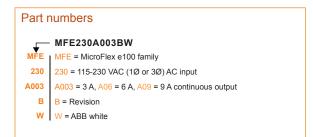
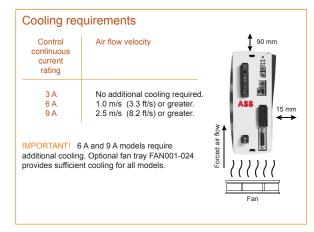
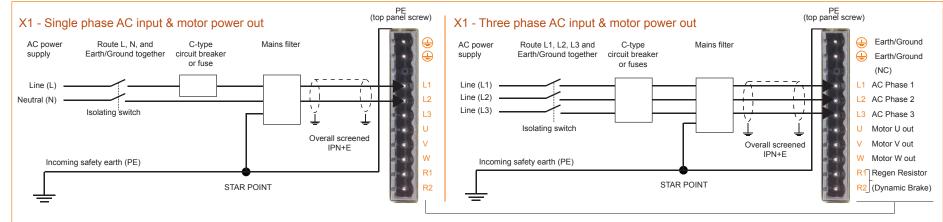


# Wall chart MicroFlex e100





Recommended system wiring



0

Recommended power filters					
Drive continuous current rating	1Ø AC power  ABB catalog number	3Ø AC power  ABB catalog number	24 VDC control supply ABB catalog number		
3 A 6 A 9 A	FI0015A00† FI0015A02† FI0029A00	FI0018A00 FI0018A00 FI0018A03	FI0014A00 (all models)		

IMPORTANT! Compliant with EN61000-6-3 (Class B).

†Alternatively, foot-mount filter FI0029A00 may be used. This filter is specially designed for use with any single-phase MicroFlex e100.

# X1 - Regenerating resistors

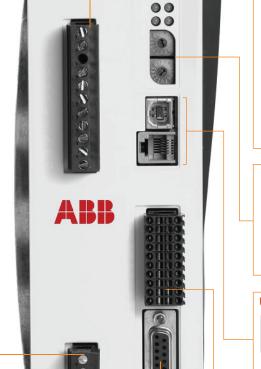
ABB catalog number	Power W	Res Ω
RGJ139	100	39
RGJ160	100	60
RGJ260	200	60
RGJ360	200	60

+24 V DC

Drive

enable





#### X6 - CANopen E1 and E2 RX+ CAN GND

RX-

Two identical RJ45 connectors with standard Ethernet pinout. Interface supports TCP/IP and provides a 2-port hub for ETHERNET Powerlink

#### Node ID (address) selection

pinout

CAN GND

Standard CANopen

CAN+

CAN V+



Example shows 0xD3 = Node 211 IP address = 192.168.100.211

#### USB port



Data-Data+

EnDat 2.1

Data+

# Auxiliary serial port



TXA TXB GND +7V out

#### **Ethernet LEDs**

Flickering

# Code

On

Status LED

Green: AC power OK, drive

enabled, normal operation

Red: AC power OK drive not enabled, no errors.

error has occurred:

Meaning

Error

**CAN LEDs** 

Code

Off

3 flashes

Blinking

Flickering

Code

2 flashes 3 flashes

Off

(flashes)

Green/Red alternating: AC power not present.

Green flickering: Firmware download in progress

Red flashing: An error has occurred. The number

of flashes (followed by a pause) indicates which

DC bus overvoltage trip IPM (integrated power module) trip Overcurrent trip

Motor overload (I t) trip

Overtemperature trip

Drive overload (It) trip Following error trip Error input triggered

Phase search error

Internal supply error,

encoder supply error.

Meaning

Meaning

No error.

All other errors, including:

parameter restore failure,

power base not recognized.

Node initializing or not powered.

Node in PREOPERATIONAL state.

Node in STOPPED state.

services in progress.

Software being downloaded

Node in OPERATIONAL state.

Auto-baudrate detection or LSS

Warning: too many error frames. Guard event or heartbeat event.
Sync error: SYNC message not received.

Auto-baudrate detection or LSS services in progress.

Node in bus-off state (removed from network).

Overspeed trip

Feedback trip

NOT ACTIVE state, waiting to be Off triggered by the manager node.

1 flash Pre-OPERATIONAL 1 state EPI starting PRE-OPERATIONAL2 state. EPL starting. 3 flashes READY TO OPERATE state. The node is signalling its readiness to operate. Blinking STOPPED state. The node has been

deactivated. OPERATIONAL state. EPL is operating

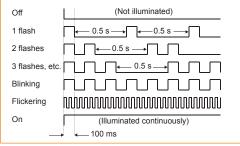
BASIC ETHERNET state. EPL is not

operating, but other Ethernet protocols may be used.

Meaning Code

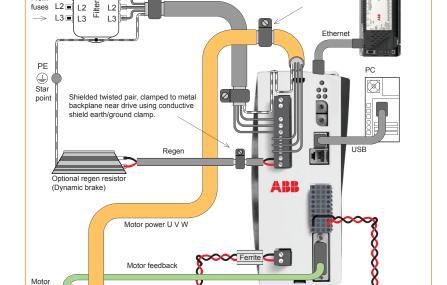
Off EPL is working correctly An error has occurred.

#### LED definitions



#### www.abb.com/motion

The information in this document is subject to change without notice. ABB assumes no responsibility for any errors that may appear in this document



2 A

0V +24 V DC

Control circuit supply. Use twisted pair cable

ith a ferrite sleeve attached close to connector X2.

resistance of at least 390 and inductance of less than 100 uH.

Regeneration resistors: If the application requires a regeneration resistor, it must have a

ABB parts RGJ139/160 (100 W), RGJ260 (200 W) or RGJ360 (300 W) are recommended.

Connect motor power cable

using conductive shield clamps

shield to metal backplane



A 24 VDC supply must be provided to power

the controlling electronics. Continuous current 0.6 A

## X8 - Feedback in



CHA+ CHA-CHB+ CHB-CH7+ CHZ-+5 V out Sense Hall II-DGND Hall U+ Hall W-Hall V-Hall W+ Hall V+

BiSS, SSI or EnDat 2.2 Data+ Data-Clock+ Clock +5 V out (NC) (NC) DGND

Smart Abs Data+ Data-Sense DGND

Clock+ +5 V out

Sin-\* Sin+\* Cos+

DGND

Data-

+5 V out Sense Sin-DGND Sin+

(NC) (NC)

MicroFlex e100 accepts incremental encoder (with or without Halls), Halls-only, SSI, EnDat, SmartAbs or SinCos feedback. Pin 12 provides a +5 V, 200 mA supply for feedback devices that require power. \* Version 2.2 EnDat encoders do not use the Sin and Cos channels. (NC) = Not Connected

## X3 - Input / Output



DINO DIN1, 2 Status

DOUT1

Opto-isolated 24 VDC input. Can be configured as a reset, error, stop or phase search input. Opto-isolated 24 VDC inputs. Can be configured as reset, error, stop or phase search inputs.

Drive Enable Opto-isolated 24 VDC input. Must be activated to allow drive to operate.

Fast response allows inputs to be used as Step & Direction demand inputs, or as real-time position capture inputs. Opto-isolated status/error output to indicate error status of drive. May also be used as a general purpose output. Current sourced from pin 11 is output on pin 1. Opto-isolated general purpose digital output. Current sourced from pin 13 is output on pin 3.

Mating connector part; Weidmuller Minimate B2L 3.5/20. Tightening torque: 0.5-0.6 N·m (4.4-5.3 lb-in), Maximum wire size: 0.5 mm