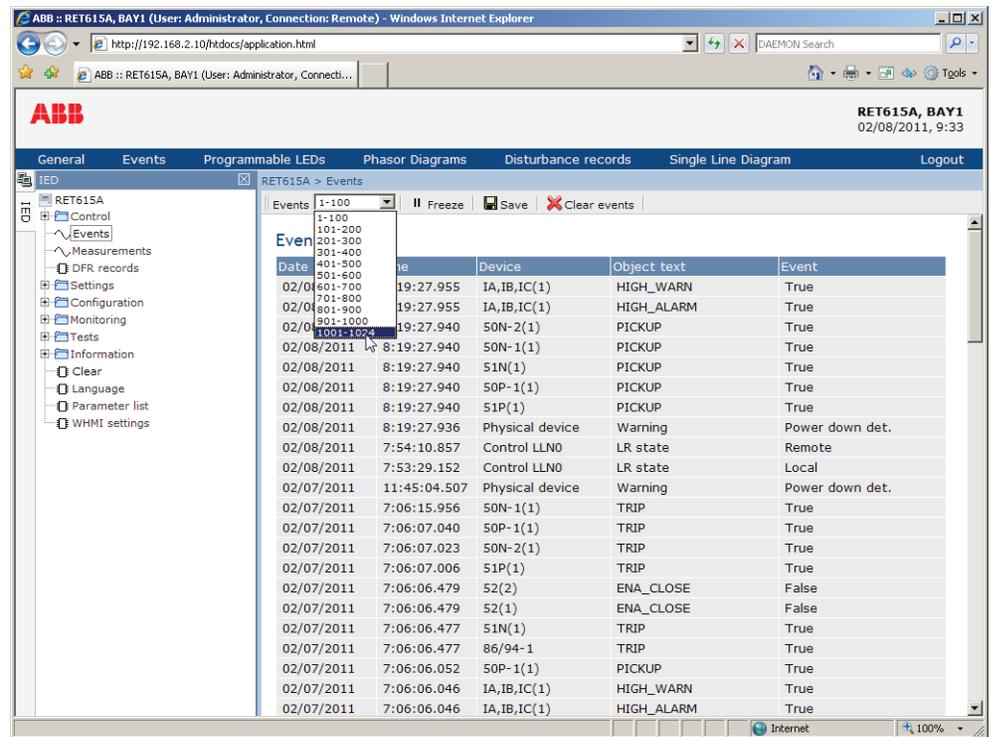


Figure 43: Events view

4. Click **Save** to save the events in CSV file format.  
The CSV file can be opened with a spreadsheet program such as OpenOffice.org Calc or Microsoft Excel.
5. Click **Clear events** to clear all events from the IED.

## 4.2.12

### Selecting the DFR record view

DFR records are listed in the DFR records view.

- Click **DFR records** on the menu bar.

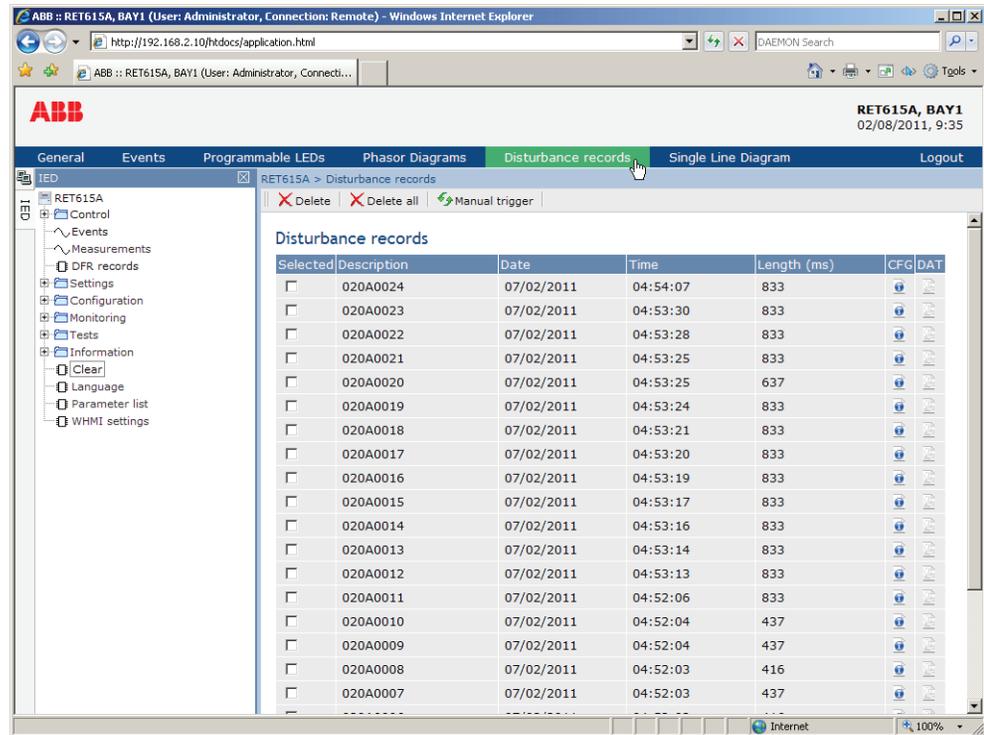


Figure 44: DFR record view

#### 4.2.12.1

### Uploading DFR records

1. Click **DFR records** on the menu bar.
2. To upload a DFR record, click the icons in the CFG and DAT columns of the record.

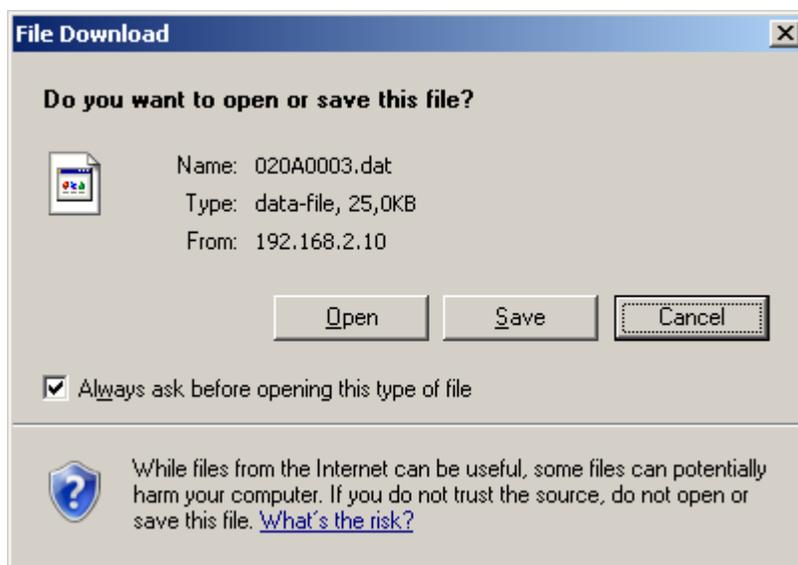


Figure 45: Uploading a DFR record

3. Save both the files in the same folder on your computer.
4. Open the DFR record files with a suitable program.

#### 4.2.12.2

#### Triggering the DFR recorder manually

1. Click **DFR records** on the menu bar.
2. Click **Manual trigger**.

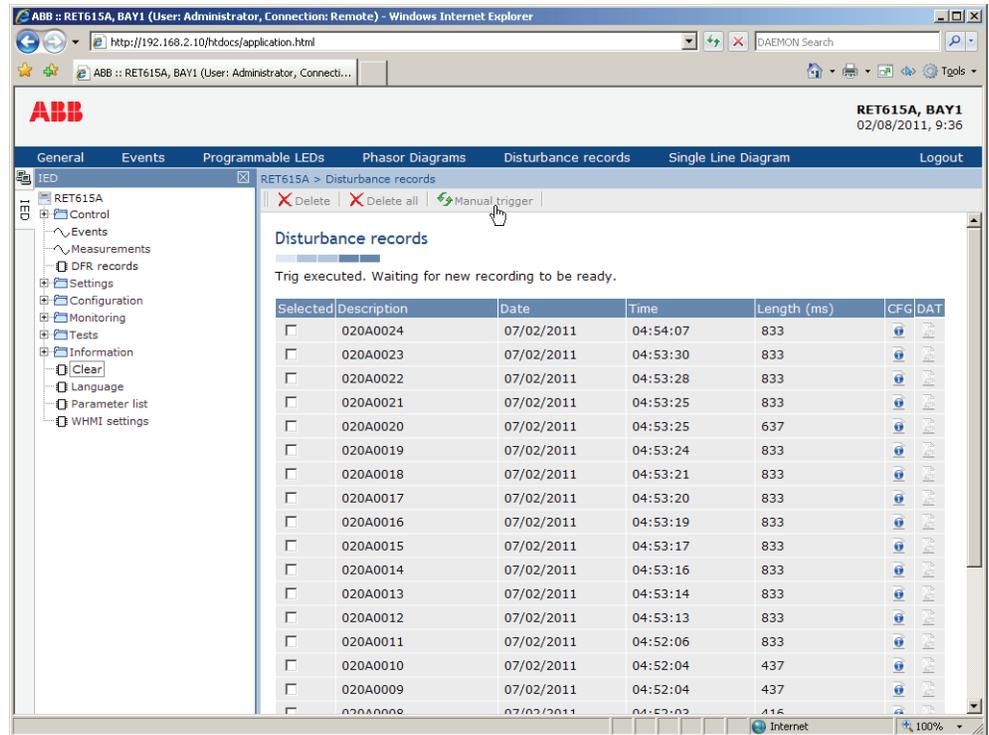


Figure 46: Manual triggering

### 4.2.12.3

### Deleting DFR records

1. Click **DFR records** on the menu bar.
2. Delete records.
  - Click **Delete all** to delete all records.
  - Select one or more recordings and click **Delete** to delete selected records.

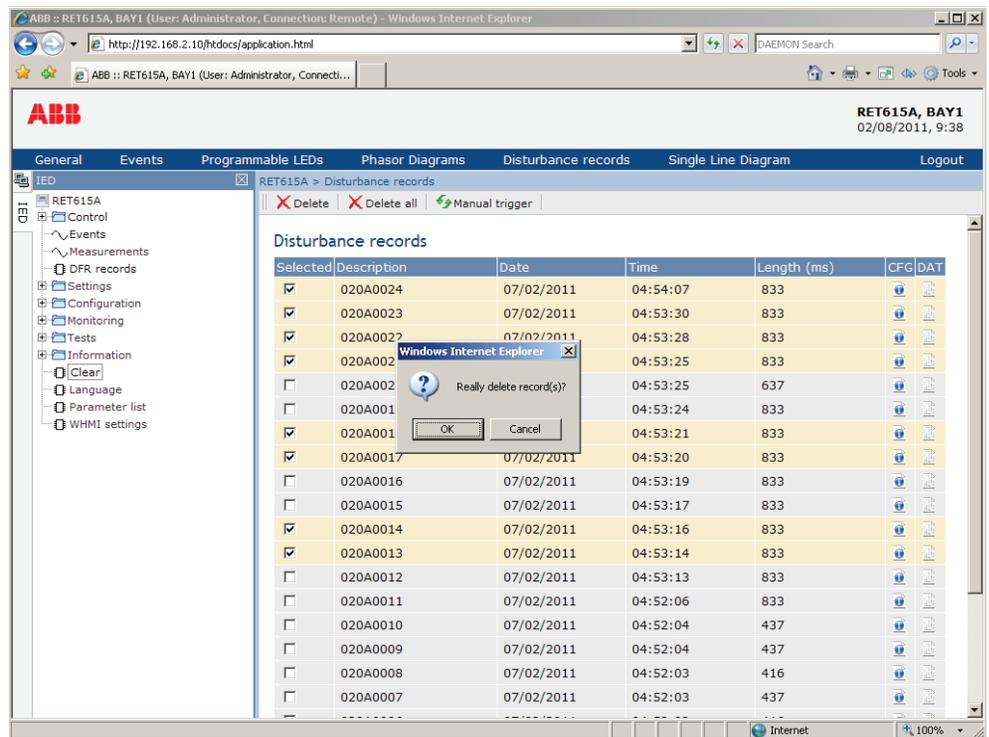


Figure 47: Deleting DFR records

3. Click **OK** to confirm or **Cancel** to cancel the deletion.

## 4.2.13

### Selecting phasor diagrams

1. Click **Phasor diagrams**.

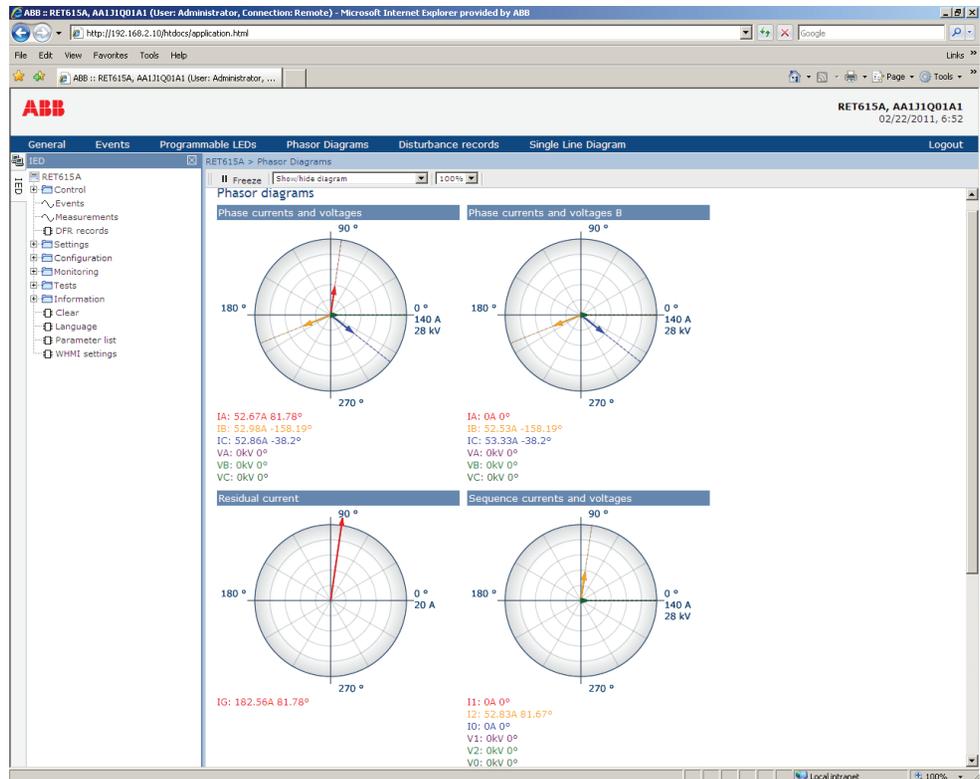


Figure 48: Monitoring phasors

2. Toggle the diagram visibility by selecting it from the drop-down menu.

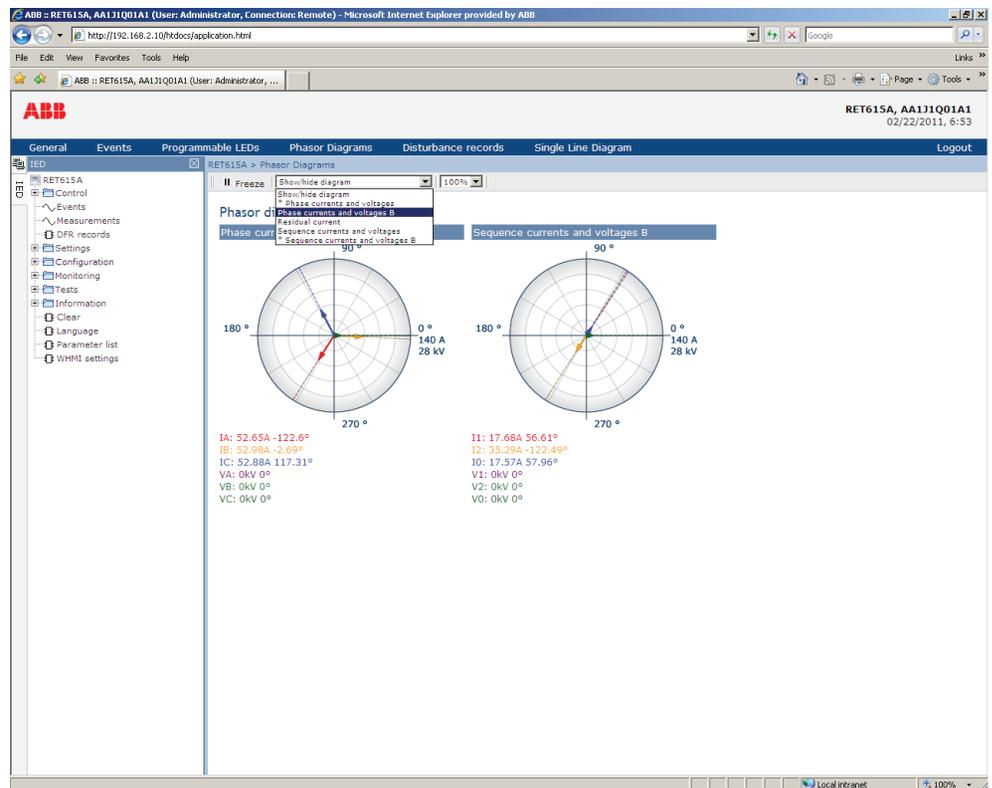


Figure 49: Toggling the diagram visibility

Visible diagrams are indicated with an asterisk \*.

3. Change the size of the diagram by changing the zoom value.

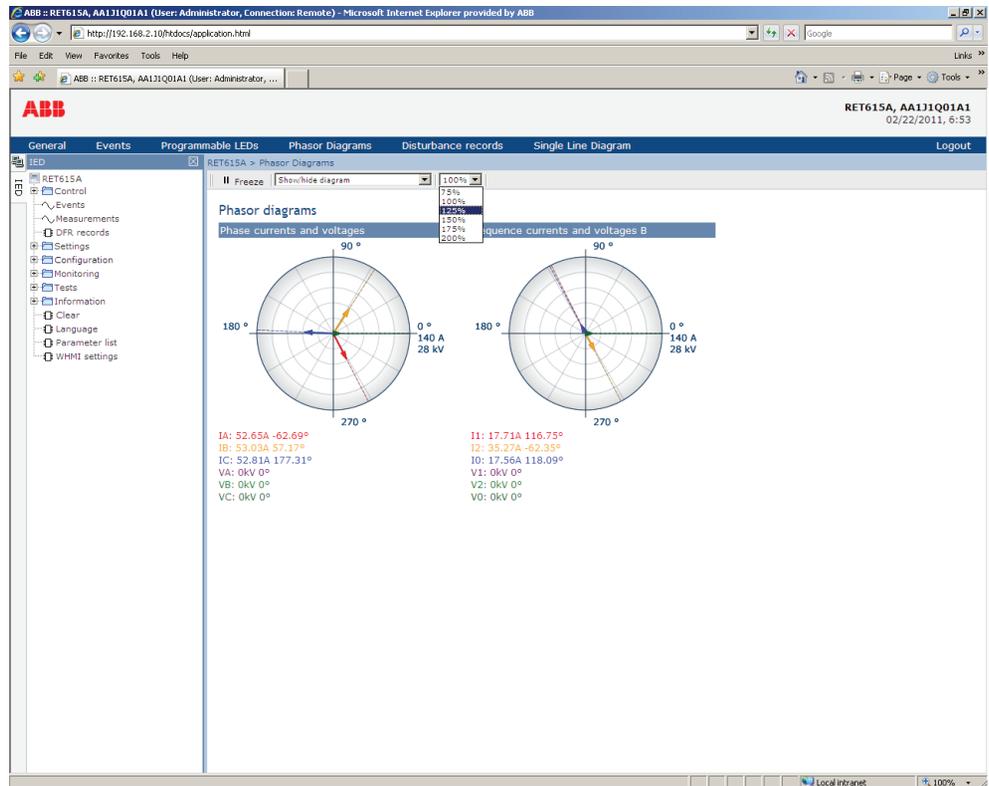


Figure 50: Zooming the diagram

- Click **Freeze** to stop updating the phasor diagram. No updates are displayed in the diagram.

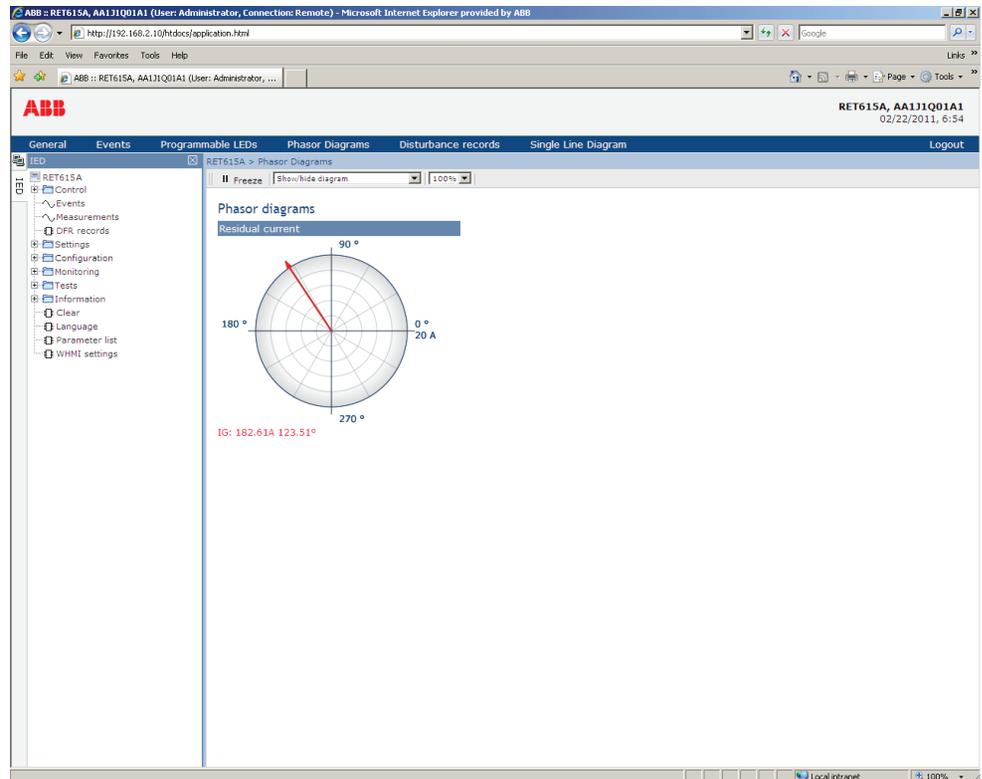


Figure 51: The arrow extends outside the circle if the current value is too high



Install an SVG plugin to view the phasor diagrams.

## 4.2.14

### Selecting fault records

- Select from the main menu **Monitoring/Recorded data/Fault record** to view a list of all available fault records.  
The newest fault record is first on the list. The fault records list is updated automatically.

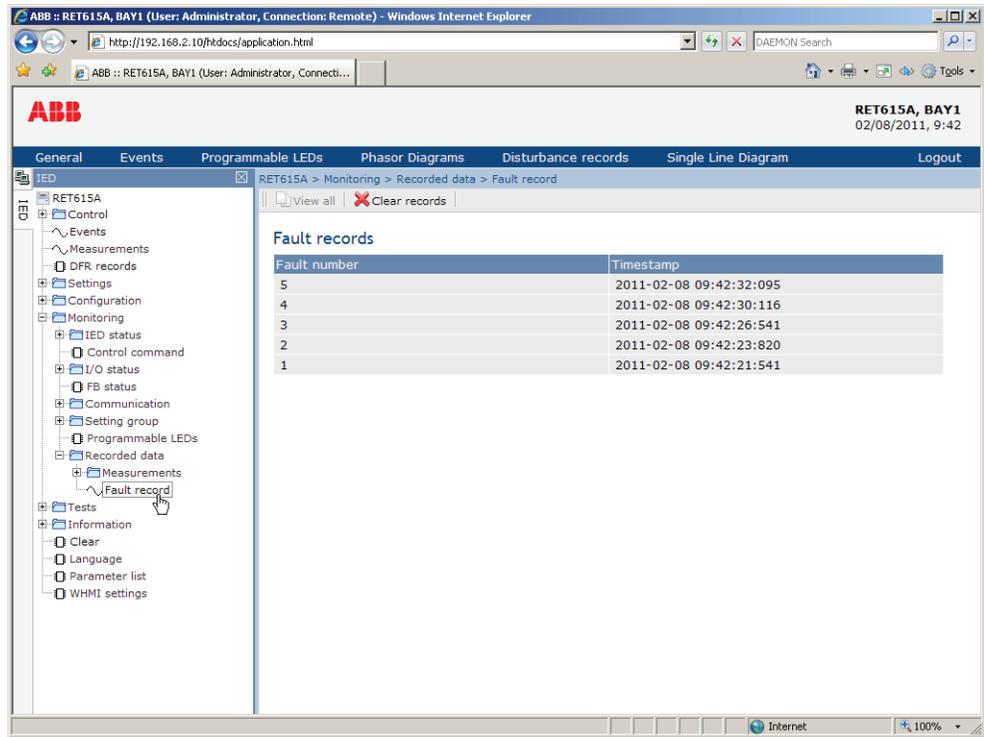


Figure 52: Fault records

The screenshot shows the ABB HMI web interface for RET615A, BAY1. The browser address bar shows the URL `http://192.168.2.10/htdocs/application.html`. The interface has a navigation menu with tabs for General, Events, Programmable LEDs, Phasor Diagrams, Disturbance records, Single Line Diagram, and Logout. The left sidebar shows a tree view with categories like IED, RET615A, Control, Events, Measurements, DFR records, Settings, Configuration, Monitoring, IED status, Control command, I/O status, FB status, Communication, Setting group, Programmable LEDs, Recorded data, Measurements, Fault record, Tests, Information, Clear, Language, Parameter list, and WHMI settings. The main content area displays the 'Fault records' table.

Parameter Name	IED Value	Unit	Min.	Max.
Fault number	1		0	999999
Time and date	2011-02-08 09:42:21:541			
Protection	51N(1)			
Pickup duration	0.00	%	0.00	100.00
Operate time	0.004	s	0.000	1000000.000
Setting group	1		1	6
Max diff current IA	0.000	pu	0.000	80.000
Max diff current IB	0.000	pu	0.000	80.000
Max diff current IC	0.000	pu	0.000	80.000
Diff current IA	0.000	pu	0.000	80.000
Diff current IB	0.000	pu	0.000	80.000
Diff current IC	0.000	pu	0.000	80.000
Max bias current IA	0.000	pu	0.000	50.000
Max bias current IB	0.000	pu	0.000	50.000
Max bias current IC	0.000	pu	0.000	50.000
Bias current IA	0.000	pu	0.000	50.000
Bias current IB	0.000	pu	0.000	50.000
Bias current IC	0.000	pu	0.000	50.000
Diff current IG	0.000	pu	0.000	80.000
Bias current IG	0.000	pu	0.000	50.000
Max current IA	0.250	xIn	0.000	50.000
Max current IB	0.251	xIn	0.000	50.000

Figure 53: Fault record parameters

## 4.2.15 Using the Web HMI help

The context sensitive WHMI help provides information, for example, of a single parameter.

- Move the mouse over the  to display the help dialog box.

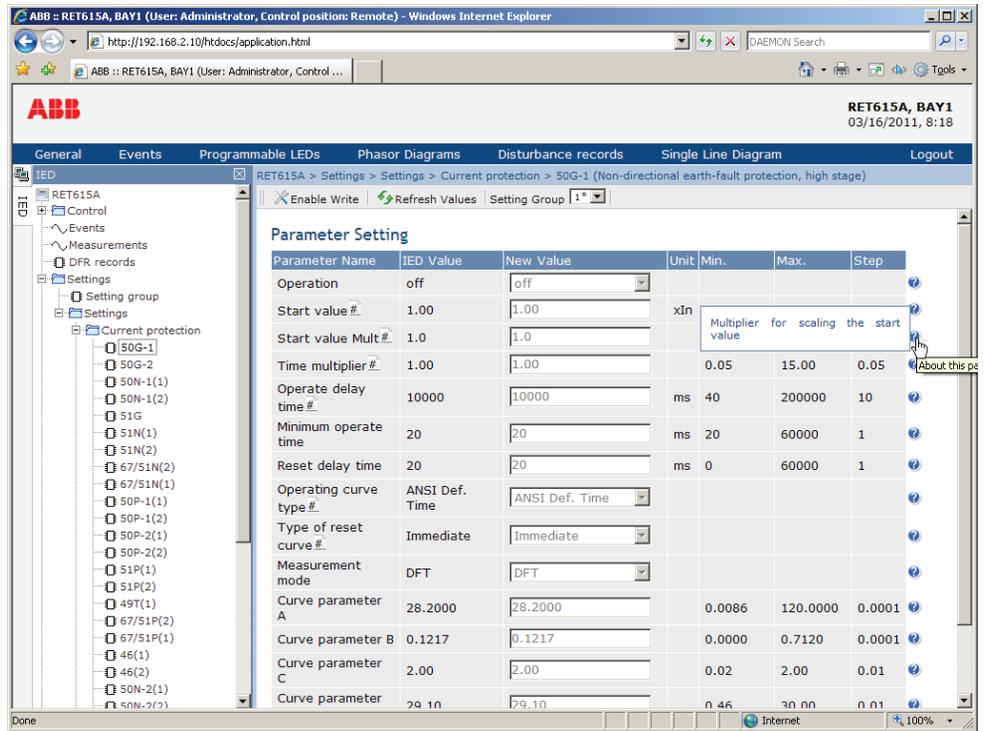


Figure 54: Opening the WHMI help

## Section 5 IED operation

### 5.1 Normal operation

In a normal IED use situation, the basic operation includes monitoring and checking procedures.

- Monitoring measured values
- Checking object states
- Checking function setting parameters
- Checking events and alarms

All basic operations can be performed via the LHMI, WHMI or with PCM600.



For more information, see PCM600 documentation.

### 5.2 Disturbance identification

Disturbances and their causes can be identified by indicator LEDs: Normal, Pickup and Trip. During normal operation, the Normal LED is steady green.

**Table 14:** *Disturbance indications*

LED	State	Description
Pickup LED	Yellow, steady	Protection picked up
Pickup LED	Yellow, flashing	Protection function blocked
Trip LED	Red, steady	Protection tripped
Normal LED	Green, flashing	Internal fault

Further actions to be taken to identify the disturbance:

- Checking programmable LEDs
- Reading event history
- Checking fault records
- Analyzing DFR recordings



Document the disturbance before clearing the information from the IED.



Only authorized and skilled personnel should analyze possible errors and decide on further actions. Otherwise, stored disturbance data can be lost.

### 5.2.1 DFR recording triggering

DFR recordings are normally triggered by IED applications when they detect fault events. DFR recordings can also be triggered manually or periodically. The manual trigger generates an instant disturbance report. Use this function to get a snapshot of the monitored line.

### 5.2.2 DFR record analysis

The IED collects disturbance records of fault events which are set to trigger the DFR recorder. DFR data is collected and stored for later viewing and analysis. The DFR recorder data can be uploaded and analyzed, for example, with PCM600.



For more information, see PCM600 documentation.

### 5.2.3 DFR reports

PCM600 can be used for creating reports of DFR recorder data.



For more information, see PCM600 documentation.

## 5.2.4 Internal IED errors

The IED self-supervision handles internal run-time fault situations. The main indication of an internal fault is a flashing green Normal LED.

Internal faults can be divided to hardware errors, run-time errors in the application or operating system and communication errors. Further actions always depend on the cause of the error.



Only authorized and skilled personnel should analyze the errors and decide on further actions.

The IED records system registrations, IED status data and events.



Document all the recorded data from the IED before resetting the tripping and IED lockout functions.

## 5.3 IED parametrization

IED parameters are set via the LHMI, WHMI or PCM600.

Setting parameters need to be calculated according to the electrical network conditions and the electrical characteristics of the protected equipment. The IED's settings need to be verified before the IED is connected to a system.



Document all changes to parameter settings.



For more information, see PCM600 documentation.

### 5.3.1 IED settings for IED functionality

Function settings can be edited one by one by navigating to the individual setting values, for example via the LHMI. The values in other setting groups should be known before editing a certain setting value.

---

After completing the editing of setting group values, the new values are activated. The user can either commit the edited values or discard them. Setting values can also be copied from one setting group to another.

### 5.3.2 IED settings for different operating conditions

IED settings can be designed for various operation conditions by defining different setting values to different setting groups. The active setting group can be changed by the IED application or manually via the LHMI, WHMI or PCM600.

## Section 6      Operating procedures

### 6.1              Monitoring

#### 6.1.1            Indications

The operation of the IED can be monitored via three different indications on the LHMI.

- Three indicator LEDs with fixed functionality: Normal, Pickup and Trip
- 11 programmable LEDs
- A text message on the display.

##### 6.1.1.1         Monitoring indication messages

Indication messages and tripping data are shown in a dialog box.

1. Read the indication message in the dialog box.  
The message can indicate the pickup or tripping of protection functions or an internal fault in the device.
2. Press **ESC** to close the indication message without clearing it or press **Clear** to activate the Clear view and to clear messages.

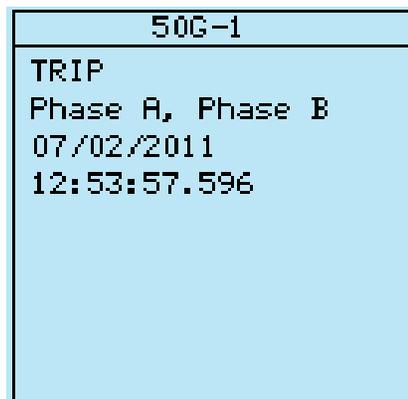


Figure 55:      Indication message

### 6.1.1.2 Monitoring an internal IED fault

The flashing green LED indicates an internal IED fault. Internal IED fault messages are shown in a dialog box.



Figure 56: Fault indication

1. Select **Main menu/Monitoring/IED status/Self-supervision** to monitor the latest fault indication.
2. Press  or  to scroll the view.

### 6.1.1.3 Monitoring condition monitoring data

1. Select **Main menu/Monitoring/I/O status/Condition monitoring**.
2. Press  or  to scroll the view.
3. Press  to enter or  to exit a submenu.

With PCM600 the user can map output signals from condition monitoring related function blocks to the appropriate destinations.

## 6.1.2 Measured and calculated values

Measurement view in **Main Menu/Measurements** shows the momentary actual values for various power system measurements.

All values show the momentary measurement value and some include demand values calculated from a set period.

### 6.1.2.1 Measured values

Measured values can be accessed through the LHMI, WHMI or PCM600.



Measured values available in the IED depend on the chosen functionality, IED type and variant.

**Table 15:** *Measured values*

Indicator	Description
IA-A	Measured current amplitude phase A
IB-A	Measured current amplitude phase B
IC-A	Measured current amplitude phase C
IA2-A	Measured current amplitude phase A
IB2-A	Measured current amplitude phase B
IC2-A	Measured current amplitude phase C
I1-A	Measured positive sequence current
I2-A	Measured negative-sequence current
I0-A	Measured zero-sequence current
I1B-A	Measured positive-sequence current
I2B-A	Measured negative-sequence current
I0B-A	Measured zero-sequence current
f-Hz	Measured frequency
Therm-Lev	Thermal level of protected object
IA-diff	Measured differential current amplitude phase IA
IB-diff	Measured differential current amplitude phase IB
IC-diff	Measured differential current amplitude phase IC
IA-bias	Measured bias current amplitude phase IA
IB-bias	Measured bias current amplitude phase IB
IC-bias	Measured bias current amplitude phase IC
PF	Average power factor
P-kW	Active power, magnitude of instantaneous value
S-kVA	Apparent power, magnitude of instantaneous value
Q-kVAr	Reactive power, magnitude of instantaneous value
PF2	Power factor, magnitude of instantaneous value
P2-kW	Active power, magnitude of instantaneous value
S2-kVA	Apparent power, magnitude of instantaneous value
Q2-kVAr	Reactive power, magnitude of instantaneous value
IG-A	Measured residual current
VG-kV	Measured residual voltage
PFA	Power factor, magnitude of instantaneous value, phase A

Table continues on next page

Indicator	Description
PFB	Power factor, magnitude of instantaneous value, phase B
PFC	Power factor, magnitude of instantaneous value, phase C
PA-kW	Active power, magnitude of instantaneous value, phase A
PB-kW	Active power, magnitude of instantaneous value, phase B
PC-kW	Active power, magnitude of instantaneous value, phase C
SA-kVA	Apparent power, magnitude of instantaneous value, phase A
SB-kVA	Apparent power, magnitude of instantaneous value, phase B
SC-kVA	Apparent power, magnitude of instantaneous value, phase C
QA-kVAr	Reactive power, magnitude of instantaneous value, phase A
QB-kVAr	Reactive power, magnitude of instantaneous value, phase B
QC-kVAr	Reactive power, magnitude of instantaneous value, phase C
PFA2	Power factor, magnitude of instantaneous value, phase A
PFB2	Power factor, magnitude of instantaneous value, phase B
PFC2	Power factor, magnitude of instantaneous value, phase C
PA2-kW	Active power, magnitude of instantaneous value, phase A
PB2-kW	Active power, magnitude of instantaneous value, phase B
PC2-kW	Active power, magnitude of instantaneous value, phase C
SA2-kVA	Apparent power, magnitude of instantaneous value, phase A
SB2-kVA	Apparent power, magnitude of instantaneous value, phase B
SC2-kVA	Apparent power, magnitude of instantaneous value, phase C
QA2-kVAr	Reactive power, magnitude of instantaneous value, phase A
QB2-kVAr	Reactive power, magnitude of instantaneous value, phase B
QC2-kVAr	Reactive power, magnitude of instantaneous value, phase C
VAB-kV	Measured phase-to-phase voltage amplitude phase AB
VBC-kV	Measured phase-to-phase voltage amplitude phase BC
VCA-kV	Measured phase-to-phase voltage amplitude phase CA
VAB2-kV	Measured phase-to-phase voltage amplitude phase AB
VBC2-kV	Measured phase-to-phase voltage amplitude phase BC
VCA2-kV	Measured phase-to-phase voltage amplitude phase CA
V1-kV	Measured positive-sequence voltage
V2-kV	Measured negative-sequence voltage
V0-kV	Measured zero-sequence voltage
V1B-kV	Measured positive-sequence voltage
V2B-kV	Measured negative-sequence voltage
V0B-kV	Measured zero-sequence voltage

### 6.1.2.2 Using the local HMI for monitoring

1. Select **Main menu/Measurements** to monitor measured and calculated values. The list of IED's basic measurements is shown.
2. Scroll the view with  and .

### 6.1.3 Recorded data

The IED is provided with intelligent and flexible functionality that collects different kinds of data. The recorded data gives substantial information for post fault analysis.

- DFR records
- Fault records
- Events
- Load profile record

#### 6.1.3.1 Creating digital fault records

Normally DFR recordings are triggered by the IED applications but the recording can also be triggered manually.

1. Select **Main menu/DFR records**.
2. Select **Trig recording** with  or .
3. Press , change the value with  or  and press  again.



Figure 57: Changing the value

The DFR recorder is now triggered.

### 6.1.3.2 Monitoring DFR data

Upload individual disturbance recordings from the IED with the PCM600 software to monitor DFR data.

1. Select **Main menu/DFR records**.  
All the DFR information is listed.
  2. Scroll the view with  or .
- The following items are listed in the view:
- Number of recordings currently in the IED memory.
  - Remaining amount of recordings that fit into the available recording memory.
  - Recording memory used in percentage.
  - If the periodic triggering function is used, the time to trigger which indicates the remaining time to the next periodic triggering of the DFR.



Figure 58: Monitoring DFR via the LHM

### 6.1.3.3 Controlling and uploading DFR recorder data

DFR recorder data can be controlled and read with PCM600. It can also be uploaded via WHMI.



For more information, see PCM600 documentation.

### 6.1.3.4 Monitoring fault records

Timestamps of the fault records are shown as a list. The first fault record is the newest.

1. Select **Main Menu/Monitoring/Recorded data/Fault record**.
2. To navigate between the fault records, press  and .
3. To enter or exit a submenu, press  or .

Fault record	A
2010-07-27 07:49	
2010-07-15 09:04	
2010-07-13 07:14	
2010-06-20 12:18	
2010-06-19 08:00	
2010-06-17 09:17	
2010-06-10 09:00	
2010-05-10 07:54	
2010-05-05 13:00	

Figure 59: Monitoring fault records

### 6.1.3.5

#### Monitoring events

Event view contains a list of events produced by the application configuration. Each event takes one view area. The header area shows the currently viewed event index and the total amount of the events. The most recent event is always first.

1. Select **Main Menu/Events**.
2. Press  to view the first event.  
Date, time, device description, object description and event text elements of the event are shown.
3. Press  or  to scroll the view.

```
6/8 02/07/2011
-----
11:34:27.832
Control LLN0
LR state
Local
```

Figure 60: Monitoring events

### 6.1.3.6 Monitoring and uploading load profile record

- Monitor the recording memory usage of the load profile via **Main menu/ Monitoring/Load profile record**.
- Upload and analyze the load profile record with PCM600.

## 6.1.4 Remote monitoring

The IED supports comprehensive remote monitoring.

### 6.1.4.1 Monitoring the IED remotely

Use the PCM600 tool and WHMI to operate the IED remotely.

- Read maintenance record and version log.
- Analyze DFR data.
- Create DFR records.
- Monitor IED values.



For more information, see PCM600 documentation.

## 6.2 Controlling

### 6.2.1 Controlling circuit breaker or contactor

The primary equipment can be controlled via the LHMI with the Open and Close buttons when the IED is set to local control mode and you are authorized to access control operations.

1. Press  to open or  to close the object.
2. Enter the password when prompted.
3. Select the object with  or  if there are more than one controllable object and press  to confirm the selection.
4. To confirm the operation, select Yes and press .

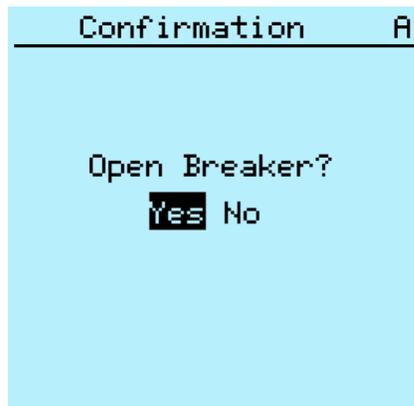


Figure 61: Opening circuit breaker

- To cancel the operation, select No and press .

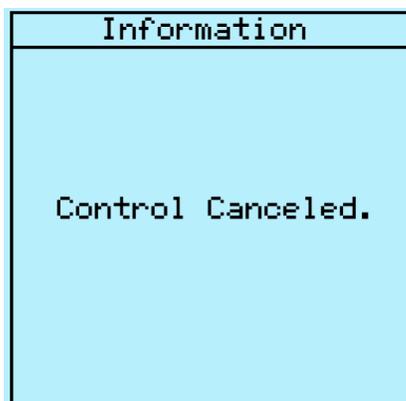


Figure 62: Cancelling operation



The time between selecting the object and giving a control command is restricted by an adjustable time-out. When an object is selected, the control command has to be given within this time.



With default configurations it is possible to control a breaker open even when the breaker is in an intermediate state.

## 6.2.2

### Controlling with single-line diagram

In the single-line diagram view it is possible to open and close the controllable object. The position indication of the object can be seen on the single-line diagram.

1. Select the object with  or  if there are more than one controllable object in the single-line diagram.  
The selected object has a square around it.

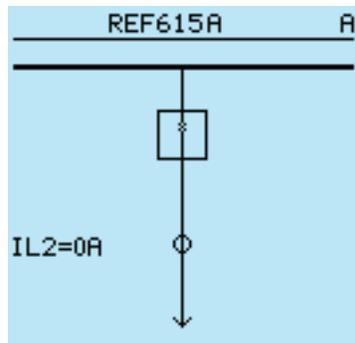


Figure 63: Single-line diagram with one breaker and IEC symbols

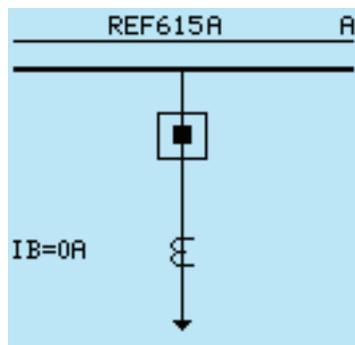


Figure 64: Single-line diagram with one breaker and ANSI symbols

2. Press  to open or  to close the selected object.
3. Enter the password when prompted.
4. Select Yes and press  to confirm.

## 6.3 Resetting IED

### 6.3.1 Clearing and acknowledging via the local HMI

All messages and indications, including LEDs and latched outputs as well as registers and recordings can be reset, acknowledged or cleared with the Clear button. Pressing the Clear button activates a menu for selecting the wanted clearance or reset function. Events and alarms assigned to programmable LEDs can also be cleared with the Clear button.

1. Press  to activate the Clear view.  
All the items that can be cleared are shown:

- Indications and LEDs
- Programmable LEDs
- Events
- Metering records
- Power quality data
- DFR records
- Fault records
- Load profile record
- Acc. energy of circuit-breaker condition monitoring, three-phase power and energy measurement, and single-phase power and energy measurement
- Rem. life of circuit-breaker condition monitoring
- Travel times of circuit-breaker condition monitoring
- Spr. charge time of circuit-breaker condition monitoring
- Temperature of three-phase thermal protection for feeders, cables and distribution transformers, and thermal overload protection for motors
- Reset of auto-reclosing and cable fault detection
- Operation time of runtime counter for machines and devices
- Counters for auto-reclosing and motor start-up supervision
- Master trip

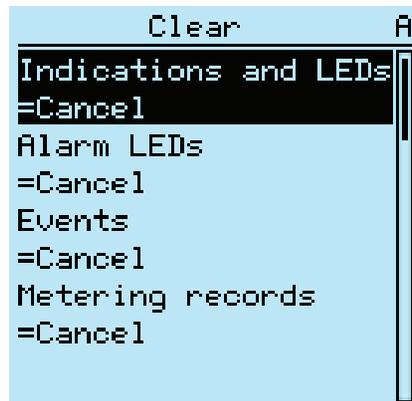


Figure 65: Clear view

2. Select the item to be cleared with  or .
3. Press , change the value with  or  and press  again.  
The item is now cleared.
4. Repeat the steps to clear other items.



Use the  button as a shortcut for clearing. The first three-second press clears the indications. The second three-second press clears the programmable LEDs.

## 6.4 Changing the IED functionality

### 6.4.1 Defining the setting group

#### 6.4.1.1 Activating a setting group

IED settings are planned in advance for different operation conditions by calculating setting values to different setting groups. The active setting group can be changed by the IED application or manually from the menu.

1. Select **Main menu/Settings/Setting group/Active group** and press .



Figure 66: Active setting group

2. Select the setting group with  or .
3. Press  to confirm the selection or  to cancel.

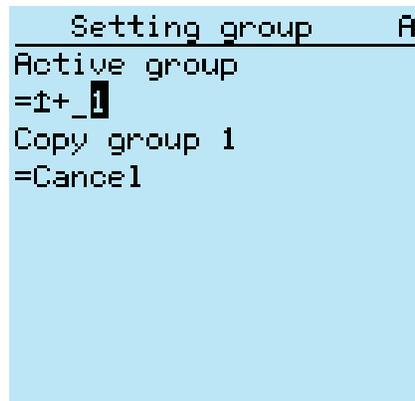


Figure 67: Selecting the active setting group

4. Commit the settings.



Remember to document the changes you make.

### 6.4.1.2

#### Copying a setting group

Setting group 1 can be copied to another group or to all available groups.

1. Select **Main menu/Settings/Setting group/Copy group 1** and press .
2. Change the options with  or  and press  to confirm the selection.

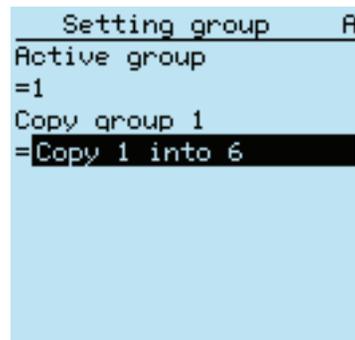


Figure 68: Copy group 1 into 6

### 6.4.1.3 Browsing and editing setting group values

1. Select **Main menu/Settings/Settings** and press .
2. Select the setting group to be viewed with  or  and press  to confirm the selection.



Figure 69: Selecting a setting group

3. To browse the settings, scroll the list with  and  and to select a setting press .
4. To browse different function blocks, scroll the list with  and  and to select a function block press . To move back to the list, press . The function block list is shown in the content area of the display. On the left in the header, you see the current setting group, and on the right the menu path.
5. To browse the parameters, scroll the list with  and  and to select a parameter, press . The setting group values are indicated with #.

```
SG2:50G-1 A
Pickup value #
=1.00 xIn #
Pickup value mult #
=1.0 #
Time multiplier #
=1.0 #
Trip delay time #
=40 ms #
```

Figure 70: Setting group parameter

- To select a setting group value, press  and to edit the value press .

```
SG2:Trip delay time A
*[1]=40 ms
[2]=40 ms
[3]=40 ms
[4]=40 ms
[5]=40 ms
[6]=40 ms
```

Figure 71: Selecting the setting group value

Only values within the selected setting group can be changed.

- Press  or  to change the value and  to confirm the selection.

```

SG2: Trip delay time A
*[1]=40 ms
[2]=1+___40 ms
[3]=40 ms
[4]=40 ms
[5]=40 ms
[6]=40 ms

```

Figure 72: Editing the setting group value

The active setting group is indicated with an asterisk \*.

## 6.4.2 Activating programmable LEDs

1. Select **Main menu/Configuration/Programmable LEDs**.
2. Select a programmable LED with  or .
3. Press  to enter the selection and  to change the programmable LED mode.
4. Change the mode with  or  and press  to confirm the selection.

## 6.4.3 Setting autoscroll delay

Autoscroll delay parameter sets the delay of scrolling down measurements view if it is set as default view and the user is logged out. Autoscroll is active if the delay value is not zero.

1. Select **Main menu/Configuration/ HMI/Autoscroll delay** and press .
2. Select delay time with  or .
3. Press  to confirm the selection.

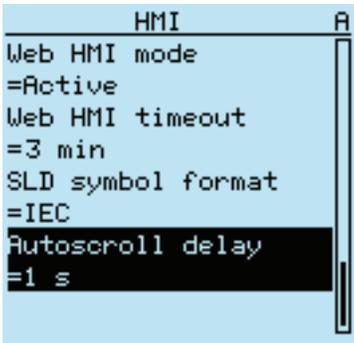


Figure 73: Autoscroll delay

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## Section 7 Troubleshooting

### 7.1 Fault tracing

#### 7.1.1 Identifying hardware errors

1. Check the module with an error.  
Check the IED supervision events in **Main menu/Monitoring/IED status/Self-supervision** for a faulty hardware module.
2. Inspect the IED visually.
  - Inspect the IED visually to find any physical error causes.
  - If you can find some obvious physical damage, contact ABB for repair or replacement actions.
3. Check whether the error is external or internal.
  - Check that the error is not caused by external origins.
  - Remove the wiring from the IED and test the input and output operation with an external test device.
  - If the problem remains, contact ABB for repair or replacement actions.

#### 7.1.2 Identifying runtime errors

1. Check the error origin from the IED's supervision events **Main menu/Monitoring/IED status/Self-supervision**.
2. Reboot the IED and recheck the supervision events to see if the fault has cleared.
3. In case of persistent faults, contact ABB for corrective actions.

#### 7.1.3 Identifying communication errors

Communication errors are normally communication interruptions or synchronization message errors due to communication link breakdown.

- In case of persistent faults originating from IED's internal faults such as component breakdown, contact ABB for repair or replacement actions.

### 7.1.3.1 Checking the communication link operation

- To verify communication, check that both LEDs above the RJ-45 communication port are lit.

**Table 16:** *Communication LEDs*

LED	Communication ok
Uplink	Steady green light
Communication	Flashing yellow light

### 7.1.3.2 Checking the time synchronization

- Check the time synchronization via LHMI in **Main menu/Monitoring/IED status/Time synchronization**.

### 7.1.4 Running the display test

A short display test is always run, when auxiliary voltage is connected to the IED. The display test can also be run manually.

- Press simultaneously  and .  
All the LEDs are tested by turning them on simultaneously. The display shows a set of patterns so that all the pixels are activated. After the test, the display returns to normal state.



If there is an indication on the display, it should be cleared first before the display test can be run manually.

## 7.2 Indication messages

### 7.2.1 Internal faults



Internal fault indications have the highest priority on the LHMI. None of the other LHMI indications can override the internal fault indication.

An indication about the fault is shown as a message on the LHMI. The text `Internal Fault` with an additional text message, a code, date and time, is shown to indicate the fault type.

Different actions are taken depending on the severity of the fault. The IED tries to eliminate the fault by restarting. After the fault is found to be permanent, the IED stays in internal fault mode. All other output contacts are released and locked for the internal fault. The IED continues to perform internal tests during the fault situation.

The internal fault code indicates the type of internal IED fault. When a fault appears, record the code so that it can be reported to ABB customer service.



*Figure 74: Fault indication*

**Table 17: Internal fault indications and codes**

Fault indication	Fault code	Additional information
Internal Fault System error	2	An internal system error has occurred.
Internal Fault File system error	7	A file system error has occurred.
Internal Fault Test	8	Internal fault test activated manually by the user.
Internal Fault SW watchdog error	10	Watchdog reset has occurred too many times within an hour.
Internal Fault SO-relay(s),X100	43	Faulty Signal Output relay(s) in card located in slot X100.
Internal Fault SO-relay(s),X110	44	Faulty Signal Output relay(s) in card located in slot X110.
Internal Fault SO-relay(s),X120	45	Faulty Signal Output relay(s) in card located in slot X120.
Internal Fault SO-relay(s),X130	46	Faulty Signal Output relay(s) in card located in slot X130.
Internal Fault PO-relay(s),X100	53	Faulty Power Output relay(s) in card located in slot X100.
Internal Fault PO-relay(s),X110	54	Faulty Power Output relay(s) in card located in slot X110.
Table continues on next page		

Fault indication	Fault code	Additional information
Internal Fault PO-relay(s),X120	55	Faulty Power Output relay(s) in card located in slot X120.
Internal Fault PO-relay(s),X130	56	Faulty Power Output relay(s) in card located in slot X130.
Internal Fault Light sensor error	57	Faulty ARC light sensor input(s).
Internal Fault Conf. error,X000	62	Card in slot X000 is wrong type.
Internal Fault Conf. error,X100	63	Card in slot X100 is wrong type or does not belong to the original composition.
Internal Fault Conf. error,X110	64	Card in slot X110 is wrong type, is missing or does not belong to the original composition.
Internal Fault Conf. error,X120	65	Card in slot X120 is wrong type, is missing or does not belong to the original composition.
Internal Fault Conf.error,X130	66	Card in slot X130 is wrong type, is missing or does not belong to the original composition.
Internal Fault Card error,X000	72	Card in slot X000 is faulty.
Internal Fault Card error,X100	73	Card in slot X100 is faulty.
Internal Fault Card error,X110	74	Card in slot X110 is faulty.
Internal Fault Card error,X120	75	Card in slot X120 is faulty.
Internal Fault Card error,X130	76	Card in slot X130 is faulty.
Internal Fault LHMI module	79	LHMI module is faulty. The fault indication may not be seen on the LHMI during the fault.
Internal Fault RAM error	80	Error in the RAM memory on the CPU card.
Internal Fault ROM error	81	Error in the ROM memory on the CPU card.
Internal Fault EEPROM error	82	Error in the EEPROM memory on the CPU card.
Internal Fault FPGA error	83	Error in the FPGA on the CPU card.
Internal Fault RTC error	84	Error in the RTC on the CPU card.
Internal Fault RTD card error,X130	96	Card in slot X130 has RTD fault.

## 7.2.2

### Warnings

Warnings are indicated with the text `Warning` additionally provided with the name of the warning, a numeric code, and the date and time on the LHMI. The warning indication message can be manually cleared.

If a warning appears, record the name and code so that it can be provided to ABB customer service.



Figure 75: Warning

Table 18: Warning indications and codes

Warning indication	Warning code	Additional information
Warning Watchdog reset	10	A watchdog reset has occurred.
Warning Power down det.	11	The auxiliary supply voltage has dropped too low.
Warning IEC61850 error	20	Error when building the IEC 61850 data model.
Warning Modbus error	21	Error in the Modbus communication.
Warning DNP3 error	22	Error in the DNP3 communication.
Warning Dataset error	24	Error in the Data set(s).
Warning Report cont. error	25	Error in the Report control block(s).
Warning GOOSE contr. error	26	Error in the GOOSE control block(s).
Warning SCL config error	27	Error in the SCL configuration file or the file is missing.
Warning Logic error	28	Too many connections in the configuration.
Warning SMT logic error	29	Error in the SMT connections.

Table continues on next page

Warning indication	Warning code	Additional information
Warning GOOSE input error	30	Error in the GOOSE connections.
ACT error	31	Error in the ACT connections.
Warning GOOSE Rx. error	32	Error in the GOOSE message receiving.
Warning AFL error	33	Analog channel configuration error.
Warning Unack card comp.	40	A new composition has not been acknowledged/accepted.
Warning Protection comm.	50	Error in protection communication.
Warning ARC1 cont. light	85	A continuous light has been detected on the ARC light input 1.
Warning ARC2 cont. light	86	A continuous light has been detected on the ARC light input 2.
Warning ARC3 cont. light	87	A continuous light has been detected on the ARC light input 3.
Warning RTD card error,X130	96	Temporary error occurred in RTD card located in slot X130.
Warning RTD meas. error,X130	106	Measurement error in RTD card located in slot X130.

## 7.3 Correction procedures

### 7.3.1 Rebooting the software

1. Select **Main menu/Configuration/General/Software reset** and press .
2. Change the value with  or  and press .

### 7.3.2 Restoring factory settings

In case of configuration data loss or any other file system error that prevents the IED from working properly, the whole file system can be restored to the original factory state. All default settings and configuration files stored in the factory are restored.

1. Select **Main menu/Configuration/General/Factory setting** and press .
2. Set the value with  or  and press .
3. Confirm by selecting **Yes** with  or  and press  again

The IED restores the factory settings and restarts. Restoring takes 1-3 minutes. Confirmation of restoring the factory settings is shown on the display a few seconds, after which the IED restarts.



Avoid unnecessary restoring of factory settings, because all the parameter settings that are written earlier to the relay will be overwritten with the default values. During normal use, a sudden change of the settings can cause a protection function to trip.



To restore factory settings from bootloader mode, press ESC + KEY simultaneously for 5 seconds.

### 7.3.3

## Setting the password

If user authorization is off or the user is logged in as an administrator, user passwords can be set via the LHMI or WHMI or with PCM600.



The password can be set to write mode with engineer or operator rights but the changes to the password are not saved.



For more information, see [User authorization](#).

1. Select **Main menu/Configuration/Authorization**.
2. Select the password to be reset with  or .
3. Press , change the password with  or  and press  again.
4. Repeat steps 2 and 3 to set the rest of the passwords.

### 7.3.4

## Identifying IED application problems

- Check that the function is on.
- Check the blocking.
- Check the mode.
- Check the measurement value.
- Check the connection to trip and DFR functions.
- Check the channel settings.

---

### 7.3.4.1 Inspecting the wiring

The physical inspection of wiring connections often reveals the wrong connection for phase currents or voltages. However, even though the phase current or voltage connections to IED terminals might be correct, wrong polarity of one or more measurement transformers can cause problems.

- Check the current or voltage measurements and their phase information from **Main menu/Measurements**.
- Check that the phase information and phase shift between phases is correct.
- Correct the wiring if needed.
- Check the actual state of the connected binary inputs from **Main menu/Monitoring/I/O status/Binary input values**.
- Test and change the relay state manually in **Main menu/Tests/Binary outputs**.

### 7.3.4.2 Sample data interruptions

Occasionally IEDs can receive corrupted or faulty measurement data during runtime. In these cases the operation system halts the corresponding application execution until correct data is received. In case of permanent faults, the measurement chain should be checked to remove the origin of the faulty measurement data.



In case of persistent faults originating from IED's internal faults, contact ABB for repair or replacement actions.

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## Section 8      Commissioning

### 8.1              Commissioning checklist

Familiarize yourself with the IED and its functionality before you start the commissioning work.

- Ensure that you have all the needed station drawings such as single line and wiring diagrams.
- Ensure that your version of the technical manual applies to the IED version you test.
- Ensure that your setting software and connectivity packages work with the IED version you test.
- Find out if you need any additional software.
- Ensure that you have the IED settings either on paper or in electronic format. The settings and logic should be well documented.
- Inspect the settings to ensure that they are correct.
- Ensure that you have the correct cable to connect your PC to the IED's communication port. The RJ-45 port supports any CAT 5 Ethernet cable but the recommendation is STP.
- Test your PC's communication port before you go to the site.
- Find out who to contact if you have trouble and make sure you have a means to contact them.
- Find out who is responsible for the settings.
- Ensure that you have with you the proper test equipment and all needed connection cables.
- Ensure that the owner of the switchgear familiarizes you with the work site and any special aspects of it.
- Ensure that you know how to operate in emergency situations. Find out where the first aid and safety materials and exit routes are.

### 8.2              Checking the installation

#### 8.2.1          Checking the power supply

Check that the auxiliary supply voltage remains within the permissible input voltage range under all operating conditions. Check that the polarity is correct before powering the IED.

## 8.2.2 Checking CT circuits

The CTs must be connected in accordance with the terminal diagram provided with the IED, both with regards to phases and polarity. The following tests are recommended for every primary CT or CT core connected to the IED.

- Primary injection test to verify the current ratio of the CT, the correct wiring up to the protection IED and correct phase sequence connection (that is A, B, C.)
- Polarity check to prove that the predicted direction of secondary current flow is correct for a given direction of primary current flow. This is an essential test for the proper operation of the directional function, protection or measurement in the IED.
- CT secondary loop resistance measurement to confirm that the current transformer secondary loop dc resistance is within specification and that there are no high resistance joints in the CT winding or wiring.
- CT excitation test to ensure that the correct core in the CT is connected to the IED. Normally only a few points along the excitation curve are checked to ensure that there are no wiring errors in the system, for example due to a mistake in connecting the CT's measurement core to the IED.
- CT excitation test to ensure that the CT is of the correct accuracy rating and that there are no short circuited turns in the CT windings. Manufacturer's design curves should be available for the CT to compare the actual results.
- Grounding check of the individual CT secondary circuits to verify that each three-phase set of main CTs is properly connected to the station ground and only at one electrical point.
- Insulation resistance check.
- Phase identification of CT shall be made.



Both primary and secondary sides must be disconnected from the line and IED when plotting the excitation characteristics.



If the CT secondary circuit is opened or its earth connection is missing or removed without the CT primary being de-energized first, dangerous voltages may be produced. This can be lethal and cause damage to the insulation. The re-energizing of the CT primary should be prohibited as long as the CT secondary is open or unearthed."

## 8.2.3 Checking VT circuits

Check that the wiring is in strict accordance with the supplied connection diagram.



Correct all errors before continuing to test circuitry.

Test the circuitry.

- Polarity check
- VT circuit voltage measurement (primary injection test)
- Grounding check
- Phase relationship
- Insulation resistance check

The polarity check verifies the integrity of circuits and the phase relationships. The polarity should be measured as close to the IED as possible to ensure that most of the wiring is also checked.

The primary injection test verifies the VT ratio and the wiring all the way through from the primary system to the IED. Injection must be performed for each phase-to-neutral circuit and each phase-to-phase pair. In each case voltages in all phases and neutral are measured.

## 8.2.4 Checking binary input and output circuits

### 8.2.4.1 Binary input circuits

Preferably, disconnect the binary input connector from the binary input cards. Check all connected signals so that both input level and polarity are in accordance with the IEDs specifications.

### 8.2.4.2 Binary output circuits

Preferably, disconnect the binary output connector from the binary output cards. Check all connected signals so that both load and voltage are in accordance with the IED specifications.

## 8.2.5 Checking optical connections

Check that the Tx and Rx optical connections are correct.



An IED equipped with optical connections requires a minimum depth of 180 mm (7.2 inches) for plastic fiber cables and 275 mm (10.9 inches) for glass fiber cables. Check the allowed minimum bending radius from the optical cable manufacturer.

## 8.3 Authorizations

### 8.3.1 User authorization

The user categories have been predefined for LHMI and WHMI, each with different rights and default passwords.

Passwords are settable. LHMI password must be at least four and WHMI password at least nine characters. Maximum number of characters is 20 for the WHMI password and 8 for the LHMI password. Only the following characters are accepted:

- Numbers 0-1
- Letters a-z, A-Z
- Space
- Special characters !"#%&'()\*+,-./:;<=>?@[\\]^\_`{|}~



User authorization is disabled by default and can be enabled via the LHMI or WHMI **Main Menu/Configuration/Authorization**.

**Table 19:** *Predefined user categories*

Username	LHMI password	WHMI password	User rights
VIEWER	0001	remote0001	Only allowed to view
OPERATOR	0002	remote0002	Authorized to make operations
ENGINEER	0003	remote0003	Allowed to change IED parameters, but no operation rights
ADMINISTRATOR	0004	remote0004	Full access



For user authorization for PCM600, see PCM600 documentation.

---

## 8.4 Using PCM600

### 8.4.1 Setting the communication between IEDs and PCM600

The communication between the IED and PCM600 is independent of the used communication protocol within the substation or to the NCC. It can be seen as a second channel for communication.

The communication media is always Ethernet and the protocol is TCP/IP.

Each IED has an Ethernet front connector for PCM600 access. Depending on the station concept and the used station protocol, additional Ethernet interfaces may be available on the rear side of the IED. All Ethernet interfaces can be used to connect PCM600.

When an Ethernet based station protocol is used, the PCM600 communication can use the same Ethernet port and IP address. The IED is able to separate the information belonging to the PCM600 dialog.

To configure the physical connection and the IP addresses:

1. Set up or get the IP addresses of the IEDs.
2. Set up the PC for a direct link or connect the PC or workstation to the network.
3. Configure the IED IP addresses in the PCM600 project for each IED. The addresses are used for communication by the OPC interface of PCM600.

#### 8.4.1.1 Communication options

Two options are available for the connection of PCM600 to the IED.

- Direct point to point link between PCM600 and the IED
- Indirect link via a station LAN or from remote via a network

#### Point to point link

The IED is provided with an RJ-45 connector on the LHMI. The connector is mainly for configuration and setting purposes. Any Ethernet cable can be used but it is recommended to use the shielded twisted pair cable.

The IED has a DHCP server for the front interface. The DHCP server assigns an IP address to the computer connected to the front interface. The computer's LAN interface has to be configured to obtain the IP address automatically.

---

## LAN or WAN network

In TCP/IP networking, a LAN is often but not always implemented as a single IP subnet. A router connects LANs to a WAN. In IP networking, the router maintains both a LAN address and a WAN address. Design considerations for computer networks cover a wide range of topics including layout, capacity planning, and security. To some extent, the network configuration also depends on user preferences.

### 8.4.1.2

## Setting communication parameters

The IP address and the corresponding mask can be set via the LHMI for the rear port. The front port uses a fixed IP address 192.168.0.254. The front port also uses DHCP.

Each Ethernet interface has a factory default IP address when the complete IED is delivered.

## Setting the front communication

To set up a standard PC with Microsoft Windows operating system for front communication:

1. To open Network Connections, click **Start**, point to **Settings**, click **Control Panel**, and then double-click **Network Connections**.
2. Double-click the connection that you want to configure, and then click **Properties**.
3. Select the TCP/IP protocol from the list of configured components using this connection and click **Properties**.

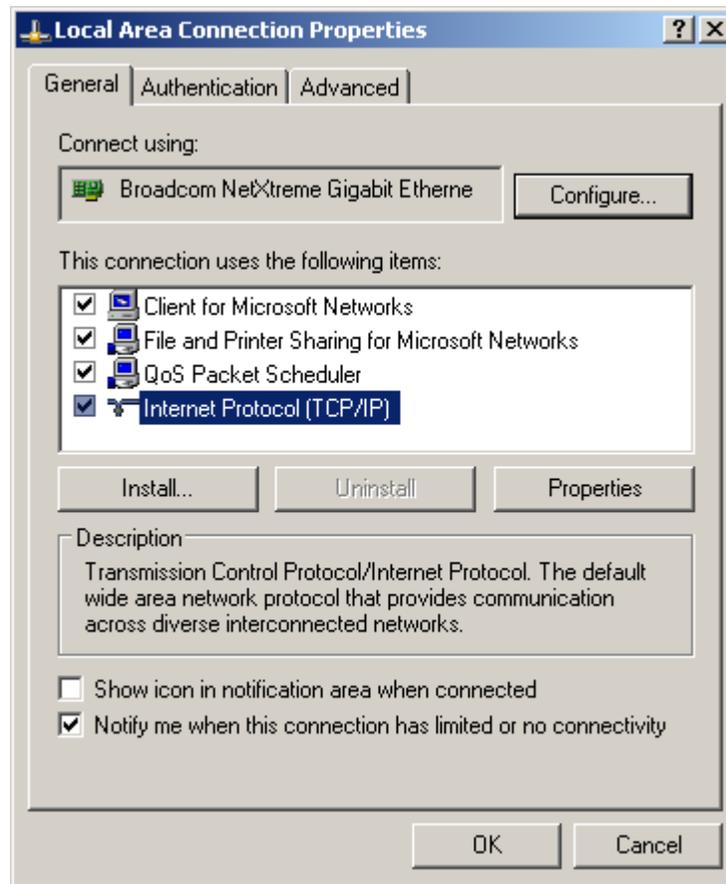


Figure 76: Selecting TCP/IP protocol

4. Select **Obtain an IP address automatically** and **Obtain DNS server address automatically**.

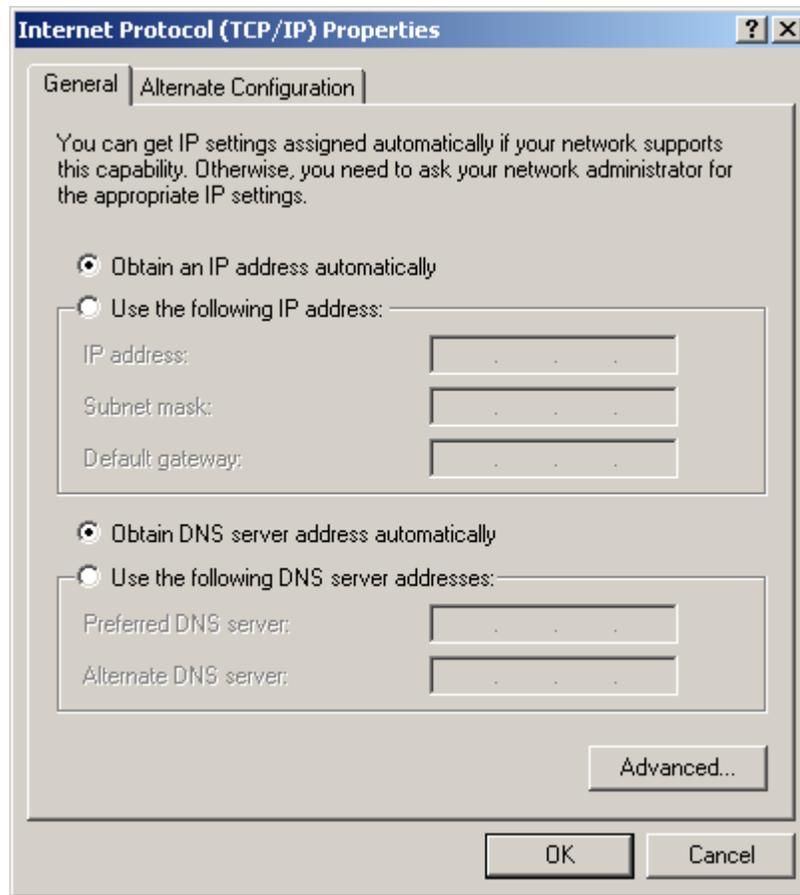


Figure 77: Obtaining IP address automatically

5. Close all open windows by clicking **OK** and start PCM600.



Administrator rights are requested to change the configuration as described above.

### Setting the rear communication

To set up a standard PC with MicroSoft Windows operating system for rear communication:

1. To open Network Connections, click **Start**, point to **Settings**, click **Control Panel**, and then double-click **Network Connections**.
2. Double-click the connection that you want to configure, and then click **Properties**.
3. Select the TCP/IP protocol from the list of configured components using this connection and click **Properties**.

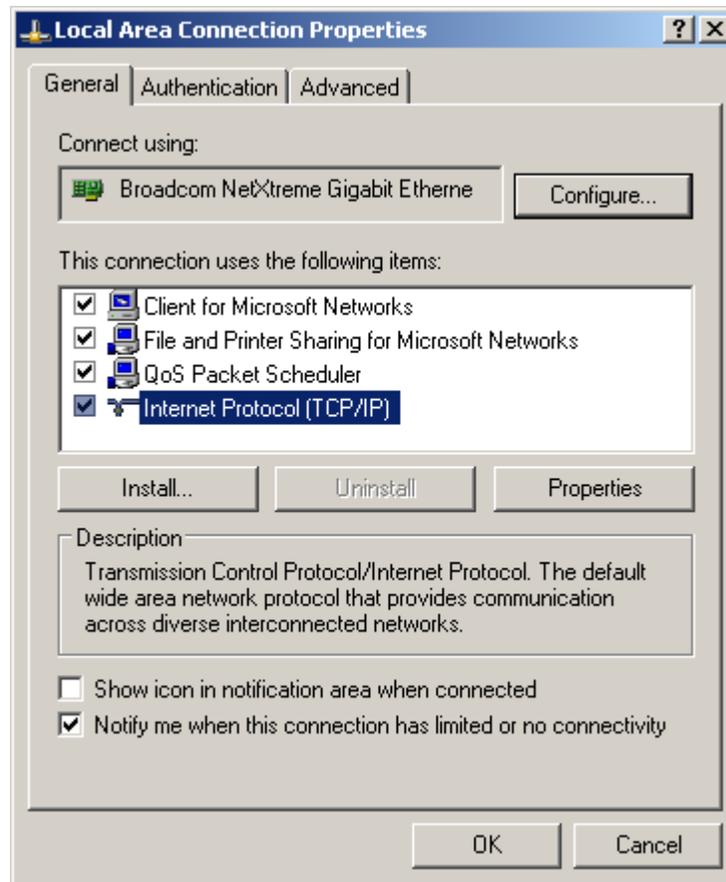


Figure 78: Selecting TCP/IP protocol

4. Choose **Use the following IP address**. Enter an IP address and a subnet mask. Make sure that the IP address is unique, that is not used by any other IED on the network.

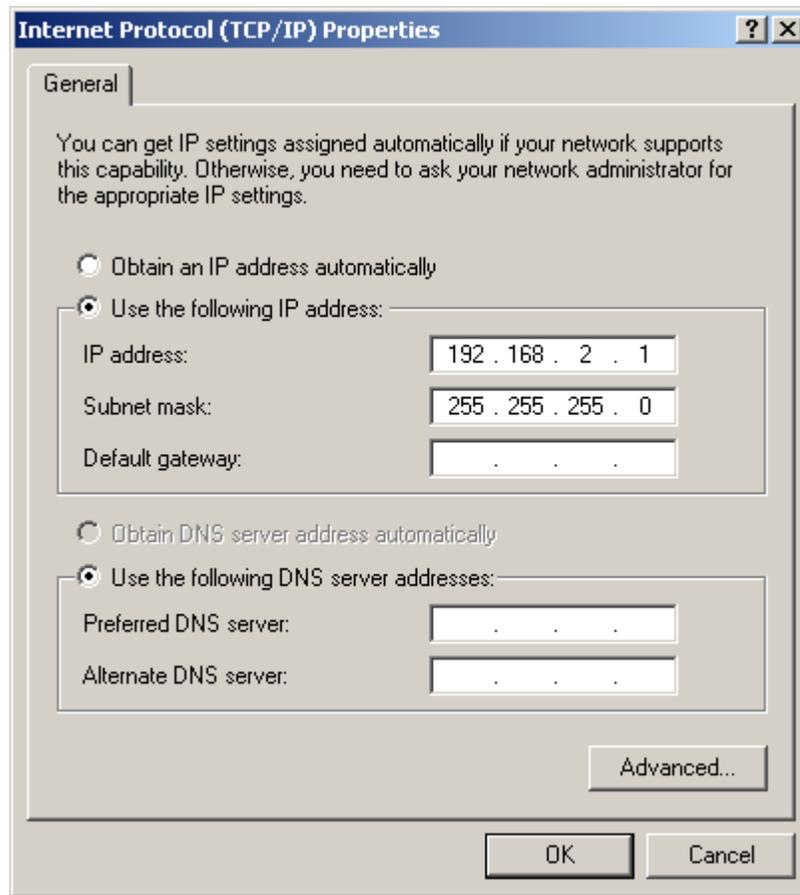


Figure 79: Setting IP address and subnet mask

5. Close all open windows by clicking **OK** and start PCM600.



Administrator rights are requested to change the configuration as described above.

### Setting IED's IP address in PCM600

In PCM600 the IED's IP address can be defined via the first window of the wizard by including a new IED in the project or by entering the IED's IP address in the Object Properties window.

1. Select the IED to which you want to define the IP address.
2. Open the Object Properties window.
3. Place the cursor in the IP Address row and enter the IP address.

The used method depends on the time at which the IP address is available. Defining IP address in the Object Properties windows allows changing the IP address at any time.

## 8.5 Setting IED and communication

### 8.5.1 Communication settings

The IED is provided with an RJ-45 connector on the LHMI. The connector is mainly used for configuration and setting purposes. The fixed IP address for the front port is 192.168.0.254.

Different communication ports are available via optional communication modules. Ethernet RJ-45 and optical Ethernet LC are the two rear port Ethernet communication options. Rear port Ethernet is intended for station bus communication. Communication protocols used via Ethernet ports are IEC 61850-8-1, DNP3 TCP/IP and Modbus TCP/IP.



For more information, see the communication protocol manuals and the technical manual.



If the protocol does not operate as expected, check that other serial protocols are not using the COM port.



DNP3 protocol ignores any parity setting in the COM settings group; DNP3 is defined as an 8 bit/no parity protocol with a 16-bit CRC every 16 bytes. This provides better error detection than parity.

#### 8.5.1.1 Serial communication ports and drivers

Depending on the hardware configuration, the IED can be equipped with one or several UART-based serial communication ports. The communication ports can be either galvanic (RS-485, RS-232) or fibre-optic. The IED uses serial ports and drivers as different types of serial communication protocol links.

Serial ports are called COM1, COM2 and so on, depending on the number of serial ports in the IED hardware configuration. Each COM port driver has its own setting parameters found via the LHMI in **Configuration/Communication/COMn** (n= 1,2,...).

Since the same IED usually supports a variety of different communication hardware options, all COM port driver setting parameters are not relevant for every communication hardware type.

**Table 20:** *COM port parameters in different HW options*

COM parameter	Values	Hardware options <sup>1)</sup>
Fiber mode	0 = No fiber	Used in the fiber-optic mode only. Note that <i>No fiber</i> mode is the same as the galvanic mode.
	1 = Fiber light ON/loop	
	2 = Fiber light OFF/loop	
	3 = Fiber light ON/star	
	4 = Fiber light OFF/star	
Serial mode	0 = RS485 2wire	For galvanic modes. RS-type depends on the communication card used. Note that this setting parameter is relevant only if <i>Fiber mode</i> is set to <i>No Fiber</i> .
	1 = RS485 4wire	
	2 = RS232 no handshake	
	3 = RS232 with handshake	
CTS Delay	0...60000 [ms]	RS232 mode only
RTS Delay	0...60000 [ms]	RS232 mode only
Baudrate	1 = 300	All modes
	2 = 600	
	3 = 1200	
	4 = 2400	
	5 = 4800	
	6 = 9600	
	7 = 19200	
	8 = 38400	
	9 = 57600	
	10 = 115200 [bits/sec]	

1) When fiber mode is used, the *Serial mode* parameter value must be *RS485 2wire*.



In addition to setting the COM parameter, a communication card with many hardware options may also require changing the jumpers on the communication card.

### Connection of a serial communication protocol to a specific serial port

The serial communication protocol (instance) settings include a setting parameter called *Serial port n* (n = protocol instance number). Setting options for this parameter are *COM1*, *COM2* and so on. Select the desired serial port for the protocol instance through this parameter.



All link setting parameters are not found in the COMn settings. Additional link setting parameters are found in the setting parameter list of the used serial protocol, since some serial protocol standards allow changes in link parameters, while other protocol standards do not.

### 8.5.1.2

## Serial link diagnostics and monitoring

Serial communication diagnostics and monitoring is divided between the serial link driver and the serial communication protocol. The lower level physical and protocol-independent aspects of the UART-based serial communication are monitored in the serial link driver. Diagnostic counters and monitoring values are found via the LHMI in **Monitoring/Communication/COMn** (n= 1,2,...).

Depending on the communication protocol, the serial driver software receives single characters or complete protocol frames, based on the frame start/stop characters or on timing.

Monitoring data for a COM channel can be divided into basic and detailed diagnostic counters.

**Table 21:** *Monitoring data for a COM channel*

Parameter	Range	Type	Description
Characters received	0...2147483646	Basic	Number of separate characters received.
Frames received	0...2147483646	Basic	Number of successfully received complete frames.
Frames discarded	0...2147483646	Basic	Number of frames discarded.
Frames transmitted	0...2147483646	Basic	Number of frames transmitted.
CD Lost	0...2147483646	Detailed	Number of carrier-detect signal lost during receive.
Collision	0...2147483646	Detailed	Number of collisions detected.
CTS Timeout	0...2147483646	Detailed	Number of clear-to-send signal timeout errors.
Transmission timeout	0...2147483646	Detailed	Number of transmission timeout errors.
Parity errors	0...2147483646	Detailed	Number of character parity errors detected.
Overrun errors	0...2147483646	Detailed	Number of character overrun errors detected.
Framing errors	0...2147483646	Detailed	Number of character overrun errors detected.
Link status	1		1 = Reset counters (by entering 1 the diagnostic counters are reset)

Whether all diagnostic counters are relevant depends on the communication hardware and communication protocol.

**Table 22:** *Basic diagnostic counters*

Counter	Function
Characters received	Counts all incoming non-erroneous characters. This counter operates regardless of if the serial driver is set to detect a whole protocol link frame or just separate characters.
Frames received	Counts all protocol specific non-erroneous frames received. Protocol-specific frames can be based on timing (for example, Modbus RTU) or on special start and stop characters (for example, Modbus ASCII).
Frames discarded	Counts all protocol-specific erroneous frames received. If the driver detects an error while receiving a frame, the frame is automatically discarded. This also means that the protocol in question will never receive a faulty frame from the driver. When this counter is increased, one of the detailed error counters is also incremented.
Frames transmitted	Counts all protocol-specific frames transmitted from the COM channel.

**Table 23:** *Detailed error counters*

Counter	Function
CD Lost	In RS-232 handshake mode, characters are to be received as long as Carrier Detect (CD) signal is active. This counter is incremented if the CD signal is lost during reception.
Collision	Counts transmission collisions. Used in RS-485 mode by some protocols where transmissions could collide. For example DNP3 unsolicited mode.
CTS Timeout.	In RS-232 handshake mode the Clear To Send (CTS) signal is not received as reply to this device Request To Send (RTS) signal.
Transmission timeout.	In RS-232 handshake mode. If the CTS signal goes inactive during transmission then the transmission is halted. Transmission will be resumed when CTS goes active again. The whole frame transmission must anyhow be ready within a specified time. If this timeout elapses then this counter is incremented. Result will be that the end of the frame is not being transmitted out.
Parity errors	Counts parity errors detected in characters.
Overrun errors	Counts overrun errors detected in characters.
Framing errors	Counts framing errors detected in characters

**Table 24:** *Link status*

Parameter	Function
Link status	Link status in write direction: By writing 1 to the parameter the diagnostic counters are reset to 0.
	Link status in monitoring direction: If the driver is in use by any communication protocol, the monitoring value shows 1. In other case, the value is 0.

### 8.5.1.3

#### Defining Ethernet port settings



Change the Ethernet port settings primarily via PCM600. Then PCM600 is able to export consistent configuration to SYS600. Ethernet port settings are recommended to be changed only when the device is stand-alone and properly configured.

1. Select **Main menu/Configuration/Communication/Ethernet/Rear port**.
2. Define the settings for the Ethernet port.
  - IP address
  - Subnet mask
  - Default gateway of the optional rear port Ethernet connector

### 8.5.1.4

#### Defining serial port settings

The serial COM setting is not currently supported.

1. Select **Main menu/Configuration/Communication/COM1** or **COM2**.
2. Define the settings for the serial port.  
It is possible to change the general serial communication parameters per port. Select fibre or galvanic mode with the proper baud rate, parity and delays depending on the system architecture and the selected physical communication port.

### 8.5.1.5

#### Setting communication protocol parameters

1. Select **Main menu/Configuration/Communication/<protocol>**.
2. Change the protocol specific settings.  
Possible settings to be changed are, for example, the selected communication port, address and link mode.

### 8.5.1.6 Connecting jumper connectors



See the technical manual for details on jumper connectors.

### 8.5.1.7 Communication checklist

1. Check the physical connections.
2. After the settings are changed, allow them to be stored in the non-volatile memory (S character on the icon area of the LHMI).  
Reboot the unit to allow the setting changes to take effect in DNP3.
3. If the WHMI connection is missing, enable the IED's WHMI setting and prevent the Web browser from attempting to use a proxy via **Internet Options/Connections/LAN Settings/Advanced/Exceptions** (for example 192.168.\*.\*;).
4. Ping the unit.  
Verify that the IED has been correctly configured to accept messages with the master's IP address, DNP3 address, and so on.
5. Use the LHMI to enable the WHMI configuration if a ping response is received from the unit but the WHMI does not respond.
  - 5.1. Clear the browser of cached pages.
  - 5.2. Logout and log back in.
6. Install a TCP packet sniffer to see what is happening on the network.
7. Clear the ARP table.
8. See the IED's technical manual to determine if the jumpers on the communication board are correct.



If this protocol does not operate as expected, check that other serial protocols are not using the COM port also.



DNP3 protocol ignores any parity setting in the COM settings group; DNP3 is defined as an 8 bit/no parity protocol with a 16-bit CRC every 16 bytes. This provides better error detection than parity.

## 8.5.2 Setting the local HMI

### 8.5.2.1 Changing the local HMI language

1. Select **Main menu/Language** and press .
2. Change the language using  or .
3. Press  to confirm the selection.
4. Commit the changes.



Figure 80: Changing the LHMI language



To change the language using a shortcut, press  and  simultaneously anywhere in the menu.

### 8.5.2.2 Adjusting the display contrast

Adjust the display contrast anywhere in the menu structure to obtain optimal readability.

- To increase the contrast, press simultaneously  and .
- To decrease the contrast, press simultaneously  and .

The selected contrast value is stored in the non-volatile memory if you are logged in and authorized to control the IED. After an auxiliary power failure, the contrast is restored.

### 8.5.2.3 Changing display symbols

To switch between the display symbols IEC 61850, IEC 60617 and ANSI:

1. Select **Main Menu/Configuration/HMI/FB naming convention** and press .
2. Change the display symbols with  or .
3. Press  to confirm the selection.



The IED has to be rebooted if the WHMI display symbols are changed. With the LHMI, the change takes effect immediately.

### 8.5.2.4 Changing the default view

The default view of the display is **Measurements** unless set otherwise.

1. Select **Main menu/Configuration/HMI/Default view** and press .
2. Change the default view with  or .
3. Press  to confirm the selection.

### 8.5.2.5 Setting the system time and time synchronization

1. Select **Main menu/Configuration/Time/System time**.
2. Select the parameter with  or .
3. Press , change the value with  or  and press  again.
4. Repeat steps 2 and 3 to set the rest of the system time parameters.
5. Select **Main menu/Configuration/Time/Synchronization/Synch source** and press .
6. Select the time synchronization source with  or .
7. Press  to confirm the selection.

#### Setting the daylight saving time

The IED can be set to determine the correct date for the DST shift every year. The UTC time is used to set the DST.

1. Set the *DST on day* and *DST off day* parameters to define on which week day the time shift occurs.
2. Set the *DST on date* and *DST off date* parameters to define on which month and week the time shift occurs.

The DST on/off date must precede the selected DST on/off day and be within the same week as the DST shift.

**Table 25:** *Possible date values for DST change on Sunday*

Day of the DST shift	DST on/off date (dd)
First Sunday of the month	1
Second Sunday of the month	8
Third Sunday of the month	15
Fourth Sunday of the month	22
Last Sunday, if the month has 30 days	24
Last Sunday, if the month has 31 days	25

For example, if the DST is observed from the last Sunday in March to the last Sunday in October and the time shift occurs at 01:00 UTC, the setting parameters are:

DST on time: 01:00  
 DST on date: 25.03  
 DST on day: Sun  
 DST off time: 01:00  
 DST off date: 25.10  
 DST off day: Sun



Set the *DST on day* and *DST off day* to "not in use" to determine the exact date and time for the DST shift. Repeat the setting yearly, as the time for the DST shift is not on the same date every year.



To disable the DST, set the *DST offset* parameter to "0 min".

## 8.5.3 Setting IED parameters

### 8.5.3.1 Defining setting groups

#### Selecting a setting group for editing

1. Select **Main Menu/Settings/Edit setting group**.
2. Select the setting group to be edited with  or .
3. Press  to confirm the selection.
4. Edit the settings.

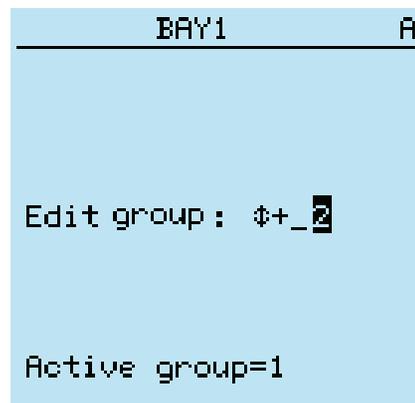


Figure 81: Selecting a setting group

#### Browsing and editing setting group values

1. Select **Main menu/Settings/Settings** and press .
2. Select the setting group to be viewed with  or  and press  to confirm the selection.



Figure 82: Selecting a setting group

3. To browse the settings, scroll the list with and and to select a setting press .
4. To browse different function blocks, scroll the list with and and to select a function block press . To move back to the list, press . The function block list is shown in the content area of the display. On the left in the header, you see the current setting group, and on the right the menu path.
5. To browse the parameters, scroll the list with and and to select a parameter, press . The setting group values are indicated with #.

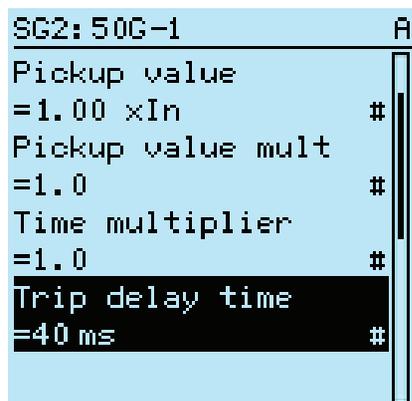


Figure 83: Setting group parameter

6. To select a setting group value, press and to edit the value press .

```
SG2:Trip delay time A
*[1]=40 ms
[2]=40 ms
[3]=40 ms
[4]=40 ms
[5]=40 ms
[6]=40 ms
```

Figure 84: Selecting the setting group value

Only values within the selected setting group can be changed.

7. Press  or  to change the value and  to confirm the selection.

```
SG2:Trip delay time A
*[1]=40 ms
[2]=1+___40 ms
[3]=40 ms
[4]=40 ms
[5]=40 ms
[6]=40 ms
```

Figure 85: Editing the setting group value

The active setting group is indicated with an asterisk \* .

### Activating a setting group

IED settings are planned in advance for different operation conditions by calculating setting values to different setting groups. The active setting group can be changed by the IED application or manually from the menu.

1. Select **Main menu/Settings/Setting group/Active group** and press .

```

Setting group      A
Active group
=1
Copy group 1
=Cancel

```

Figure 86: Active setting group

2. Select the setting group with  or .
3. Press  to confirm the selection or  to cancel.

```

Setting group      A
Active group
=i+_1
Copy group 1
=Cancel

```

Figure 87: Selecting the active setting group

4. Commit the settings.



Remember to document the changes you make.

### 8.5.3.2

### IED parametrization

IED parameters are set via the LHMI, WHMI or PCM600.

Setting parameters need to be calculated according to the electrical network conditions and the electrical characteristics of the protected equipment. The IED's settings need to be verified before the IED is connected to a system.



Document all changes to parameter settings.



For more information, see PCM600 documentation.

### 8.5.3.3 Defining DFR channel settings

1. Select **Main Menu/Configuration/DFR/Channel settings**.
2. Press or to select the wanted channel and parameter.
3. To change channel settings, press .

Analog channels are fixed except channel 4 which is selectable based on the Ground CT option.

### 8.5.3.4 Configuring analog inputs

1. Select **Main Menu/Configuration/Analog inputs**.
2. Select the analog input to be configured with or .
3. Press , change the value with or and press again.
  - For CTs, the secondary current and primary current need to be set to the correct values.

## 8.6 Testing IED operation

The IED has to be in the test mode before the digital outputs and certain output signals of protection and other functions can be activated.

## 8.6.1 Selecting the test mode

The test mode can be activated using the LHMI. The green Normal LED will be flashing to indicate that the test mode is activated.



The Normal LED also flashes if the IED detects a diagnostic failure. Check the test mode setting and the IED's IRF alarm contact status to find the reason for the failure.

The test mode is useful for simulated testing of functions and outputs without providing current inputs.

1. Select **Main menu/Tests/IED test/Test mode** and press .

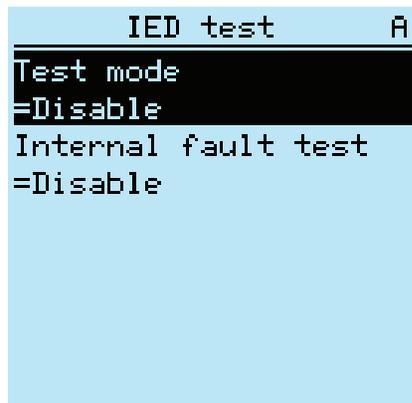


Figure 88: Entering test mode

2. Select the test mode status with  or .
3. Press  to confirm the selection.



If you do not cancel the test mode, it remains on and the Normal LED remains flashing.

## 8.6.2 Testing the digital I/O interface

To activate or deactivate, for example, a digital output:

1. Select **Main menu/Tests/Binary outputs/X100 (PSM)/X100-PO1** and press .
2. Select the value with  or .
3. Press  to confirm the selection.



If the optional BIO-module (X110) is included in the IED, the menu path could also be **Main menu/Tests/Binary Outputs/X110 (BIO)/<binary output>**.

### 8.6.3 Testing functions

To activate or deactivate an output signal for protection or other function:

1. Select **Main Menu/Tests/Function tests/Current protection/<function block name>** and press .
2. Select the output signal to be activated or deactivated with  or  and press .
3. To deactivate all output signals for the function, select **Reset** with  or  and press .

### 8.6.4 Selecting the internal fault test

The internal fault may be tested by using the LHMI. When enabling the test, the internal relay fault output contact is activated, the green Normal LED will be blinking and internal fault test indication is shown on the LHMI. See Technical Manual for internal relay fault output contact location.



Differing from real internal fault situation, the other output contacts are not released and locked during the test. In other words, protection functions can operate and trip the outputs when the internal fault is tested.

1. Select **Main menu/Tests/IED test/Internal fault test** and press .

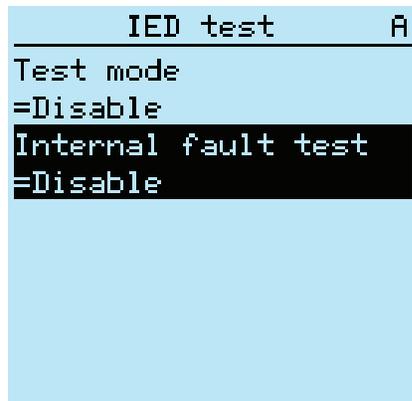


Figure 89: Internal fault test

2. Select the value with  or .
3. Press  to confirm the selection.

## 8.7 ABB Product Data Registration

The ABB Product Data Registration feature traces composition changes related to the IED's SW or HW.

After a composition change, an LCT indication is seen on the LHMI at the IED start-up. At this point, PCM600 should be connected to the IED as it reads the changed data from the IED. The LCT indication is cleared in the same way as other indications. If PCM600 is not connected to the IED, the indication is seen again after the IED's reboot.

The number of composition changes can be seen from the *Composition changes* parameter in **Main Menu/Monitoring/IED status**.



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## Section 9      Glossary

<b>ACT</b>	Application Configuration tool in PCM600; Trip status
<b>ANSI</b>	American National Standards Institute
<b>ARP</b>	Address Resolution Protocol
<b>CAT 5</b>	A twisted pair cable type designed for high signal integrity
<b>COMTRADE</b>	Common format for transient data exchange for power systems. Defined by the IEEE Standard.
<b>CPU</b>	Central processing unit
<b>CRC</b>	Cyclical redundancy check
<b>CSV</b>	Comma-separated values
<b>CT</b>	Current transformer
<b>DFR</b>	Digital fault recorder
<b>DHCP</b>	Dynamic Host Configuration Protocol
<b>DNP3</b>	A distributed network protocol originally developed by Westronic. The DNP3 Users Group has the ownership of the protocol and assumes responsibility for its evolution.
<b>DST</b>	Daylight saving time
<b>EEPROM</b>	Electrically erasable programmable read-only memory
<b>EMC</b>	Electromagnetic compatibility
<b>Ethernet</b>	A standard for connecting a family of frame-based computer networking technologies into a LAN
<b>FB</b>	Function block
<b>Firmware</b>	System software or hardware that has been written and stored in a device's memory that controls the device
<b>FPGA</b>	Field programmable gate array
<b>GOOSE</b>	Generic Object Oriented Substation Event
<b>HMI</b>	Human-machine interface
<b>HW</b>	Hardware
<b>IEC 61850</b>	International standard for substation communication and modelling

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<b>IEC 61850-8-1</b>	A communication protocol based on the IEC 61850 standard series
<b>IED</b>	Intelligent electronic device
<b>IP</b>	Internet protocol
<b>IP address</b>	A set of four numbers between 0 and 255, separated by periods. Each server connected to the Internet is assigned a unique IP address that specifies the location for the TCP/IP protocol.
<b>LAN</b>	Local area network
<b>LC</b>	Connector type for glass fiber cable
<b>LCD</b>	Liquid crystal display
<b>LCP</b>	Liquid crystal polymer
<b>LCT</b>	Life cycle traceability
<b>LED</b>	Light-emitting diode
<b>LHMI</b>	Local human-machine interface
<b>Modbus</b>	A serial communication protocol developed by the Modicon company in 1979. Originally used for communication in PLCs and RTU devices.
<b>Modbus TCP/IP</b>	Modbus RTU protocol which uses TCP/IP and Ethernet to carry data between devices
<b>NCC</b>	Network control center
<b>OPC</b>	Object linking and embedding for process control
<b>PA</b>	Polyamide
<b>PBT</b>	Polybutylene terephthalate
<b>PC</b>	Personal computer; Polycarbonate
<b>PCM600</b>	Protection and Control IED Manager
<b>R/L</b>	Remote/Local
<b>RAM</b>	Random access memory
<b>RJ-45</b>	Galvanic connector type
<b>RoHS</b>	Restriction of the use of certain hazardous substances in electrical and electronic equipment
<b>ROM</b>	Read-only memory
<b>RTC</b>	Real-time clock
<b>Rx</b>	Receive/Received

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<b>SCL</b>	Substation configuration language
<b>Single-line diagram</b>	Simplified notation for representing a three-phase power system. Instead of representing each of three phases with a separate line or terminal, only one conductor is represented.
<b>SLD</b>	Single-line diagram
<b>SMT</b>	Signal Matrix tool in PCM600
<b>STP</b>	Shielded twisted-pair
<b>SVG</b>	Scalable vector graphics
<b>SW</b>	Software
<b>TCP/IP</b>	Transmission Control Protocol/Internet Protocol
<b>Tx</b>	Transmit/Transmitted
<b>UTC</b>	Coordinated universal time
<b>VT</b>	Voltage transformer
<b>WAN</b>	Wide area network
<b>WHMI</b>	Web human-machine interface





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